Copyright is owned by the Author of the thesis. Permission is given for a copy to be downloaded by an individual for the purpose of research and private study only. The thesis may not be reproduced elsewhere without the permission of the Author.

# THE QUANTITATIVE ASSESSMENT OF PHOTODENSITY OF THE THIRD CARPAL BONE IN THE HORSE. 

A thesis presented in partial fulfilment of the requirements for the degree of Master of Veterinary Science at Massey University, Palmerston North New Zealand

Cristy Jane Secombe

## CONTENTS

LIST OF ILLUSTRATIONS .....  i
LIST OF TABLES ..... $v$
ACKNOWLEDGEMENTS ..... vi
ABSTRACT ..... vii
INTRODUCTION ..... 1
1.1 Prevalence of carpal bone fractures ..... 1
1.2 Normal structure and function of synovial joints ..... 4
1.3 Functional anatomy of the carpus ..... 7
1.4 Physiology ..... 11
1.5 Changing micromorpholgy of C3 ..... 15
1.6 Diagnosis of third carpal bone disease ..... 16
1.7 Methods of analysing bone mineral density ..... 20
1.7.I Subjective evaluation of radiographs ..... 22
1.7.2 Radiogrammetr! ..... 22
1.7.3 Objective evaluation of radiographs -radioabsorptiometry ..... 23
1.7.+ Single photon absorptiometry ..... 24
1.7.5 Dual photon absorptiometry ..... 26
1.7.6 Computed tomograph ..... 27
1.7.8 Quantitative ultrasound ..... 28
1.7.9 Neutron activation analysis ..... 29
1.7.10) Compton scattering technique ..... 3()
1.8 Summary ..... 30
1.9 Research hypothesis and objectives ..... 30
MATERIALS AND METHODS ..... 32
2.1 Definitions ..... 32
2.2 Animals ..... 34
2.3 Disarticulation of the distal row of carpal bones. ..... 35
2.4 Determination of the extent of variation in x-ray beam angle required before C3
becomes obscured in the tangential views ..... 35
2.5 Film type ..... 35
2.6 Digitising the radiographs ..... 35
2.7 Determining photodensity of the distal row when the $x$-ray beam angle is varied from $90^{\circ}$ ..... 36
2.7.1 Radiographing the distal row ..... 36
2.7.2 Image analysis ..... 38
2.8 Determining photodensity of the distal row of carpal bones when x-ray beam angle is varied from $60^{\circ}$. ..... 4
2.8.1 Radiographing the distal row ..... $+4$
2.8.2 Image analysis. ..... 4
2.9 Changing ROI size ..... 44
2.9.1 ROI program ..... $+4$
2.10 Determination of the inherent differences between View A and B ..... 45
2.1().1 Leg angle ..... 45
2.1().2 Plate angle ..... 46
2.1().3 X-ray beam angle ..... 46
2.10. + Modifying images $A$ and $B$ to form hypothetical image $C$. ..... $+6$
2.1().5 Image analysis. ..... $+7$
2. 11 Statistical analysis ..... 48
2.11.1 Dorsal analysis ..... 48
211.2 Palmar analysis ..... 49
2.11.3 Region of interest size analy sis ..... 49
THE RELIABILITY OF THE QUANTITATIVE
MEASUREMENT OF PHOTODENSITY IN ISOLATED
DISTAL ROWS OF CARPAL BONES ..... 50
3.1 Introduction ..... 50
3.2 Materials and Methods ..... 50
3.2.I Study 1 ..... 5()
3.2.2 Study 2 ..... 51
3.3 Results ..... 52
3.3.1 Study 1 ..... 52
3.3.2 Study 2 ..... 54
3.4 Discussion ..... 56
RESULTS ..... 59
4.1. Dorsal analysis ..... 61
+.1.I Main effect of angle ..... 62
+.1.2 Main effect of ROI ..... 7()
+.1.3 Main effect of group ..... $8($
4.2. Palmar analysis ..... 83
+.2.1 Main effect of angle ..... $8+$
+.2.2 Main effect of ROI ..... 92
+.2.3 Main effect of group ..... 102
4.3. Region of interest size analysis ..... 105
t.3.I Main effect of radius size ..... 106
DISCUSSION ..... 110
5.1 Photodensity in relation to BMD ..... 110
5.2 Effect of angle on photodensity ..... 111
5.3 Effect of ROI on photodensity ..... 113
5.4 Effect of exercise on photodensity ..... 114
5.5 Effect of ROI size on photodensity ..... 115
5.6 View A Compared to View B - Which is the more accurate view? ..... 115
5.7 Relevance of this study ..... 116
5.8 Sources of error. ..... 117
5.9 Critique of the subjective assessment of photodensity of C3 ..... 115
5.10 Further research ..... 118
5.11 Conclusion. ..... 118
REFERENCE LIST ..... 119
APPENDIX 1 ..... 126
Dorsal data ..... 126
Palmar data ..... 131
ROI size data ..... 137
APPENDIX 2 ..... 146

1. Dorsal data ..... 146
1.1 Main effect of angle ..... 147
1.2 Main effect of ROI ..... 155
1.3 Main effect of group ..... 161
2. Palmar data ..... 162
2.1 Main effect of angle ..... 163
2.2 Main effect of ROI ..... 171
2.3 Main effect of group ..... 177
3. ROI size analysis ..... 178
3.1 Main effect of radius size ..... 178

## LIST OF ILLUSTRATIONS

Figure 1.1: Diagrammatic representation of the isolated proximal row of carpal bones ..... 8
Figure 1.2: Diagrammatic representation of the articulation of the proximal row with the radius 8
Figure 1.3: Diagrammatic representation of the isolated distal row of carpal bones ..... 9
Figure 1.t: Diagrammatic representation of the intercarpal ligaments of the carpus ..... 12
Figure 1.5: Line drawing of view A ..... 17
Figure 1.6: Radiograph of the distal row of carpal bones using View A. ..... 17
Figure 1.7: Line drawing of View B ..... 18
Figure 1.8: Radiograph of the same distal row of carpal bones as in Figure 1.6 using View B ..... 18
Figure 1.9: The relative use of methods of non-invasive bone mineral density methods from 196()-199() ..... 21
Figure 1.1(): Lincar absorption coefficient as a function of photon energy. ..... 23
Figure 2.1: Line drawing of Vien A ..... 33
Figure 2.2: Line drawing of View $B$ ..... 34
Figure 2.3: Image of isolated distal row taken at $\varphi()$ degrees ..... 36
Figure 2.4. The distal row of carpal bones, together with circle. cube and wedge on a radiographic cassette. ready for exposure. ..... 37
Figure 25 Line drawing demonstrating that if the distal row of carpal bones is lying horizontal on the cassette the $x$-ray beam angle is equal to both the C3-beam angle and the plate-beam angle. ..... 38
Figure 2.6: Line drawing of determination of $\theta$ ..... 39
Figure 2.7: A calibrated image taken at 9()$^{\circ}$. ..... 41
Figure 2.8: Image of isolated distal row of carpal bones with lines determining the position of the ROI's ..... 43
Figure 2.9: ROI's placed in a dorsal position. ..... 43
Figure 2.1(): ROI's placed in a palmar postion. ..... 43
Figure 2.11: ROI's with a radius of 2.5 mm . ..... 44
Figure 2.12: ROI's with a radius of 3.5 mm ..... $+4$
Figure 2.13: Line drawing illustrating bone-MCIII angle(a). skin-MCIII angle(b) and C.3 beam angle(c) ..... 45
Figure 2.14: Line drawing illustrating hypothetical View C. ..... $+7$
Figure +. 1: Graph illustrating the effect of colour in reading the graph. ..... 6()

> Figure 4.2: Column graph of the main effect of x-ray beam angle on the photodensity of ROI's when in a dorsal position. Error bars represent $+/-1$ standard error (s.c.m.).
Figure +4 : Column graph of the effect of angle on photodensity of ROI 2 in a dorsal position Error bars represent $+/-1$ s.c.m. ..... 64
Figure +5 Column graph of the effect of angle on photodensity of ROI 3 in a dorsal position. Error bars represent $+/-1$ s.e.m. ..... 65
Figure 4.6 : Column graph of the effect of angle on photodensity of $\mathrm{ROI}+$ in a dorsal position. Error bars represent $+/-1$ s.e.m. ..... 66
Figure 4.7: Column graph of the effect of angle on the photodensity of ROI 5 in a dorsal position. Error bars represent $+/-1$ s.c.m. ..... 67
Figure +8: Column graph of the effect of angle on the photodensity of the non-exercised group when ROI's were in a dorsal position. Error bars represent $+/-1$ s.e.m ..... 68
Figure +9 : Column graph of the effect of angle on the photodensity of the exercised group when ROI's were in a dorsal position. Error bars represent $+/-$ I s.e.m ..... 69
Figure +.1(): Column graph demonstrating the main effect of ROI site on photodensity when
ROI's were in a dorsal postion. Error bars represent $+/-1$ s.e.m. ..... 7()
Figure +.11: Column graph of the effect non-exercise on the photodensity of ROI's in a dorsal
position. Error bars represent $+/-$ I s.e.m. ..... 71
Figure +.12: Column graph of the effect of exercise on the photodensity of ROI's in a dorsal position. Error bars represent $+/-$ I s.c.m. ..... 72
Figure +.13: Column graph of the photodensity of ROI's in a dorsal position when x-ray beam angle was 6() degrees. Error bars represent $+/-1$ s.e.m. ..... 73
Figure 4.14: Column graph of photodensity of ROI's in a dorsal position when x-ray beam angle was 65 degrees. Error bars represent $+/-1$ s.e.m. ..... 7+
Figure +.15: Column graph of photodensity of ROI's in a dorsal position when x-ray beam angle "as at 7() degrees. Error bars represent $+/-1$ s.e.m ..... 75
Figure +.16: Column graph of photodensity of ROl's in a dorsal postion when X -ray beam angle was 75 degrees. Error bars represent $+/-1$ s.e.m. ..... 76
Figure +.17: Column graph of photodensity of ROI's in a dorsal position when x-ray beam angle "as 8() degrees. Error bars represent $+/-1$ s.e.m. ..... 77
Figure +. 18: Column graph of photodensity of ROI's in a dorsal position when x-ray beam angle was 85 degrees. Error bars represent $+/-1$ s.e.m. ..... 78
Figure +19 : Column graph of photodensity of ROI's in a dorsal position when x-ray beam angle was 9() degrees. Error bars represent $+/-1$ s.e.m. ..... 79

Figure 4.20: Column graph of the effect of group on photodensity when ROI's were in a dorsal
position. Error bars represent + /-1 s.e.m. ....................................................... 80
Figure +21: Column graph of the effect of group on angle when ROI's were in a dorsal position. Error bars represent $+/-1$ s.e.m.81
Figure 4.22: Column graph of the effect of group on photodensity of ROI's when in a dorsal position. Error bars represent $+/-1$ s.e.m ..... 82
Figure 4.23: Column graph of the main effect of w-ray beam angle on photodensity when ROI's were in the palmar postion. Error bars represent $+/-1$ standard error (s.e.m.). ..... 84
Figure 4.24: Column graph of the effect of x -ray beam angle on photodensity of ROI I when ROI's were in a palmar position. Error bars represent $+/-1$ s.e.m. ..... 85
Figure 4.25: Column graph of the effect of x-ray beam angle on photodensity of ROI 2 when ROI's were in a palmar position. Error bars represent $+/-1$ s.e.m. ..... 86
Figure +.26: Column graph of the effect of x-ray beam angle on the photodensity of ROI 3 when ROI's were in a palmar position. Error bars represent $+/-1$ s.e.m. ..... 87
Figure 4.27: Column graph of the effect of x -ray beam angle on ROI + when ROI's were in a palmar position. Error bars represent $+/-1$ s.e.m. ..... 88
Figure +.28: Column graph of the effect of x-ray beam angle at ROI 5 when ROI's were in a palmar position. Error bars represent $+/-1$ s.e.m. ..... 89
Figure +29: Column graph of the effect of x-ray beam angle on photodensity of the non- exercised group when ROI's 1 ere in a palmar position. Error bars represent $+/-1$ s.e.m. ..... $9(1)$
Figure +.3): Column graph of the effect of x-ray beam angle on photodensity of the exercised group when ROI's were in a palmar position. Error bars represent $+/$ - 1 s.e.m. ..... 91
Figure +.31: Column graph of the main effect of ROI site on photodensity when ROI's were in a palmar position. Error bars represent $+/-1$ s.e.m ..... 92
Figure +.32: Column graph of the effect of the non-exercise group on photodensity of ROI's in a palmar position. Error bars represent $+/-1$ s.e.m. ..... 93
Figure 4.3 : Column graph of the effect of exercise on the photodensity of ROI's in a palmar position. Error bars represent + /- I s.c.m. ..... $9+$
Figure $4.3+$ : Column graph of the photodensity of ROI's in a palmar position when $x$-ray beam angle was 6() degrees. Error bars represent $+/-1$ s.e.m. ..... 95
Figure 4.35 : Column graph of the photodensity of ROI's in a palmar position when $x$-ray beam angle was 65 degrees. Error bars represent $+/-1$ s.e.m. ..... 96
Figure +36: Column graph of the photodensity of ROI's in a palmar position when the angle was 7() degrees. Error bars represent $+1-1$ s.e.m. ..... 97
Figure 4.37: Column graph of the photodensity of ROI's in a palmar position when . x -ray beam angle was 75 degrees. Error bars represent $+/-1$ s.e.m. ..... 98
Figure 4.38: Column graph of the photodensity of ROI's in a palmar position when the angle was 80 degrees. Error bars represent $+/-1$ s.e.m. ..... 99
Figure 4.39: Column graph of photodensity of ROI's in a palmar position when angle was 85 degrees. Error bars represent +/- 1 s.c.m ..... 100
Figure 4.4(): Column graph of photodensity of ROI's in a palmar position when angle was 90 degrees ..... 101
Figure +. 1 : Column graph of the main effect of group on photodensity when ROI's were in a palmar position. ..... 102
Figure 4.42: Column graph of the effect of x-ray beam angle on the photodensity of the evercised and non-evercised group ..... 103
Figure 4.43: Column graph of the effect of group on the photodensity of ROI's in a palmar position ..... $10+$
Figure.++4 : Column graph of the effect of ROI size when ROI's were in a palmar position. ..... 106
Figure 4.45: Column graph of the effect of x-ray beam angle on photodensity of ROI's at vary ing radius sizes ..... 107
Figure +.46: Column graph of the effect of ROI size on photodensity while holding the angle at 60) degrees ..... 108
Figure.++7 : Column graph of the effect of ROI size while holding x-ray beam angle at 9() degrees. ..... 109

## LIST OF TABLES

Table 1.1: Prevalence of carpal fractures in Thoroughbreds and Quarterhorses ..... 2
Table 1.2: Prevalence of carpal fractures in Standardbreds. ..... 2
Table 1.3: Racing performance following surgical treatment of osteochondral (chip) and slab fractures. ..... 3
Table 1.4: Microradiography studies of excised C3's from horses in different stages of training. ..... 14
Table 1.5: Scoring of the trabecular pattern of C3 seen on the skyline projection ..... 20
Table 3.1 : Results of raw data and descriptite statistics for ROI after digitisation of a radiograph 1() times. ..... 52
Table 3.2: Results of one-way ANOVA for ROI after digitisation of a radiograph I() times. ..... 52
Table 3.3: The coefficient of variation (within) for each ROI after digitisation of a radiograph 1() times. ..... 53
Table 3.t: Results of raw data and descriptive statistics for variation of horizontal and vertical angle after digitisation of a radiograph $1(1)$ times ..... 53
Table 3.5: Results of one-way ANOV'A for angle after digitisation of radiograph 10 times. ..... 54
Table 3.6: The cocfficient of variation (within) for both horizontal and vertical angle after digitisation of a radiograph 1() times ..... 54
Table 3.7: Descriptive statistics of vařing bone/angle combinations including coefficient of variation and coefficient of variation (within). ..... 55
Table 3.8: The intra-class coefficient for each ROl at varying bone/angle combinations ..... 55
Table 3.9: Results of descriptive statistics and the coefficient of variation (within) for vertical angle when the bone/angle combination is varied. ..... 56
Table 3.1(): Results of descriptive statistics and the coefficient of variation (within) for horizontal angle when the bone/angle combination is varied. ..... 56
Table +.1: A table of the overall ANOV'A results for the dorsal analy sis ..... 61
Table 4.2: A table of the overall ANOV'A results for the palmar analysis. ..... 83
Table +.3: A table of the overall ANOV'A results for the ROI size analy sis. ..... 105

## ACKNOWLEDGEMENTS

Thank-you to my supervisors. Elwyn Firth, Nigel Perkins, Donald Bailey and Brian Anderson for their time and effort in assisting me through the journey of my masters project. I am particularly thankful for the enthusiasm and time Elwy spent helping me with all aspects of this research. Many thanks to Donald. without whom the transition into the world of image analysis would have been far more turbulent. I especially wish to thank Nigel for his continuous support. invaluable statistical assistance and wisdom. particularly regarding manuscript preparation. Thank-you to Nicki Moffat, Sue Jenkins and Julie Warnock for their help. both practical and theoretical with the radiographic component of the project. My appreciation also goes to Russell Watson and Jim Hargreaves. without whom the cube. wedge and circle would still be a figment of my imagination. I wish to thank Nigel. Chris Rogers and Jason Shaw for their assistance with computer related challenges that I faced along the way. Finally a special thank-you to my husband Mark Secombe. whose unvielding support. commitment and enthusiasm enabled me to lock myself in front of the computer and complete this project.

The work in this project was supported financially by a grant from the New Zealand Equine Research Foundation. of which I am grateful.


#### Abstract

The purpose of this study was to determine if a method of non-invasive bone mineral analysis could be adapted to quantitatively assess photodensity in the third carpal bone of the horse. The technique chosen was radiographic absorptiometry. which determines bone mineral density from a radiograph that includes a control (usually a wedge) of known photodensity. When taken correctly the tangential view of the distal row of carpal bones allows visualisation of the dorsal aspect of the third carpal bone. without superimposition of overlying structures. The method is technically demanding. because the angle at which the x -ray beam penetrates the third carpal bone can not be exactly replicated in a clinical situation. as it is affected by the x-ray beam angle and the limb flexion angle. To utilise radioabsorptiometry in the tangential view. assessment of the effect of variation in x -ray beam angle was required.


Fourtecn isolated distal rows of carpal bones were radiographed vary ing the x -ray beam angle in $5^{\circ}$ increments over $15^{\circ}$ from the base angles of 6()$^{\circ}$ and 9()$^{\circ}$. The radiographs were digitised and processed to determine the photodensity of specific regions of interest in terms of millimetres of aluminium. using the wedge as reference. The results indicated that small variations in x-ray beam angle significantly affect photodensity

Quantitative assessment of the photodensity of the fourth carpal bone showed changes associated with exercise. similar to those in the third carpal bone Changing the size of the region of interest when $x$-ray beam angle was varied by 3()$^{\circ}$ did not affect photodensity of the region of interest. Although conversion from photodensity to bone mineral density was not possible within this project. the findings supported other authors who have studied bone mineral density of the third carpal bone.

There are two tangential views of the distal row of carpal bones. The two methods affect the radiographic image differently because the magnification and distortion changes are different in each. and this precluded accurate comparison. Therefore. it was impossible to determine which method would more accurately assess the photodensity of the third carpal bone.

The study concluded that quantitative assessment of photodensity of the third carpal bone using either tangential view was clinically inapplicable at this time, because of the significant effect of very small changes in angle on photodensity. This is unfortunate. because the current practice of visual subjective assessment of photodensity of the third carpal bone remains unsatisfactory. in particular the differentiation between grades of sclerosis.

## INTRODUCTION

Scientific knowledge regarding the diagnosis. treatments and prognosis of osseous disease has greatly increased over the last 3() years. In contrast. research aimed at providing information to prevent osscous discase has lagged behind. An exception has been the development of a variety of non-invasive bone mineral analysis methods used in the prevention of osteoporosis in humans. One technique. radioabsorptiometry (RA). has been found to be a relatively simple and accurate technique for assessment of bone mineral density. and is used by human phesicians for the detection and monitoring of osteoporosis.

There are ferl studies investıgating the use of non-invasive bone mineral analysis in horses. Such methods would be useful for the detection of phesiological and pathological alterations in the sheleton of horses trained for athletic pursuits. The purpose of this investigation is to evaluate one method of non-masive bone mineral analysis (RA). using the third carpal bone (C3). in order to try and prov ide a technique to aid the early detection of pathological alterations in C3. C? discase and non-invasite bone mineral analy sis is reviewed below.

## 1.I Prevalence of carpal bone fractures

Retrospective studies performed in a number of countries have shown that lameness appears to be the most common cause of interference with a horse's training schedule. resulting in lost days in work. a prolonged spell. or retirement from racing. ${ }^{1-3}$ The carpus is a relatively common site of lameness with fractures of the carpal bones during training or racing accounting for $1-8 \%$ of all injuries in some populations. ${ }^{++\xi}$

Table 1.1: Prevalence of carpal fractures in Thoroughbreds and Quarterhorses.

| Retrospective | Distal radius | Radial carpal | Third carpal | Intermediate |
| :--- | :--- | :--- | :--- | :--- |
| study |  | bone | bone | carpal bone |
| Mizuno $^{6}$ | $35.3 \%$ | $29.5 \%$ | $35.2 \%$ | Not recorded |
| Park $^{7}$ | $14.8 \%$ | $46.4 \%$ | $19.4 \%$ | $15.4 \%$ |
| Mcllwraith $^{8}$ | $19.5 \%$ | $35 \%$ | $4.4 \%$ | $27.7 \%$ |

Table 1.2: Prevalence of carpal fractures in Standardbreds.

| Retrospective | Distal radius | Radial carpal | Third carpal | Intermediate |
| :--- | :--- | :--- | :--- | :--- |
| study |  | bone | bone | carpal bone |
| Lucas $^{\circ}$ | $(0 \%$ | $49.6 \%$ | $49.2 \%$ | $1.2 \%$ |
| Palmer ${ }^{10}$ | $2 \%$ | $35.3 \%$ | $61.6 \%$ | $1 \%$ |

The distribution of fractures within the carpus of Standardbreds (SB's) and Thoroughbreds (TB's) varies (Tables 1.1 and 1.2). In one study of 1852 carpal fractures. $48 \%$ involved fractures of the third carpal bone ( $C$ ) , but the distribution of breeds was not documented ${ }^{[1} C 3$ fractures were classified as osteochondral ("chip") or slab fractures and were not differentiated by size or location. Schneider ch al ${ }^{11}$ developed a classification system of C 3 fractures based on their size and location.

- Type I: incomplete fractures of the radial facet. These are often difficult to diagnose as the fracture line is often present in only one projection.
- Type 2: large proximal chip fractures of the radial facet. Almost all have a similar appearance and are on the medial aspect of the ridge that separates the radial and intermediate facet.
- Type 3: small chip fractures in various sites of the radial facet: there is often another fracture in the same joint or in the other carpus.
- Type t: medial corner fractures. these are large and the fracture line always propagates medially into the second carpal bone (C2-C3) articulation. Often other fractures. associated with C 3 or the radiocarpal bone $(\mathrm{Cr})$ are present
- Type 5: frontal plane slab fractures of the radial facet. These are reasonably uniform in location and appearance. A small number of these fractures are comminuted and $33 \%$ are displaced.
- Type 6: frontal slab fractures involving both the intermediate and radial facet. Configuration is to either fracture in the middle of the radial facet (propagating laterally into the C 3 - fourth carpal bone ( $\mathrm{C}+4$ ) articulation) or to break medially from C 2 and advance laterally to $\mathrm{C}+$.

Slightly less than $50 \%$ of these fractures were comminuted and greater than $65 \%$ were displaced often leading to an unstable carpus.

- Tipe 7: slab and osteochondral fractures of the intermediate facet.
- Type 8: sagittal slab fractures on the medial side of the radial facet. Nearly 5()$\%$ are associated with an osteochondral fracture within the same carpus.

Using the above classification scheme the term slab fracture includes Types 5.6. and 8. The total frequency of slab fractures. when taken as a ratio of C 3 fractures. is $+1 \%$. $\mathrm{Type}+$ fractures are also considered to be partial sagittal slab fractures. ${ }^{\text {. } P a l m e r ~}{ }^{(1)}$ investigated the frequency of slab fractures and found the prevalence to be $22 \%$ of carpal fractures. When classified by breed. $29 \%$ of SB's sustained slab fractures of $C$ and these were distributed equally between both legs: $14 \%$ of TB's sustained slab fractures of the C.3. most commonly in the right foreleg. Variation between breed and limb distribution is supported by other studies. ${ }^{12} 13$

Table 1.3: Racing performance following surgical treatment of osteochondral (chip) and slab fractures.

| Fracture Type At least 1 race | Returning to previous level of <br> function |  |
| :--- | :--- | :--- |
| Ostcochondral $85-9()^{\circ} \%^{1415}$ $68.1 \%^{1+}$ <br> (chip)   |  |  |
| Slab | $60-70 \%^{121316}$ | $43 \%^{12}$ |

The diagnosis. treatment and prognosis of horses that have sustained slab fractures of $C 3$ is well reported in the literature. ${ }^{12}$ The orenwhelming finding is that the prognosis for return to function is dramatically reduced when compared to osteochondral fractures within the carpus (Table 1.3) Slab fractures are likely to be the end result of C? disease. Another clinical entity that has reeently been described may involve the same pathoph siological process. and perhaps precede slab fractures. Lesions included incomplete frontal fractures of C 3 . crush fractures of the subchondral trabecular bone. and full thickiness or partial thichness cartilage damage of the radial facet. However. clinical signs occur at an earlier stage. before radiographic changes can be detected subjectively. ${ }^{17}$ The majority of these fractures were in SB's. and the lesion distribution was equal between both forelimbs. The crush fractures were similar to those reported by Ross ${ }^{18}$. howeter within that case series radiographic lucency was detected in the tangential projection. perhaps due to increased severity of lesions. Surgical treatment is
recommended and the prognosis for return to athletic function is similar to that of osteochondral fractures within the carpus. ${ }^{1718}$

### 1.2 Normal structure and function of svnovial ioints

Synovial joints consist of 2 or more articulating bones. joint capsule. synovium. extra and intraarticular ligaments. ss novial fluid. joint cavity and articular cartilage.

The joint capsule consists of a thick fibrous portion that inserts a variable distance from the articular surface and is lined by thin subsynovium and synovium. The fibrous section is composed of comective tissue that has a low cellularity: the extracellular matrix is made up of fascicles of collagen bundles (type III and I). proteoglycan. noncollagenous proteins and water. ${ }^{10}$ The fascicles are separated by loose comnective tissue and have a random organisation allow ing them to move independently: this reduces joint friction. resists multidirectional forces. protects the synovial membrane from trauma. and allows maximal range of joint motion. ${ }^{2 n}$ The proteogly can- gly cosaminogly can component gives the matrix a gel-like quality that supports the collagen. and alterations of these proteins can change the mechanical capability of the capsule.

Collateral ligaments are intracapsular ligaments that aid in stabilisation of the joint. Biochemical composition and biomechanical nature are similar to the joint capsule and they appear to act in accordance with Wolff's law. ${ }^{19}$ Extra-articular ligaments originate outside the insertion of the fibrous joint capsule. and are subjected to lower loads than those which cause abrupt failure. Injury usually results in a cumulative failure of individual collagen fibers ${ }^{\text {al }}$ Intra-articular ligaments are those within the joint. the most familiar being the intercarpal ligaments and the cruciate ligaments of the stifle joint. Their properties are similar to those of extra- articular ligaments.

Synovium is composed of modified mesenchyme: approximately $1-4$ synoviocytes thich and cells have both secretory and phagocy tic functions. ${ }^{19}$ The synovial membrane serves no biomechanical purpose but like all soft tissues can respond to stress by an increase in collagen production. alterations in trans-synovial diffusion. or changes in synoviocyte metabolism. The lack of basement membrane and gaps between the synoviocstes allow the movement of capillary filtrate through the interstitial fluid into the s!novial space. thus forming s!novial fluid. This is governed by Starling's forces (hỵdrostatic and colloid pressure difference between plasma and synovial fluid) and excessive fluid is drained from the joint by lymphatic vessels. ${ }^{2}$ Normal synovial fluid pressure is subatmospheric which may assist in stabilizing the joint. ${ }^{19}$

Synovial cells produce proteins (hyaluron) that contribute to the unique nature of synovial fluid and have the potential for direct release of lysosomal enzemes (particularly neutral metalloproteinase). prostaglandins. free radicals and crtokines. ${ }^{\text {² }}$ Synovial fluid is the medium through which nutrients reach articular cartilage. The endothelium prevents large molecules from leaving the joint while small molecules depart via diffusion. This is controlled by the presence of large proteins (e.g. hyaluronan) which function as a barrier to small molecule exchange. ${ }^{23}$ There are a number of proposed mechanisms of joint lubrication that function under different loads and stresses. and all are reliant on synovial fluid and its viscous nature. ${ }^{21}$ Viscosity is associated with hyaluron amount and characteristics. and allows the synovial fluid to tolerate transient shear stresses and absorb some of the energy generated by movement. ${ }^{19}$

Articular (hyaline) cartilage derives its translucent appearance from a high water content and collagen structure. Microscopically it is divided into 3 unmineralised zones that are delineated from the calcified zone by the tidemark.

- Zone 1: the most superficial «ith the highest number of cells. which are small. flat and parallel to the surface. Collagen fibrils are tangential to the articular surface.
- Zone 2: the cells are larger and more rounded than those in zone I and the collagen fibrils are arranged in a complex three-dimensional pattern.
- Zone 3: the cells are as large as zone 2. organised with their long axis perpendicular to the surface. The collagen fibrils are larger with a perpendicular orientation. forming a relativels inflexible mesh.

It has been suggested that the variation of zones represents a functional adaptation to differing mechanical requirements: Zone 1 has an abundance of collagen and forms a wear resistant protective layer. whereas the deeper zones contain large amounts of proteogly cans and are organised to withstand compressive loading. ${ }^{19}$

The extracellular matrix of equine articular cartilage is predominantly composed of type II collagen which provides tensile strength. proteogly cans and noncollagenous extracellular matrix molecules. and includes fibronectin and growth factors. Chondrocestes are the cellular component of articular cartilage. Although they make up a small percentage of the cartilage they are responsible for the production and turnover of extracellular matrix. They receive nutrients and excrete wastes via the synovial fluid and are sensitive to changes in the matrix caused by physical stimuli and catabolism. It is not known how the chondroctes co-ordinate matrix turnover. but. dennamic loading and cytokines are thought to play a substantial role. High and continually compressive loads are pathological to the articular cartilage whereas moderate crelic compressive loads are beneficial to the matrix. ${ }^{.1}$ These factors influence the production
and activation of the chondrocitic enzermes that can degrade the extracellular matrix. this degradative process is balanced by enzeme inhibitors and growth factor synthesis. ${ }^{19}$

Articular cartilage and subchondral bone are 2 dissimilar tissucs. Calcified cartilage. with its intermediate properties acts as an interface between these tissues to reduce shear stresses. ${ }^{21}$ Calcified cartilage undergoes remodelling throughout life. as numerous segments contain osteoclastic fibrovascular tissue and new bone. The cause of this may be due to micro-injur as a result of loading a relatively brittle structure when compared to articular cartilage. ${ }^{2+}$ The tidemark (the junction betwcen calcified and non-calcified cartilage) also reduplicates in response to micro-injury and physiological ageing at the expense of articular cartilage. resulting in cartilage thinning. ${ }^{5}{ }^{26}$

Subchondral bone provides structural support to overlying articular cartilage allowing high loads to be sustained without significant deformation. The stiffness of subchondral bone is due to its high mineral content (hydroxyapatite). This inorganic matrix accounts for $6.5 \%$ of total bone matrix. The organic matrix (osteoid) is made up of water. collagen and other proteins and is responsible for the elasticity and pliability of subchondral bone. Heterogeneity of trabecular bone in the area of the subchondral bone plate makes it histologically difficult to distinguish between trabecular bone and cortical bone. ${ }^{10}$

Trabecular bone has a distinct architecture: the basic cellular structure consists of individual trabeculac of varying thickness that are interconnected with spaces between them. Wolff's law controls trabecular orientation. which is parallel to the deeper zones of cartilage and perpendicular to the articular surface. ${ }^{19}$ Trabecular bone is heterogencous and thus its material properties vary with age and anatomic location. The bone is able to regulate strength and stiffness by changing apparent density. this is governed by a squared power law relationship. meaning small changes in apparent density relate to large changes in strength. ${ }^{.7}$ Increases in apparent density are due to increasing thickness of the individual trabeculae and decreasing the size of the intra-trabecular spaces. with the reverse being true for decreasing apparent density Remodeling of trabecular bone occurs on the endosteal surface (the interface between the trabeculae and the marrow) and involves the filling in of a defect created by osteoclasts with bone produced by osteoblasts. ${ }^{28}$ The resistance for fatigue failure appears to be greater for trabecular bone than it is for cortical bone as the mechanism for failure is fracture and buckling of individual trabeculae rather that an accumulation of cracks in the bone matrix as in cortical bone. ${ }^{29}$

Osteonic or cortical bone differs from trabecular bone in its porosity (thus apparent density) and architecture. ${ }^{33}$ Cortical bone is a solid material that contains a series of voids (Haversian canals). and its porosity. usually around $10 \%$. is related to the number of these voids. Cortical bone is a poorly compliant but relatively tough tissue that becomes stiffer and stronger. absorbing more energy as the loading rate increases. Once a threshold is reached these properties reduce. Remodeling of this tissue involves the formation of a bone-remodeling unit consisting of a cutting cone that resorbs bone. When resorption is complete osteoblasts fill the canal $\begin{aligned} & \text { ith } \\ & \text { concentric lamellar bone and the canal becomes progressively smaller until it is only }\end{aligned}$ large enough to contain blood vessels. ${ }^{28}$

Relative density and architecture determine the properties of subchondral bone. and as bone is an adaptive tissue these properties are not constant. ${ }^{31}$ This is reflected by the changes that occur with increasing age. Young ${ }^{31}$ found a significant increase in subchondral bone stiffness and density between yearlings and untrained 2 year olds.

### 1.3 Functional anatomy of the carpus

In most horses the carpus consists of 7 carpal bones arranged in 2 rows between the radius and the metacarpal bones. In a mid-frontal section. the bones of the carpus. except the accessory carpal bone. are approximately rectangular. leading to the term cuboidal bones. The dorsal and palmar surfaces are convex. The palmar surface is very irregular and with the accessory carpal bone forms part of the carpal canal. Figures I.I illustrates the proximal aspects of the proximal row and Figure 1.2 illustrates the articulation of the provimal row with the radius. Cr articulates with the medial sty loid process of the radius and $C 2$ and $C$. The intermediate carpal bone ( Ci ) articulates with the interprocess area of the radius and $C 3$ and $C+$. The ulnar carpal bone ( Cu ) is the smallest of the proximal row and articulates with the lateral styloid process of the radius and with $\mathrm{C}+$. The accessory carpal bone's dorsal border articulates $w$ ith the caudal aspect of the lateral radius and the Cu . Figure 1.3 illustrates the provimal aspect of the distal row. The second carpal bone is the smallest constant bone. the provimal surface of which articulates with the Cr . distall! "ith the second metacarpus (MCII) and palmar aspect of the third metacarpus (MCIII). The provimal surface of $\mathrm{C}+$ articulates with the intermediate and the Cu . the distal surface with the MCIII and the fourth metacarpal (MCIV). ${ }^{32}$


Figure 1.1: Diagrammatic representation of the isolated proximal row of carpal bones. $\mathbf{M}=$ medial, $\mathrm{L}=$ lateral. (modified from (iett $)^{3-}$ )


Figurel.2: Diagrammatic representation of the articulation of the proximal row with the radius. (modified from E.C.Firth and W.Hartman ${ }^{33}$ )


Figure 1.3: Diagrammatic representation of the isolated distal row of carpal bones. $\mathbf{M}=$ medial, $\mathrm{L}=$ lateral. (modifical from (ictt. ${ }^{32}$ )

The third carpal bone is the largest bone of the distal row, contributing to $2 / 3$ rds of the medial to lateral dimension. and is twice as wide dorsally as palmarly. The 2 facets of the proximal surface are separated by a dorsopalmar ridge. The medial facet (concave) is known as the radial facet and articulates $\because$ ith the distal surface of the Cr . The lateral facet (concave dorsally and convex palmarly) is known as the intermediate facet and articulates with the distal surface of Ci . The distal surface of $C$ ? articulates almost entirely with MCIII. and the lateral and medial aspects of the bone articulate with MCIV and MCII respectively. ${ }^{32}$

The radial carpal bone. Ci and CS receive the majority of the load accepted by the carpus and are most often injured at fast gaits. ${ }^{3+}$ The other 3 cuboidal bones are smaller. thereby carrying less load and are not as prone to injury. The proximal joints of the carpus are high motion joints of different types. The radiocarpal joint is a rotating joint with the normal range of flevion being limited by the palmar joint capsule and flexor muscles. ${ }^{35}$ The intercarpal joint is a hinged joint and capable of only 1()$^{\circ}-2()^{\circ}$ hyperextension due to the palmar location of the collateral ligaments and the shape of the joint surface. ${ }^{36}$ The carpometacarpal joint has very little motion and no capacity for flexion or extension. ${ }^{36}$.37 The joint capsule is thought to be common to all 3 joints. attaching proximally to the radius and distally to the proximal metacarpus. The synovial membrane forms three pouches corresponding to the 3 joints: the radiocarpal and the intercarpal pouches are voluminous. whereas the carpometacarpal pouch is limited. The distal 2 pouches communicate. ${ }^{3 /}$

A study by Firth ch al ${ }^{\text {kn }}$ described the relationship of movement between the joints of the carpus and associated cuboidal bones during passive movement. The radiocarpal joint contributes most of its flexion at the begiming of passive flexion. The differing rotational ases of the radius result in the Cr and Cis sliding past each other in a provimal-distal direction during movement. so that at full flexion the distal border of Cr is seteral millimeters distal to that of the distal border of Ci . The Cu . Ci and accessory carpal bone move as a single unit and tilt a total of $25^{\circ}$ in full flexion. while the Cr achieves a tilt of $5^{\circ}$. The intercarpal joint plays a role in the later stages of carpal flexion. As the degree of flexion increases the distal row of carpal bones pivots about an axis contributing to the later stages of carpal flexion.

The carpus has a number of extra-articular and intra-articular ligaments. The lateral collateral carpal ligament attaches provimally to the lateral styloid process of the radius and distally to the proximal MCIV. with some fibers ending on MCIII. The medial collateral carpal ligament is stronger and wider distally than the lateral with the proximal attachment on the medial styloid process of the distal radius and the distal attachment on the second and third metacarpus.

Numerous ligaments are present dorsally that are essential in the normal functioning of the carpus. Intra-articular ligaments of the carpus occur in the intercarpal and carpometacarpal joints. intercarpal intra-articular ligaments are more prone to injury. There are 3 ligaments. the dorsomedial intercarpal ligament. the medial palmar and the lateral palmar intercarpal ligaments. The dorsomedial intercarpal ligament arises from the lateral border of the Cr and attaches distally to the dorsomedial aspect of C2 and in some cases C3. The lateral palmar intercarpal ligament has a proximal attachment on the distal palmar medial surface of the Cu and palmar lateral surface of the Ci and travels distomedially to predominantly insert on the proximal palmar lateral surface of $C 3$. The medial palmar intercarpal ligament exhibits variation in anatomy between horses. The proximal attachment is usually to the distolateral surface of the Cr and inserts distally on the provimal palmar medial surface of C 3 and the proximal palmar lateral surface of C2. This ligament is usually divided into + bundles ${ }^{39}$

### 1.4 Physiology

When undergoing maximal exercise the carpus acts as a stress absorber. When avially loaded most of the carpal articulations allow an interlocking wedge arrangement to be formed. Some of the load is transferred to the intercarpal ligaments. as illustrated in Figure $1.4{ }^{37}$ It is thought that by this mechanism sudden stress is converted into a longer elastic loading stress and thus the strain rate is decreased. "It appears that the carpus requires this mechanism for energ! absorption as its elastic ability to overestend is limited (due to the palmar soft tissues) when supraphesiologic loads are applied. Thus it is postulated that the stresses imposed on the carpus during maximal exercise would lead to degenerative changes if there were a reduction in the number of bones in the carpus. ${ }^{\text {(1) }}$ This may occur on the medial aspect of the intercarpal joint. as loads from the radius may pass on to the Cr and directly on to the radial facet of the C 3 without being dissipated to the intercarpal ligaments. This predisposes the ? major weight bearing bones to injury. in particular the radial facet of $C 3.37$


Figure 1.4: Diagrammatic representation of the intercarpal ligaments of the carpus. (modified from E. C.Firth, N. I)eane, K. (iibson et al ${ }^{3 / 6}$ )

When the major weight bearing carpal bones are loaded. the majority of the load is accepted by the fluid component of articular cartilage causing instant deformation. As the load is shifted to the solid component there is slower creep deformation. this continues until equilibrium is reached between the cartilage and the external force applied. This property is true of all viscoclastic materials. ${ }^{21}$ It appears that moderate loading enhances cartilage metabolism. however. high continuous loads and complete immobilisation appears to damage cartilage. ${ }^{21}$ As mentioned previously there is an abundance of collagen in the superficial zones. which resist tensile forces. consequently small pathologic alterations within this area may weaken the articular surface and its biomechanical resistance to shear. tensile and compressive forces. ${ }^{+1}$ Compliant subchondral bone acts as a shock absorber between articular cartilage and epiphyseal bone. thereby helping to minimise pathology at the articular surface. The shock absorptive capacity appears to reduce as apparent density increases and thus compliance decreases.

Bone is a constantly adaptive tissue and it is widely accepted that relative density increases with exercise. ${ }^{31+2+i}$ It is thought that during exercise the trabecular bone deforms when placed under a mechanical load. Repetitive loading stimulates the osteoblasts lining the spongiosa to upregulate. leading to thickening of the trabeculae at the expense of the intra-trabecular spaces. this is termed modelling. ${ }^{2 \prime \prime}$ In order to explain the distribution of changes that occur within C 3 as a result of exercise. it important to stud loading patterns at rest and at vary ing gaits. At rest the palmar aspect of both the radial and intermediate facets bear the most weight. Application of high loads in this position result in intermittent weight bearing on the dorsal aspect of both facets. When moving at low gaits such as walking and trotting the load is distributed evenls over the radial and intermediate facets excluding the most dorsal aspect. Under load conditions that mimic those of galloping. the load is transferred to include the dorsal rim of the intermediate and radial facets with a shift towards the dorsomedial aspect of the radial facet. ${ }^{3+13}$

Table 1.4: Microradiogı aphy studies of excised C3's from horses in different stages of training.

| Horses | Microradiography |
| :---: | :---: |
| Untrained | The trabeculae were aligned in a proximodistal direction in an open pattern and the subchondral bone formed a constant width across each section. |
| Trained but unraced | Inclination to trabecular thickening and decreased intra-trabecular spaces. |
| Actively racing | A unique pattern of appositional growth. this occurred at the expense of marrow spaces. thus forming a bony bridge between the proximal and distal surfaces of $C 3$. Sclerosis of subchondral bone was greatest at the dorsomedial aspect of the radial facet of the $C 3$ in a band 3 mm palmar to the dorsal margin. |

Microradiographic examination of C 3 's from horses that have undergone different levels of exercise show evidence of modelling. This is particularly evident in actively racing horses. In a band 3 mm from the dorsal margin an increase in photodensity and change in architecture demonstrate this modelling (Table 1.4). t ${ }^{\text {³l }}$ Increasing radiographic photodensity correlates with increasing bone mineral density (BMD). Firth el cil ${ }^{+1}$ took sagittal sections in a dorsopalmar direction of the intermediate and radial facets of C 3 . Radiographs were taken of the sagittal sections and compared with BMD measurements performed by dual x-ray
 compared them with bone volume measurements using morphometry. Both studies found that bone volume density in the dorsal proximal. dorsal central and dorsal distal regions of C 3 was significantly greater in trained compared to untrained horses. Both studies demonstrated that the dorsal central regions of interest had the greatest increase in density: Similar findings have been observed in TB's trained on a treadmill. Bone mineral density increases in the distal dorsal region of C3. then the proximal dorsal region and finally the central dorsal region. (Unpublished data Firth 99)

### 1.5 Changing micromorpholgy of C3

The adaptive response to evercise is a phisiological process. However. continued modelling in response to high loads leads to pathological changes demonstrated by microradiography (Table 4) ${ }^{+2}$ Continued modelling causes sharp gradients in stiffness $5-10 \mathrm{~mm}$ from the dorsal edge of C. 3 which may result in incomplete dissipation of forces within articular cartilage during loading. predisposing it to injury: ${ }^{31}$ Repetitive micro-trauma to the articular cartilage leads to chondrocite injury. which in turn responds by producing enzemes that destroy the extracellular matrix. The gross changes that may be seen include yellow ish discoloration. dullness, fibrillation and ebumation. Microscopic changes include loss of proteoglycan. disruption of the various zones of articular cartilage. changed chondrocyte morphology. exposure of the calcified cartilage and polishing of the exposed subchondral bone. ${ }^{26}$ Uhlhorn el al ${ }^{\text {ti }}$ found that bones with cartilage lesions of the radial facet of $C$ ? had a significantly higher bone volume density than those that did not. Pool ${ }^{21}$ found that although there does not appear to be a good correlation between the degree of deterioration of the articular cartilage and subchondral bone sclerosis both appear in varying degrees in affected bones.

Remodelling occurs concurrently with modelling. True remodelling occurs when there is no net increase in bone mineral density: repair and damage occur at the same rate. When damage (presumably from the sharp change in stiffness gradient within the subchondral bone. as a result of modelling) exceeds repair it is presumed that the high rate of microf ractures disrupts the canalicular system and possibly the capillary bed. The result is a wedge shaped area of ischemic. sclerotic subchondral bone within C?. This secondary lesion usually measures 8 $1(0 \mathrm{~mm}$ in length. $3-5 \mathrm{~mm}$ in width and $1-2 \mathrm{~mm}$ in depth. It is located $2-4 \mathrm{~mm}$ from the dorsal provimal margin of the radial facet and is composed of acellular fragments of sclerotic bone with the deep surface being separated from viable compacted bone by a line of resorption. A vascular response arises from viable bone to fill the trough with osteogenic granulation tissue that invades and repairs the necrotic subchondral bone. ${ }^{\text {2 }}$

It is suggested these lesions are associated with development of conner or complete slab fractures. Small areas appear to undergo repair without destabilisation of overlying cartilage. Unsupported articular cartilage either collapses into the eavity or becomes detached. Studies of slab fractures by Pool ${ }^{20}$ suggest these fractures occur in pathological bone. All lesions begin at the dorsoproximal surface of $C$ in an area of chronic injury and repair. The fracture line extends distally where it either turns obliquely to create a partial slab fracture or contimues to
create a compete slab fracture. Usually the proximal $1 / 4$ of the fracture line appears irregular and contains fibrous tissue. the distal $3 / 4$ appears as an acute fracture. ${ }^{20}$

In vivo and in vitro studies demonstrate that traumatic loading induces damage to the subchondral bone and calcified cartilage before inducing damage to articular cartilage. ${ }^{+6+7}$ Therefore it has been proposed that carly detection of sclerosis may be helpful in preventing degenerative joint disease and fractures. ${ }^{\text {+ }}$

### 1.6 Diagnosis of third carpal bone disease

Radiography is the main diagnostic tool used in the assessment of carpal injuries. As with all radiographic evaluations a number of views are taken to ensure adequate assessment. since superimposition is a problem in the radiographic evaluation of joints. Lesions may be missed due to x-ray beam obliquity in relation to the lesion or by masking of overly ing structures. Carpal views taken are the lateromedial. flesed lateromedial. dorsolateral-palmaromedial at 3()$^{\prime \prime}$ and 6()$^{\prime \prime}$. dorsomedial-palmarolateral at $45^{\prime \prime}$ and the flexed dorsoproximal-dorsodistal oblique. the latter is commonly known as the tangential view of the distal carpal row. Most lesions can be detected in some but not all radiographic views. and a proportion of lesions are detected only on the tangential view. ${ }^{11+5}$

There are 2 tangential views used to assess the distal carpal row. View A (Figure 15 ) involves flexing the $\operatorname{leg}$ at 6()$^{\prime \prime}$ with MCIII parallel to the floor. the N -ray beam is angled 3()$^{\circ}$ from horizontal. the plate placed distal to the carpus and angled towards the beam as close to 9()$^{\prime \prime}$ as possible This view results in little distortion of $C 3$. however. some magnification does occur View B (Figure 1.7) involves flexing the carpus and placing the plate on the dorsal aspect of MCIII. with the centre of the plate at the level of C'3 and the x -ray beam angled at 3()$^{\prime \prime}$ from horizontal. This view causes little magnification but a significant amount of distortion. as the beam angle is not perpendicular to the plate. The X -ray beam angle. leg angle and $C$ ? beam angle are similar between both views. however. the plate angle significantly differs.


Figure 1.5: Line drawing of view A


Figure 1.6: Radiograph of the distal row of carpal bones using View A. A fracture is present within the radial facet of C 3 .


Figure 1.7: Line drawing of View $B$


Figure 1.8: Radiograph of the same distal row of carpal bones as in Figure 1.6 using View B. A fracture is present within the radial facet of C3.

Subtle lesions are likely to be detected with advanced radiographic equipment and film/cassette combinations. predominantly due to improvement in intensifying screens and radiographic film Intensify ing screens contain a range of materials which convert a few photons of high energ! (x-ravs) into many photons of low energy (blue light). In the production of these screens 2 qualities are important. namely speed (the smallest possible exposure to produce an image) and optimum definition of the image. Those factors that contribute to one quality are detrimental to the other. and a compromise must be reached. In most circumstances the advantage of reducing the exposure time is of more importance than optimum detail. In equine radiography speed of exposure may contribute to greater detail as movement blur is reduced. ${ }^{\text {to }}$

X -ray film is an emulsion. which is a coating containing finely dispersed grains of silver halide When exposed to low energy photons, the halide is converted to metallic silver. which on developing and fixing results in the blackening of the exposed area. Most films are double emulsion. with emulsion on both sides of the film. Various emulsions enable fine or standard detail. Single emulsion films are coated on one side only. and are designed for use with cassettes with single intensify ing screens and produce very fine detail. at the expense of increased exposure time. ${ }^{+9}$

The majority of carpal radiographs taken in the field use medium or standard double emulsion film and cassettes with double standard intensify ing screens. This allows minimum exposure time and adequate detail for the subjective analy sis of the tangential view of C3. Exposure times vary with film focal distance and equipment used. and each machine should have an exposure chart developed for each film type. Recent improvement in screen and film detail has lead to the use of single emulsion film and screens. and may improve trabecular detail of C3 without much increase in exposure time.

The occurrence of C 3 sclerosis without the presence of other radiographic changes has led to the development of a grading scale (Table 1.5 ) ${ }^{\text {5" }}$ The radiographic views used to assess this are Views A and B. The radiographic quality must be such that the trabecular pattern can be recognised. not only in C 3 but also in $\mathrm{C}+$ as the latter is used as a "control". Grade I and 2 are believed to represent physiological adaptation. ${ }^{\text {5" }}$

Table 1.5: Scoring of the trabecular pattern of C3 seen on the skyline projection. ${ }^{\text {0 }}$
Grade I - trabeculation clearly evident, no areas of focal thickening.
Grade II - trabeculac clearly evident, with evidence of thickening in focal areas.
Grade III - trabeculation lost in focal areas
Grade IV - almost complete loss of trabeculation in the radial and/or the intermediate facet of C3

C + sclerosis is rarely seen and if present is more likely to be due to a radiographic artefact. ${ }^{\text {su }}$ Investigation of subchondral bone changes of $C+$ do not appear in the literature. There are a small number of reports on slab fractures of $C+$ these are usually sagittal fractures and are often accompanied by a slab fracture of the intermediate bone. It is speculated that the cause of these fractures is abnormal force acting on normal bones. although this has not been proven. ${ }^{51}$

The validity of subjectively grading selerosis of the third carpal bone has recently been examined. ${ }^{+5}$ In this study View B was used and only radiographs that showed C + and C 2 were included. The radiographs were graded using a grading system similar to that of O'Brien. "Once the horses were euthanased the distal row of carpal bones was disarticualted and radiographed in a proximodistal direction. C3 was then assessed for bone volume density using bone morphometry. The authors found that subjective assessment of the tangential radiographic view allowed differentiation between sclerotic and non-sclerotic C.3s. however the grade of selerosis could not be determined. Although this is a significant finding some degree of sclerosis is believed to be a physiological response to exercise. ${ }^{+4}$ thus it appears that subjective analy sis of radiographs may not differentiate between physiological and pathological sclerosis.

Subjective analysis of changes in BMD is not without problems. It has been generally believed that that changes in bone mineral density of less than $30 \%$ can not be detected subjectively Although this was based on experiments performed $f^{()}$years ago. ${ }^{53}$ a more recent study by Finsen ${ }^{\text {t }}$ agrees $w$ ith this hypothesis when dealing with the peripheral skeleton. Other studies have shown that although this was true for cortical bone sites. a change of only $8-14 \%$ is required for bones with a high trabecular content. ${ }^{5}$ It must be stated that all of the work in regard to subjectively assessing BMD has been conducted in humans. in situations where BMD is decreasing rather than increasing as is the usual case in the young working horse.

### 1.7 Methods of analysing bone mineral density

The prevalence of osteoporosis in humans has resulted in the development of many methods of non-invasive bone mineral analysis in order to detect early disease and monitor its progression and response to therapy. Despite the number of methods. agreement has not been reached over
the most effective for the diagnosis and serial assessment of osteoporosis. either for the single patient or when large populations are examined.

The pattern and rate of bone loss varies between the appendicular and axial skeleton. cortical and trabecular bone. and various disease states and therapeutic interventions. Thus variation in measurements using different techniques is not only a function of accuracy, precision and sensitivity. but also physiologic variation. Therefore. many methods of non-invasive bone mineral analysis are complementary rather than exclusive ${ }^{56}$. and the following will be discussed.

- Subjective evaluation of radiographs and radiogrammetry
- Objective evaluation of radiographs - radioabsorptiometry
- Photon absorptiometry - single and dual
- Computed tomography
- Ultrasonograph
- Neutron activation analysis
- Compton seattering technique


Figure 1.9: The relative use of methods of non-invasive bone mineral density methods from 1960-1990. Abbreviations: $R G=$ radiogrammetry; $P D=$ photodensitometry $(R A)$; NAA/CS = neutron activation analysis and Compton scattering; SPA = single-photon absortiometry; DPA = dual-photon absortiometry; QCT = quantitative computed tomography; $\mathrm{pQCT}=$ peripheral quantitative computed tomography; $\mathrm{DXA}=$ dual x-ray absortiometry; SXA = single x-ray absorptiometry; US = ultrasound. (reprinted from Sartoriust'. P $23+$ by courtesy of Marcel Iekiker.Inc)

Most of the above methods measure oniy bone mineral content (BMC) or BMD. The measurement should be interpreted in light of clinical symptoms. because although BMC and BMD are closely linked with bone strength. it is not the only factor associated with a high fracture risk. Others include bone geometry. architecture. point defects. neuromuscular coordination and frequency of falls. Thus these methods only partially detect an increased risk for fracture. ${ }^{57}$

### 1.7.1 Subjective evaluation of radiographs

Subjective evaluation of radiographs is the simplest non-invasive method of BMD assessment Parameters used to indirectly assess change in bone mass include reduced or increased photodensity. or changes in bone morphology. Based on experiments conducted in the 194()'s. it was believed that changes in BMD of less than 3()$\%$ could not be detected subjectively ${ }^{58} \mathrm{~A}$ more recent stud ${ }^{5}{ }^{+t}$ agrees with this hypothesis when assessing the peripheral skeleton. Other studies have shown that although this is true for cortical bone sites. change of just $8-1+\%$ is required for detection of subjective BMD differences in trabecular bones. ${ }^{55}$ Although subjective assessment is a relatively insensitive method for BMD analysis it is an imperative part of the standard routine of reading radiographs. and is currently the most commonly employed method of estimation of BMD in the horse

### 1.7.2 Radiogrammetry

Radiogrammetry a more objective method. is inexpensive and simple to perform. It involves morphometric measurements of cortical bone from radiographs. primarily using the ratio of cortical thickness to the overall thickness of tubular bones. This requires direct caliper measurements of the inner and outer diameters of the cortices from which bone mass indices are then calculated. It is best performed with cortical bone from the appendicular skeleton. most commonly the metacarpal thickness due to their accessibility by x-ray imaging and the low radiation exposure to the patient. ${ }^{\text {s. }}$

Originally it was thought that radiogrammetry allowed accurate measurement of cortical bone volume and thickness. and as bone remodeling was low in the appendicular skeleton. this reflected changes in total bone mass. ${ }^{50}$ Further studies have revealed that the test results of this procedure are relatively inaccurate because of the irregularities in the shape of the metacarpal cortical regions and intracortical resorption. ${ }^{6 \prime \prime}$ This technique was extensively used in the 196()'s and 197()'s to assess BMD. but is now thought to be inadequate for the diagnosis of osteoporosis and its progression. However. it appears sufficient for epidemiological studies of large populations. ${ }^{58}$

### 1.7.3 Objective evaluation of radiographs -radioabsorptiometry

Radioabsorptiometry (RA) measures BMD objectively by measuring radiographic photodensity achieved by comparing a material of known photodensity with bone. The technique has been available for over 5() years, but prior to the development and application of computers and image analysis it was inaccurate, imprecise and time consuming. ${ }^{61}{ }^{62}$

The technique involves taking a conventional radiographic image. of either the right or left hand. The hand is placed on a template and a reference standard is placed in a predetermined place. Two radiographs are taken at different exposures using single X -ray film. The radiograph is captured. converted into a digital image and an image analysis program is used manage the data. Data are collected on phalanges 2.3 and + and the computer calculates the average values for BMD and bone area. The data is collected in arbitrary units rather than $\mathrm{g} / \mathrm{cm}^{2}$ or $\mathrm{g} / \mathrm{cm}^{3}$. however these units do have dimensions of mass and volume. ${ }^{610: 3}$

The material of known photodensity to which bone is compared to is often in the form of a wedge. however there are other reference standards The reference standard is included in the radiographic image to correct between film differences. due to film quality. exposure and processing, Nearly all wedges are in ramp form and the ideal reference wedge has the same absorption coefficient as the material being measured as shown by Figure 1.10. The most common metallic wedge to be used is aluminium or an aluminium alloy. The wedge dimensions are comparable to the thichness of the phalangeal bone. ${ }^{03}$


Figure 1.10: Linear absorption coefficient as a function of photon energy. (modified from Colbert ${ }^{6,3}$ )

Two radiographs are taken in order to verify the results. Between film disparities are usually less than $2 \%$. If the discrepancy is more than $3 \%$ from the mean then the radiographs are checked for defects. which can be produced by processing or exposure faults. If there is a discrepance the procedure is repeated. ${ }^{63}$ Accuracy error is very low as RA is highly correlated with ash weight of measured bones. This may be because the trabecular and cortical bone of the phalan. is roughly equivalent to the central skeleton. ${ }^{6+1}$ Precision error is also very lon as reproducibility of this technique is $99 \%$ or greater ${ }^{6}$

The consistency with which RA studies measure bone mass is high. even when skeletal sites measured and populations studied vary. RA is thought to be as good as. or in some cases better than. other bone mass measurement techniques and its predictice association of fracture risk is high ${ }^{\text {ol }}$ The main application for this technique is to detect and monitor osteoporosis. It also has been used to assess osseous changes associated with Iead poisoning and renal discase. and in the treatment of osteogenesis imperfecta ${ }^{63}$

The technique has several advantages. it is readily available to the non-specialist phesician and no large capital expenditure is required. The radiographs are taken and then submitted to an image analysis laboratory for interpretation. so the technique is of significant use in remote areas where access to other bone mass anale sis methods is limited. The use of this technique to assess the efficiency of therapy in individual patients has not been studied in a controlled clinical trail. ${ }^{(5)}$ Recent improvements of RA reduce the disadvantages associated with this technique. A valid concern. as with other techniques utilising the appendicular skeleton. is that the BMD values of the phalanges may not predict BMD of the axial skeleton. ${ }^{+9}$
R.A has been used in the dog and the horse. ${ }^{65}$ (6) Both of these studies were performed on isolated bones that had all soft tissue removed. as its presence results in a high accuracy error The calcaneus was used in the horse because there is a high amount of trabecular bone which is more sensitive to changes in bone mass. howerer it appeared that the optical density was influenced by the mass of the bone rather than the actual mineral density. The study concluded that RA using the calcaneus was not a reliable indicator of BMC

### 1.7.4 Single photon absorptiometry

Single photon absorptiometry (SPA) assesses BMC by a single source of low energy photons (from a highly collimated source) that penetrates the bone of interest, and was one of the most
widely accepted and clinically applied devices in the 1970's and 1980's. The degree of attenuation of the beam by the bone is measured by a scintillation detector system, and there is a direct relationship between the number of photons absorbed and BMC. ${ }^{67}$

The main components required for an absorptiometry unit are a single encrgy source photon unit. most commonly iodine and americuium isotopes. and a detector. As SPA uses only one energy source. the bone site must be encased in a constant thickness of soft tissue or equivalent (e.g. water). as soft tissue critically contributes to the attenuation profile. The photons travel from the source (usually under the patient). pass through the patient and continue upward to enter a detector where the intensity of the beam is determined. The source and the detector are aligned and connected so they move in unison. ${ }^{68}$ The forearm is placed in a water bath and a base line measurement obtained in the region of the interosseous membrane. The average attenuation of the beam by the bone is calculated and compared with data in a standard curve derived from a reference. from this information BMC can be calculated. ${ }^{56+9}$

Precision error associated with SPA is as low as $0.3 \%$. however there can be considerable interunit variability and miscalibration. Other sources of variation are interosseous and subcutancous fat. ${ }^{\text {i }}$ SPA measurements do not reflect axial bone density accurately and there appears to be an accurace error of up to $12-15 \%$ in estimating spine or femoral density ${ }^{\text {.9 }}$ This method does not take into account bone volume and thus only BMC can be measured. In order to assess BMD. cross sectional area (CSA) is required. this can be achieved by using combined ultrasound velocity to detect cortical CSA and thus bone mineral content divided by CSA is equal to bone mineral density. ${ }^{71}$

SPA at peripheral sites has been less successful for the diagnosis and monitoring of osteoporosis than believed possible when the method was first developed. and the development of DPA and DXA have led to dwindling usage of this modality : ${ }^{69}$

SPA has been used in horses in combination with ultrasonic transmission velocity to determine the BMD of MCIII and changes that occur to BMD in response to immobilization. ${ }^{7172}$ Although this is a relatively precise method. the disadvantages include expense. lack of portability of equipment. and the requirement of bandages to provide a constant soft tissue covering. The patient is required to stand completely still for at least 9() seconds. ${ }^{73}$ A disadvantage of this process in the horse is that it provides the mineral content per unit length of bone and takes no account of differences in bone size. thus it is only useful in comparing changes in the individuals with negligible CSA alterations. ${ }^{\text {² }}$

SPA has been modified to $x$-ray absorptiometry. This uses a radiographic source as opposed to a radionuclide. The advantages of this are that the radioactive source does not need to be replaced and the waste eliminated. Additionally. extensive control measures required to compensate for isotope decay are not required. The limitations associated with SPA are also apparent when using single energy x-ray absorptiometry. ${ }^{68}$ SPA has provided the experience necessary to adapt the DPA and DXA to non-invasive bone mineral analysis.

### 1.7.5 Dual photon absorptiometry

Dual photon absorptiometry (DPA) involves using 2 photon sources that emit at 2 discrete energies and can more accurately assess BMC when there is variable soft tissue covering. ${ }^{57}$ The principle of DPA is that 2 different sources of radiation are attenuated by tissues in differing amounts. Entering the results of the attenuation through soft tissue and bone into a mathematical equation allows an attenuation profile of bone to be determined and eliminates the need for a constant soft tissuc covering. ${ }^{\text {S6 }}$ This technique is useful in the axial skeleton. as it is not surrounded by a constant soft tissue covering. ${ }^{\text {6. }}$ The most commonly used isotope is gadolinium. as it is a dual energy source

DPA is superior for measurement of cortical BMC than for trabecular BMC ${ }^{57}$ Sources of precision and accuracy error are greater in DPA than SPA. and thus exactness is compromised. as demonstrated in both human and equine studies. ${ }^{74}$

Although DPA has bought about improvement in measurement of axial BMC disadvantages include an increased scanning time to 2()$-4()$ minutes. patient movement causing inaccuracy and decreased resolution. The patient is exposed to a greater amount of radiation. Source energy strength decreases as it passes through the patient. requiring complicated corrections to be made. making the procedure less accurate. The isotope is costly. difficult to obtain and restricted in its use. ${ }^{+9}$ Additional limitations are most evident in elderly and severely osteoporotic patients. Extraosseous calcification in arteries and degenerative deformities or fractures of the vertebrae can reduce the reproducibility and the accuracy of DPA. ${ }^{+9}$

Dual x-ray absorptiometry (DXA). based on SXA was introduced commercially in the late $19810^{\circ}$ s. The source is an $x$-ray tube and 2 distinct energy levels are generated. The system is more versatile than SPA and superior to DPA. as it can carry out the functions of DPA at a lower operating cost. scanning time and total radiation dose. ${ }^{\text {+4.68 }}$ Lack of radionuclide decay and a large difference between the energy levels emitted result in improved image resolution meaning that the accuracy and precision error are improved. ${ }^{75+9}$ These additional advantages
have made DXA the most widely used method to assess BMD in clinical and population medicine as well as the primary research tool for BMD assessment. Sources of error apparent to DXA are similar to those of DPA. and are related to calcification seen in the elderly patient. ${ }^{+9}$

DPA or DXA have only been used in excised bones in the horse. as the time taken to scan is prohibitively long. ${ }^{+476}$

### 1.7.6 Computed tomography

Computed tomography (CT) involves obtaining cross sectional images using narrow beam . X rays and computer processing of the images. integration and analy sis. There is advanced soft tissue differentiation and no superimposition of overlying structures. as the third dimension is known which gives CT major benefits over conventional radiography and allows the quantification of tissue densities. ${ }^{77}$

There are a number of components that are involved in the development of an image: these are collection of data from the patient. computer processing of data. image display. and storage of data. The information is collected from the patient in the form of x -ray photons: the patient lies on a table and moves into a gantry. The gantry contains a x-ray tube. collimators and detectors. The x -ray tube emits a beam of photons. and may be stationary or rotating depending on the type of CT scanner. The operator determines the thickness of the slice by altering the collimators. The x-ray detectors convert the photons into an electronic signal of which the relative intensity reflects a number of photons emitted from the patient. Using a number of complex mathematical equations the computer converts the electrical signal into a gray scale. this can be achieved because the number of photons leaving the x -ray tube is known. and the number emerging from the patient is detected. ${ }^{77}$

The image is made up of many rows and columns of pixels. and each pixel represents a small piece of tissue. Each pixel is assigned a number that reflects the intensity of photons that emerged from the patient. known as Hounsfield units. Looking at a matrix of numbers is difficult to interpret. thus the numbers are assigned to a gray scale and an mage formed. ${ }^{77}$ Image storage is achieved using magnetic tape. or hard copies can be formed $«$ ith radiographic film.

There are numerous applications of CT in the living animal, including a meriad of uses in the musculoskeletal system. Some of the more important applications in the musculoskeletal system are the assessment of trauma. infection. neoplasia. articular discase. vascular disease and
metabolic bone disease. It has recently become a popular method of assessing BMD due to some advantages over other methods of assessment. Firstly. it can directly measure trabecular bone, which has a high turnover rate when compared to cortical bone and reflects rapid. subtle changes in BMD. Secondly. osscous architecture as well as BMD can be studied giving a better indication of bone strength. Finally. CT can exclude heterotrophic calcification such as vascular calcification or heterotrophic ossification e.g. degenerative joint disease. ${ }^{\text {+9 }}$

The disadvantages of this method are: exposure of the patient to the highest radiation dose. considerably longer scan time and although this technique is precise and accurate. reproducibility is a problem due to inaccuracies in positioning patients. leading to high accurac! errors. ${ }^{197.8}$

Given its apparent advantages over other methods of non-invasive BMD analysis. CT has been used in the assessment and prevention of osteoporosis. Site selection is not uniformly agreed on. however. the 2 most common areas are the spine and the appendicular skeleton. ${ }^{78}$ Although information derived from one site does not necessarily relate to other sites. peripheral CT analy sis appears to be becoming more popular as it offers short examination times. small precision error and a small radiation dose. "It appears that like other forms of analy sis of BMD. analy sis by CT can distinguish patients with osteoporosis but can not predict those patients who are likely to develop fractures. as BMD is only one quality associated with fracture risk. ${ }^{7 *}$

CT has been used in both small and large animals for a variety of disorders. however there is little work relating to the assessment of BMD. Markel ${ }^{70}$ performed a study assessing the BMD of osteotomies of the tibia of the dog. with the view that CT may be useful for prediction of delayed and non-union of fractures.

### 1.7.8 Quantitative ultrasound

Quantitative ultrasound ( QU ) is used to assess the BMD via the measurement of the speed of sound through a bone of known diameter. The speed of sound may be influenced by bone mass. distribution of cortical and trabecular bone and architecture of the bone. ${ }^{58}$ Absorption and reflection of the ultrasound beam are the factors that are important in attenuation. however. frequency is also important. QU uses low frequencies $(20)(0-60)(0) \mathrm{kHz})$ to measure BMD. as the attenuation of the sound waves is almost linear. Numerous in vitro studies substantiate a high correlation between trabecular bone volume and ultrasound attenuation. ${ }^{\text {ss }}$ Other measurements that are performed are velocity. speed of sound and stiffness. ${ }^{\text {sp }}$

QU provides information on bone quantity and quality. ${ }^{80}$ Ultrasound beam attenuation is thought to depend on bone structure and relates to trabecular orientation and size. The more complex the structure the more the ultrasound beam is attenuated or blocked. As beam attenuation is closely correlated with bone volume. osteoporotic bone has a lower attenuation than normal bone. ${ }^{\text {sif }}$ Velocity assesses the speed of sound from one surface to the other and the greater the complexity of the structure the greater the velocity. thus osteoporotic bone has a lower velocity.

There are relatively few studies assessing bone mass in women using QU. however they have been shown to predict fracture risk in both retrospective and prospective studies. ${ }^{\text {sin }}$ Advantages over other methods are no radiation and lower cost of equipment. As the relationship between bone mass. clastic properties of bone and ultrasound has been established but is uncertain. the influence of surrounding soft tissue. the path of the ultrasound waves and the effect of phesical activity have not been adequately determined. QU is primarily a research tool. However it is expected to be used climically in areas where more expensive forms of BMD anal sis are not available and for pregnant women in the near future. ${ }^{5880}$

Ultrasound velocity measurements have been used in combination with SPA in the horse in order to monitor the effects of treadmill exercise on the MCIII. This study found that ultrasound velocity altered with training. however there was no change in BMC or BMD when assessed by SPA. ${ }^{81}$ This may be due to a change in the apparent architecture of the bone without a change in BMD.

### 1.7.9 Neutron activation analysis

Both neutron activation analy sis and Compton scattering techniques are among the earlier methods of noninvasive BMD. They now have negligible clinical influence and their inclusion in this revien is for completeness.

The basis of neutron activation analysis is to use neutrons to assail a small fraction of the total calcium contained in the body. producing a radioactive form of calcium which results in gamma photon emission that can be quantified with external detectors. ${ }^{\text {ss }}$ This technique estimates BMC as in the skeleton the calcium makes up a constant fraction of the mineralized tissue. Measurement sites can either be total body or selected areas. The total calcium measured primarily reflects cortical bone. Precision and accuracy error are higher than other methods of BMD analysis and errors can be caused by heterotrophic calcification such as vascular calcification or heterotrophic ossification e.g. degenerative joint disease. ${ }^{\text {58 }}$

This technique could be applied to horse. but there is a requirement for immobilization for several minutes. which may be difficult to achieve. and as high doses of radiation are required human safety issucs are raised. ${ }^{76}$

### 1.7.10 Compton scattering technique

The Compton scattering technique uses an .x-ray source to irradiate a small amount of bone and interprets information from the seattered beam rather than the transmitted beam. This method measures the BMD in cortical or trabecular bone. Precision error is higher than other forms of analysis due to photon attenuation outside the region of interest and using high photon energies and an increased radiation dose counteracts this. ${ }^{\text {is }}$

The relative accuracy and inexpensite nature of the method may mean that it could be applicable to horses. however. immobilization is required for around 1() minutes and thus its use is likely to be limited. ${ }^{76}$

### 1.8 Summary

As BMD is a major determinant of fracture risk associated with osteoporosis there are numerous techniques that measure this parameter. Limitations of older techniques have been overcome however even the most recent methods have advantages and disadvantages and applications in animals are limited.

### 1.9 Research hypothesis and objectives

Slab fractures of C . contribute to wastage within the equine industry. As sclerosis of this bone occurs prior to fracture and possibly prior to cartilage changes. an objective method of detection of sclerosis would be useful. R.A is a form of quantitative non-invasive bone mineral analvsis that may be clinically applicable to CS in the horse. As RA requires C $\mathbf{C}$, to be isolated from other superimposing structures the tangential view is the only radiographic view that may be used. A standardised procedure is followed when using RA in humans to ensure that changes in photodensity can be attributed to changes in BMD. There is no variation in x-ray beam angle. positioning of the bone or the angle at which the x -ray beam hits the x -ray plate. The procedure involved with achieving a tangential view of C3 is variable. It is difficult to accurately reproduce x -ray beam angle. position of C and the angle at which the x -ray hits the plate when taking this view. In order to determine if RA could used to assess BMD of C 3 it must be established if variation in the angle that the x -ray beam penetrates C3 (C3-beam angle)
significantly affects measured photodensity. On this premise the following null hypothesis was proposed:

Photodensity is not affected by small variations in C3-beam angle.

The objectives of this part of the study are to:

- Radiograph isolated C3's at an x-ray beam angle of 9()$^{\circ}$ as is done in human RA studies and vary the angle in a proximopalmar-distodorsal direction in $5^{\circ}$ increments and determine the photodensity of specific regions of interest ( $\mathrm{ROI}^{\circ}$ s) in millimetres of aluminium.
- Radiograph isolated C3's at the N-ray beam angle suggested in the literature $\left(60^{\circ}\right)$ and vary the angle in proximodorsal- distopalmar direction in $5^{\circ}$ increments and determine the photodensity of specific regions of interest ( $\mathrm{ROI}^{`}$ s) in millimetres of aluminium

During the above experiments the C? beam angle is to vary over 3()$^{\circ}$. and the effect of ROI size on the mean photodensity is unknown. This led to the null hypothesis:

ROI size does not significantly affect mean photodensity over a 3()$^{\circ}$ variation in x-ray beam angle (from 9()$^{\circ}$ to 6()$\left.^{\circ}\right)$.

The objective for this part of the study is to increase and decrease the radius of the ROI by 0.5 mm and determine the mean photodensity for each size of ROI at 5 different sites at an $\times$-ray beam angle of 9()$^{\circ}$ and 6()$^{\circ}$.

As discussed the tangential vien can be achieved using I of 2 methods. which in this project have been labelled View A and Vies B. The final part of the project is to determine the inherent differences between View A and View B. This will be achieved by understanding the:

1. Differences in radiographic technique between the 2 views and therefore the differences in image formation.
2. Area of C? examined by these views and the effect this has on the objective assessment of photodensity of $C 3$.

## MATERIALS AND METHODS

### 2.1 Definitions

- Radiograph - the exposed radiographic film.
- Image - the digitised radiograph.
- X-ray beam angle - the angle between the tube head and the horizontal axis. Horizontal is termed ()$^{\circ}$. vertical is 9()$^{\circ}$ Vertical $x$-ray beam angle is the angle the tube head deviates in a vertical plane. Horizontal x-ray beam angle is the angle the tube head deviates in a horizontal plane.
- Plate-beam angle - the angle at which the s-ray beam strikes the "plate". i.e. the surface of the cassette containing radiographic film. Horizontal is termed ()$^{\circ}$. vertical is $\varphi()^{\circ}$. Vertical plate-beam angle is the angle at which the s-ray beam strikes the plate in a vertical plane Horizontal plate-beam angle is the angle the s-ray beam strikes the plate in a horizontal plane
- C3-beam angle - the angle between the s-ray beam and a transterse plane through C? parallel to the distal articular surface of $C ?$
- Leg angle - the angle between the dorsal surface of the radius and MCIII. full extension of the limb is 18()$^{\circ}$
- Plate angle - the angle between the cassette surface and the dorsal surface of MCIII.
- View A - the tangential view of $C 3$ with the cassette at 9()$^{\circ}$ to the $x$-ray beam. The leg angle is 6()$^{\circ}$. the $x$-rat beam angle 3()$^{\circ}$ and the plate angle is 6()$^{\circ}$ (so the plate-beam angle is as close to 9() degrees as possible) (Figure 2.1).
- View B - the tangential view of C3 with the cassette parallel to. and placed against the dorsal surface of MCIII. The leg angle is 6()$^{\circ}$. the $x$-ray beam angle 3()$^{\circ}$. and the plate angle is ()$^{\circ}$ (Figure 2.2)


Figure 2.1: Line drawing of View A


Figure 2.2: Line drawing of View B

### 2.2 Animals

Bones from fourteen 2-year-old female Thoroughbreds were used. The treatment group consisted of seven fillies broken in over a 6 week period. the control group (the other 7) were confined to pasture pens ( $25 \mathrm{~m} \times 8 \mathrm{~m}$ ). The horses $w$ ere fed lucerne chaff. oats. commercially formulated pelleted ration (sweet feed). and clover hay: the control (non-exercised) animals were fed $75 \%$ of the ration of the exercised horses. All horses were weighed weekly. and observed daily for any clinical abnormality. The 7 exercised horses were boxed overnight and in small pens during the day. They followed a standard commercial training regimen under the direction of a licensed professional trainer. The exercise regimen consisted of 4 weeks slow cantering. + weeks fast cantering. followed by + weeks fast cantering with fast gallops superimposed twice weekly. Horses in the exercised group were ready to trial or race at the conclusion of the training period. These horses were euthanased for other purposes. and the left carpal bones were available.

### 2.3 Disarticulation of the distal row of carpal bones

The left distal carpal row was isolated ber sectioning the collateral ligaments. intercarpal ligaments, palmar carpal fascia and carpometacarpal ligaments. Once disarticulated as much soft tissue as possible was remored. and the distal row was immersed in $98 \%$ alcohol.

### 2.4 Determination of the extent of variation in $x$-ray beam angle required before C3 becomes obscured in the tangential views.

Clinically. within both View A and B small changes in X -ray beam angle appeared to result in variation of the amount of dorsal C 3 visualised. In both tangential views the x-ray beam angle travels in a palmaroproximal to dorsodistal direction as shown in figure 2.1. To determine how much to vary the x -ray beam angle in the main study a pilot study was performed. The goal was to ascertain the variation in angle required before C 3 was completely obscured. This was determined by radiographing 2 legs disarticulated at the radiohumeral joint and frozen at a leg angle of 6()$^{\circ}$ : the x -ray beam angle was varied in $5^{\circ}$ increments from the x -ray beam angle suggested in the literature. ${ }^{82}$ In either tangential view. the x -ray beam angle can be varied by up to $15^{\circ}$ before the dorsal aspect of C 3 becomes completely concealed by either distal radius or proximal MCIII

### 2.5 Film type

The film type used was medical grade HR G-30 film (Fugi Photo Film Company Limited. 26-30) Nishiazabu 2-chome. Minato-ku. Tokio I(1)6. Japan.)

### 2.6 Digitising the radiographs

The radiographs were scanned using an AGFA DUOSCAN (Agfa-Gevaert N. V. Septestraat 27. B-264() Mortsel) desktop. flatbed scanner that has a built in scanning bed for transparencies. Transparencies were scanned directly. there was no intervening glass plate between the lens and the film. preventing diffraction and distortion. AGFA FOTOLOOK (Agfa-Gevaert N.V.

Septestraat 27. B-264() Mortsel) was the software scanning interface. The glass slide that holds the radiograph was cleaned prior to each set of $1+$ radiographs being scanned. The radiographs "ere scanned using the transmission option. grey scale. at 250 lines per inch and $20 \%$. which reduced the image to $20 \%$ of the original radiograph size. The images were then labelled and saved in a bitmap format to a hard drive. Figure 2.3 shows an example image of one bone taken at an x -ray beam angle of 9()$^{\circ}$.


Figure 2.3: Image of isolated distal row taken at 90 degrees.

### 2.7 Determining photodensity of the distal row when the x-ray beam angle is varied from $90^{\circ}$

### 2.7.1 Radiographing the distal row

A Picker-Explorer mobile machine was used to expose film in cassettes with medium intensifying screens. Which were cleaned prior to taking radiographs. A template was designed so that the metal cube. wedge. circle (used for calibration- see below) and distal row of carpal bones would be in a similar position for every radiograph. The thickest part of the wedge was placed closest to the dorsal edge of C3. The template was the same size as the plate used ( 18 cm $\therefore 24 \mathrm{~cm})$ and the beam was collimated to the edge of the template and centred between the wedge and the dorsal aspect of the distal row. (Figure 2.t)


Figure 2.4: The distal row of carpal bones, together with circle, cube and wedge on a radiographic cassette, ready for exposure.

The distal row of carpal bones was removed from alcohol, washed with tap water for 2-3 minutes, towel dried and then placed on the template. On the basis of the findings in section 2.4, the isolated carpal bones were placed on a cassette and radiographed at 9()$^{\circ}$ (control). Further radiographs were taken at $5^{\circ}$ increments to a total of $15^{\circ}$ from 9()$^{\circ}$, thus with the $x$-ray beam travelling in a palmaroproximal to dorsodistal direction the $x$-ray beam angles were $85^{\circ}, 8()^{\circ}$ and $75^{\circ}$. The x -ray head was set for the angle required and a radiograph taken using 45 kV and 6.3MAS. The radiograph was processed using an automatic processor (Kodak RP X-Omat Processor, Model M6B). The first radiograph taken was immediately digitally captured and calibrated to determine the exact plate beam angle, which is the same as the x -ray beam angle because the distal row was lying horizontally on the cassette (Figure 2.5). This process was repeated until the $x$-ray beam angle was as close to the predetermined angles as possible. Once the x -ray head was set to the correct angle, all 14 C3's were radiographed and immediately scanned and digitised to prevent accumulation of particles on the film that may result in subsequent artefactual problems.


Figure 2.5: Line drawing demonstrating that if the distal row of carpal bones is lying horizontal on the cassette the x-ray beam angle is equal to both the C3-beam angle and the plate-beam angle.

### 2.7.2 Image analysis

All image analyses were performed using the Vision Image Processing System (VIPS). ${ }^{83}$ Two macro programs were specifically written for this project. to define the analytical steps performed inside the VIPS program: the calibration program and the region of interest program

### 2.7.2.1 Calibration program

The role of this program was to calibrate the image. to determine the plate-beam angle and allow the photodensity of C 3 to be measured in units of millimetres of aluminium. There are three essential components in each image for the program to function: namely the circle the cube and the wedge.

A stainless steel circle with a 130 mm external diameter was made. The outer edge was bevelled in order to provide a sharp edge on the radiograph and digitised image. regardless of beam angle. The aim of the circle was to calibrate the size (in mm ) of each pixel and determine the aspect ratio. which gives a ratio between the height and the width of each pixel. therebs allowing accurate reproduction of the radiograph in the form of a digitised image. The calibration was completed using a circle-based measurement. identifying the horizontal and vertical diameter of the circle. and using the known diameter of the circle to calculate the aspect
ratio. The circle was as large as possible, to allow more accurate calibration. by reducing the relative error inherent in the measuring process. ${ }^{8+}$

A $15 \mathrm{~mm} \times 15 \mathrm{~mm}$ stainless steel cube was used to determine the angle at which the radiograph was taken. This was achieved by knowing the dimensions of the cube in an image where the plate-beam angle was 9$)^{\circ}$ (perpendicular to the plate). The cube's image on the radiograph when the plate-beam angle varies allowed subsequent determination of $90^{\circ}-x^{\circ}$. Both the iertical and horizontal beam plate angles were determined from the cube using the following equation (Figure 2.6)

$$
\theta=\tan ^{-1} x\left(\frac{C}{L-C}\right)
$$

$\mathrm{C}=$ actual cube length. width and height
$\mathrm{L}=$ image cube length.
$\theta=$.-ray beam angle. vertical or horizontal.


Figure 2.6: Line drawing of determination of $\theta$.

The x-ray beam angle and $C$ ? beam angle could be determined once the beam plate angle was determined. as the distal carpal row was laying horizontal on the plate (Figure 2.5). The dimensions of the cube allowed a change in angle of $2^{\circ}$ to be detected.

The smooth surface (i.e. non-graduated) wedge was aluminium. and measured $23.7 \mathrm{~mm} \times+8.5$ $\mathrm{mm} \times 20 \mathrm{~mm}$ (height x length x width). Its purpose was to provide a scale of densities for comparison with the photodensity of each region of interest (ROI) within C 3 and $\mathrm{C}+$
Aluminium was chosen because its atomic number. specific gravity and attenuation coefficient is similar to that of bone mineral. Within an excised bone radiographed in air the specific misture of mineral. bone matrix and fat is unknown. thus the bone mass determinations made with the wedge are only approximate. The required height of the wedge was determined by radiographing several different aluminium wedges with C 3 s and subjectively deciding the height that encompassed the range of photodensities likely to be encountered. As aluminium has a similar specific gravity and atomic number to bone. the maximum height of the wedge was very similar to the thickness of C ?

By knowing the plate angle and the distance from one end of the wedge (detectable by the presence of a piece of stainless steel along the length of the wedge) to the density of interest. the average photodensity of each ROI could be calibrated to millimetres of aluminum. This was achieved by determining the thickest part of the wedge at the plate-beam angle according to the following equation

$$
\mathrm{T}=\frac{(\mathrm{H} \times \mathrm{L}) \div \sin \theta_{\mathrm{h}}}{\left(\mathrm{~L} \times \sin \theta_{v}\right)-\left(\mathrm{H} \times \cos \theta_{v}\right)}
$$

$\mathrm{T}=$ maximum thickness of wedge at the specified x -ray beam angle.
$\mathrm{H}=$ actual height of the wedge
$\mathrm{L}=$ actual length of the wedge.
$\theta_{h}=$ horizontal angle.
$\theta_{1}=$ vertical angle.

Once the thickness was determined the relative photodensity in terms of millimetres of aluminium of the wedge could be determined. The height of each pixel is ascertained by the following equation:

$$
\text { Pixel height }=\frac{\text { aspect ratio } \times \text { pixel width }}{\operatorname{Cos} \theta \mathrm{w}}
$$

$\theta_{\mathrm{w}}=$ angle of the wedge in the image from vertical.

The photodensity of each pixel is determined by the following equation:

$$
\text { Pixel thickness }(\mathrm{PT})=\frac{\text { pixel height } \times \mathrm{T}}{\mathrm{~L}}
$$

Thus at the thin end of the wedge the first pixel is Xmm of aluminium, the second pixel from the thin end is $(\mathrm{X} \times 2) \mathrm{mm}$, the third is $(\mathrm{X} \times 3) \mathrm{mm}$ and so on until the thickest part of the wedge is reached. An intensity curve is then matched to the thickness curve and the photodensity for a particular point on the wedge can be established. This process allows the wedge to be corrected for changes in plate-beam angle. thereby acting as a standard regardless of angle changes. The wedge linearly increased in photodensity until a certain height. where a plateau was reached. In order to accurately assess photodensity in terms of mm of aluminium the photodensity of the ROI must be within the linear range of the wedge (Figure 2.7).


Figure 2.7: A calibrated image taken at $90^{\circ}$.

### 2.7.2.2 Region of interest program

The ROI program was used to determine the site of 5 ROI's. 4 within C3 and I within C4. The ROI's were circles (so orientation is not important). with a radius of 3 mm and thus an area of $28 \mathrm{~mm}^{2}$. Radiographs were taken of 5 bones where a $6 \mathrm{~mm} \times 6 \mathrm{~mm}$ marker was placed 2 mm from the dorsoproximal edge of the C3. The most dorsal aspect of $C 3$ is at the dorsocentral aspect of the bone. not the dorsoproximal aspect. Therefore in the $90^{\circ}$ image the marker appears to be 6 mm from the most dorsal edge of the C 3 . at $85^{\circ}$ it is 5.3 mm from the dorsal edge. at $80^{\circ}$ it is 4.7 mm from the dorsal edge and at $75^{\circ}$ it appears to be 4 mm from the most dorsal edge of the C3. The ROI's move dorsally as the angle reduces. the degree of displacement is dependant on vertical plate-beam angle. and development of the required equation was based on the findings from marker placement as described above

A consistent width of C 3 was difficult to determine as corners are smooth rather than sharp. thus 9 mim was removed from all borders of the digitised image of the distal row of carpal bones. resulting in sharp points at which to delineate the line across the widest aspect of the C3 ROI's I and + were determined from these points. the distance from each point depended on the x -raybeam angle (at $90^{\circ}$ the centre of the ROI's was at 6 mm from the dorsal edge). Once ROI's I and + were determined a line was drawn between them and ROI 2 and 3 were evenly spaced between I and $\downarrow$. The exact position of ROI's 2 and 3 was determined based on the same relationship as ROI 1 and + . and was also dependent on x -ray beam angle. ROI's 2 and 3 were adjusted slightly to place them at the required distance from the dorsal aspect of the bone. as the dorsal aspect of C 3 is not a straight line. ROI I was placed on the abaxial aspect of the radial facet. ROI 2 was placed on the axial aspect of the radial facet. ROI 3 was placed on the axial aspect of the intermediate facet and $\mathrm{ROI}+$ on the abaxial aspect. ROI 5 was placed in the $\mathrm{C}+$ The centre of ROI 5 was determined by extending the line drawn between ROI's I and +4 and was dependent on the width of $\mathrm{C}+($ Figure 2.8).


Figure 2.8: Image of isolated distal row of carpal bones with lines determining the position of the ROI's. The inner line is achieved by removing 9 mm from outer edge of the distal row. The outer line is dependent of the vertical x-ray beam angle the radiograph was taken at, in this case $60^{\circ}$. The squares within the image are the points that are used to determine the position of the ROI's as described in 2.7.2.2.

Once the ROI program was developed all images were processed with ROI placement in a dorsal position. The dorsal position meant that at a 9()$^{\circ}$ x-ray beam angle the centre of each ROI was 6 mm from the dorsal edge. The images were also processed in a more palmar position. which involved the ROI's at $90^{\circ}$ being placed 9 mm from the dorsal edge. At both dorsal and palmar ROI placements, when the x-ray beam angle was reduced the ROI's moved dorsally as described above (Figure 2.9 and 2.10).


Figure 2.9: ROI's placed in a dorsal position. Figure 2.10: ROI's placed in a palmar postion.

### 2.8 Determining photodensity of the distal row of carpal bones when x-ray beam angle is varied from $60^{\circ}$.

### 2.8.1 Radiographing the distal row

The distal row of carpal bones was radiographed in the same manner as per 3.1 with the exception being the $x$-ray tube was set for the angles 7$)^{\circ}, 65^{\circ}$ or 6()$^{\circ}$ and radiographs were taken at 44 kV and 6.3MAS. Radiographs taken at $75^{\circ}$ in section 7 were also included.

### 2.8.2 Image analysis

### 2.8.2.1. Calibration program

The calibration program was the same as used in 3.2.1. with the exception that for the radiographs at 6()$^{\circ}, 65^{\circ}$ and 7()$^{\circ}$ the calibration circle was modified to 16() mm in diameter which prevented superimposition of the distal row of carpal bones on the circle when the angle was reduced.

### 2.8.2.2 Region of interest program

The region of interest program from 7.2.2 was used. The ROI positions were located in both dorsal and palmar positions as in 7.2.2.

### 2.9 Changing ROI size

### 2.9.1 ROI program

The region of interest program from 7.2.2 was used and the calibrated digitised images of $\varphi()^{\circ}$ and 6()$^{\circ}$ were processed. The program was then manually modified to alter the radii sizes to 2.5 mm and 3.5 mm . The ROI's were placed in the palmar position as for 7.2.2. (Figure's 2.11 and 2.12)


Figure 2.11: ROI's with a radius of 2.5 mm . Figure 2.12: ROI's with a radius of 3.5 mm .

### 2.10 Determination of the inherent differences between View A and B

### 2.10.1 Leg angle

Leg angle was difficult to establish as a result of cranial soft tissuc coverage of the radius. To determine if leg angle could be accurately estimated by a goniometer. 3 legs were disarticulated at the radiohumeral joint and frozen at angles. $55^{\circ} .+5^{\circ} .37 .5^{\circ}$ and leg + was chilled so the angle could be varied. The frozen legs were radiographed in a lateral to medial direction with a focal distance of $14(1) \mathrm{cm}$ and exposure of $68 \mathrm{k} V$ and 5 MAS . Cassettes ( $24 \mathrm{~cm} \times 3(0 \mathrm{~cm}$ ) with medium intensify ing screens were used. and MCIII was placed parallel to the edge of the cassette. The .xray beam was collimated and centred on the palmar aspect of the flexed carpus. and the radiograph checked to ensure the cranial surface of the radius formed a straight line. if not the radiograph was taken again. Measurements determined from the image were. bone-MCIII angle (the angle between the cranial aspect of the radius and MCIII). skin-MCIII angle (the angle between the cranial surface of the forearm |above the carpus| and MCIII) and C3 beam angle (the angle allowing maximum visualisation of C3) (Figure 2.13)


Figure 2.13: Line drawing illustrating bone-MCIII angle( $a$ ), skin-MCIII angle(b) and C3 beam angle(c)

From the measurements taken it was determined that limb flexion angle measurement with the goniometer. was the same as the skin-MCIII angle estimated from the radiographs. but less than the bone-MCIII angle. Therefore it appears that flexing the limb with the aid of a goniometer is a relatively accurate method of determining leg angle.

### 2.10.2 Plate angle

Plate angle is significantly different between View A and B. The cassette is placed parallel ( $\left(0^{\circ}\right)$ to MCIII with the centre at the level of C3 in View B and as a result plate-beam angle is $30^{\circ}$ from horizontal (Figure 2.2). In View A, the cassette is placed in the middle third of MCIII at an angle of $60^{\circ}$. the plate-beam angle is approximately $90^{\circ}($ Figure 2.1). The plate angle difference between View A and B results in radiographic image disparities.

### 2.10.3 X-ray beam angle

X-ray beam angle should be about $3\left(0^{\circ}\right.$ to maximise the amount of $C 3$ seen in both tangential views. the exact angle is dependent on leg angle. When the forelimb is flexed the distal row of carpal bones is almost perpendicular to horizontal. Thus the C 3 -beam angle in both tangential views is 61$)^{\circ}$ when the x -ray beam angle is $30^{\circ}$ (Figure 2.1 and 2.2)

### 2.10.4 Modifying images $A$ and $B$ to form hypothetical image $C$

Images of View A and B appear different. but to identify the same ROI the images must appear similar. Images of View A and B were manipulated using VIPS to form hypothetical View C (Figure 2.14). Leg angle. s-ray beam angle and C3 beam angle remain unchanged in Viell C. however the plate angle was $60^{\circ}$ and the plate position was at the level of the distal row of carpal bones. To accomplish this. magnification of View A. distortion of Vien B and difference in x -ray beam intensity were accounted for.

The image of View A was modified to form View C by multiply ing the length-based dimensions. be the following equation:

$$
\frac{\mathrm{X}}{(\mathrm{X}+\mathrm{A})}
$$

$X=$ the distance from the point source to $C 3$
$\mathrm{X}+\mathrm{A}=$ the total focal distance

The inherent behaviour of the x-ray beam meant a different intensity of x-rays reached the plate in View A compared to View C. which alters photodensity of the image. In View C the photodensity of each pixel will be greater than in View A. Therefore, pixel thickness (photodensity) in View A. was divided by the following equation to form pixel thickness in Vicw C:

$$
\frac{\mathrm{X}^{2}}{(\mathrm{X}+\mathrm{A})^{2}}
$$

View B was modified to Vicw C by correcting for the distortion that occurs in View B by a multiplying the vertical dimension by:

$$
\sin \theta
$$

In View B the area over which the x-ray beam was distributed was increased, thus decreasing x-ray beam intensity and pixel thickness (photodensity) when compared to View C. Therefore. pixel thickness (photodensitỵ) in View B. was divided by the following equation to form pixel thickness in View C:

$$
\sin \theta
$$



Figure 2.14: Line drawing illustrating hypothetical View C.

### 2.10.5 Image analysis

### 2.10.5.1 Calibration

The images were then calibrated using the program as in 3.2.1. The circle was of the same design. however the external diameter was 160 mm . The cube was unchanged and the wedge increased in height to cover the range of photodensities required. In View A the cube. wedge
and circle were placed as in 3.1. In View B the wedge was placed in the opposite direction. because although C3 is radiographed in a palmaroproximal to dorsodistal direction. the x -ray beam strikes the rest of the plate from a dorsoproximal to palmarodistal direction

### 2.10.5.2 Determining the region of interest in image $C$

The ROI program was used to determine + ROI's within C3 and I within C + . The ROI's were circles with a radius of 1 mm . and thus an area of $3.14 \mathrm{~mm}^{2}$. The most lateral and medial point of C 3 was located by the program. and a line drawn between them. The line was divided by 5 and the outer margins of the divisions became the centre of each ROI. The ROI in C+ was placed $2 / 5$ of the distance from the most axial edge. Once the position was determined the actual ROI's were placed 4 mm from the dorsal edge of C3

## 2. 11 Statistical analysis

All analises were performed on the images obtained for each distal row of excised carpal bones (14). The effect of variation of angle and exercise on photodensity as well as ROI size and placement were analy sed using analysis of variance (ANOVA) using type III sums of squares. All analyses were performed with SPSS (version 9.0 for Windows)

Three separate anal ses were conducted:

1. Analysis of the data generated from the dorsal placement of the ROI's at $60^{\circ}$. $65^{\circ} .7()^{\circ} .75^{\circ}$. $80^{\circ}$ and 9()$^{\circ}$.
2. Analysis of the data generated from the palmar placement of the ROI's at 6()$^{\circ}, 65^{\circ}, 70^{\circ} .75^{\circ}$. 8()$^{\circ}$ and 9()$^{\circ}$
3. Anal sis of the data generated from the palmar placement of ROI's of radius size 2.5 mm . 3 mm and 3.5 mm at 9()$^{\circ}$ and 6()$^{\circ}$

Variables in the data sets included horse. ROI (1.2.3.4.5). angle. group (exercised and control) and ROI diameter. Horse was coded as a random effect and nested within group for the purpose of anal sis. All other variables were coded as fixed effects. Bonferoni adjusted t-tests were used to follow up significant effects from the ANOVA and $\alpha$ was set at $0 .(1)$

### 2.1 1.1 Dorsal analysis

The main effect of ROI. angle and group was determined and painwise comparisons were performed on both ROI and angle to establish difference between individual means. As there
were only 2 treatment groups no follow up analysis was performed on group. Pairwise comparisons were also performed between:

- Angle at each ROI
- Angle at each group
- ROI at each angle
- ROI at cach group
- Group at cach angle
- Group at cach ROI


### 2.11.2 Palmar analysis

The main effect of ROI. angle and group was determined and pairw ise comparisons were performed on both ROI and angle to establish difference between individual means. As there were only 2 treatment groups no follow up analvsis was performed on group. Pairvise comparisons were performed between:

- Angle at cach ROI
- Angle at each group
- ROI at cach angle
- ROI at cach group
- Group at each angle
- Group at cach ROI


### 2.11.3 Region of interest size analysis

The main effect of diameter was determined. and pairvise comparisons between angle at a constant diameter size as well as between different diameter sizes at either 6()$^{\circ}$ or 9()$^{\circ}$ were performed.

# THE RELIABILITY OF THE QUANTITATIVE MEASLREMENT OF PHOTODENSITY IN ISOLATED DISTAL ROWS OF CARPAL BONES 


#### Abstract

3.1 Introduction

Radioabsorptiometry (RA) is a sensitive non-invasive quantitative method to assess bone mineral density. ${ }^{63}$ This technique has had a resurgence in recent years and been extensively used in humans. resulting in a number of precision and accuracy studies. ${ }^{6063}$ Radioabsorptiometry in its more primitive form has been applied to the horse and the dog with little success. ${ }^{656}$ There are no known studies of the radioabsorptiometry technique in horses assessing reliability. that is the repeatability or reproducibility of the technique. The purpose of this chapter is to assess the reliability of RA when applied to $C 3$.


### 3.2 Materials and Methods

To test reliability of this technique 2 investigations were performed. Three statistical methods "ere used to determine reliability: these were coefficient of variation. coefficient of variation (within) and intra-class correlation coefficient.

### 3.2.1 Study 1

A single radiograph was taken of an isolated distal row of carpal bones. circle. cube and wedge as described in 2.7.1 and the radiograph was scanned 10 times using the AGFA DUO Scanner as described in 2.6. This resulted in 10 images of the same radiograph that were calibrated as per 2.7.2.1 and had regions of interest (ROI) identified as in 2.7.2.2. The data obtained were the horizontal and vertical plate-beam angle (defined in materials and methods) and 5 ROI's measured in mm of aluminium.

The data were entered into SPSS (version 9.() for Windows) and separate analyses were performed on the ROI data. Mean estimates of photodensity (expressed as millimetres of aluminium). standard deviation and coefficient of variation were estimated on the ROI data. A one way analysis of variance (ANOVA) was performed using ROI as the between subjects factor. The pooled standard deviation was calculated from the ANOVA table and the within subject coefficient of variation was determined for each ROI. The intra-class correlation coefficient (ICC). an alternative method of measuring reliability. was estimated. A one way.
random effects ANOVA was used to estimate between and within ROI mean square terms and ICC calculated for absolute agreement. ${ }^{85}$

The horizontal and rertical x-ray beam angle (see definitions in chapter 2) data were entered into SPSS (version 9.() for Windows) and similar reliability analyses were performed

### 3.2.2 Study 2

In order to determine the repeatability over different radiographs using the same bone at the same angle (bone/angle). 6 bones were radiographed 4 times at exactly the same bone/angle combination. using + different exposures as described in 2.7.1. The radiographs were digitised. and specific ROI's identified as in study 1 .

The data were organised by ROI for analysis. Mean estimates of photodensity (expressed as millimetres of aluminium). standard deviation and coefficient of variation were calculated for cach bone/angle combination within each ROI. A 2-way random effects ANOVA was performed on each level of ROI. and was used to generate within bone/angle coefficients of variation.

A 2-way random effects ANOVA was performed with random factors being bone/angle combination and radiograph. This was used to produce an estimate of the intra-class correlation coefficient for model ICC (2.1) as defined by Shrout and Fleiss. ${ }^{\text {sí }}$

Estimates of the vertical angle of the x-ray beam were made at different bone/angle combinations in $2+$ radiographs. In a similar manner estimates of the horizontal angle were made in 12 radiographs. The data were used to assess reliability of angle determination by the VIPS macro. Estimations of the mean angle. standard deviation and coefficient of variation Were made for each bone/angle combination. A 2-way random effects ANOVA was used to generate a single estimate of pooled standard deviation for the vertical and horizontal data respectively: These were used to estimate within bone/angle coefficient of variation. A 2-way random effects ANOVA was also used to generate intra-class correlation coefficient estimates for the data using the model ICC (2.1) following the notation of Shrout and Fleiss. ${ }^{\text {st, }}$

### 3.3 Results

### 3.3.1 Study 1

A total of 5() measurements from 1() images of the same radiographs were used in the ROI data analysis. The mean. standard error and the coefficient of variation is presented in table 3.1.

Table 3.1: Results of raw data and descriptive statistics for ROI after digitisation of a radiograph 10 times.

| Replicate | ROI I | ROI 2 | ROI 3 | ROI 4 | ROI 5 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 165.28 | 135.34 | 129.54 | 128.62 | 124.10 |
| 2 | 162.72 | 134.49 | 128.27 | 127.53 | 124.93 |
| 3 | 162.49 | $13+.08$ | 127.78 | 12660 | 123.74 |
| + | 16064 | 134.14 | 126.30 | 126.15 | 124.29 |
| 5 | 162.87 | 134.49 | 129.77 | 128.04 | 124.86 |
| 6 | 161.04 | $13+10$ | 127.80 | 126.80 | 123.62 |
| 7 | 162.35 | 136.40 | 128.56 | 128.60 | 12503 |
| 8 | 163.61 | 134.78 | 128.22 | 128.50 | 124.70 |
| 9 | 162.33 | 135.68 | 127.65 | 128.29 | $124.4+$ |
| 10 | 163.73 | 135.48 | 129.05 | 128.31 | 125.74 |
| Mean | 162.11 | $134.9(0$ | 128.26 | 127.75 | 124.55 |
| Standard <br> Deviation | 1.33 | 0.79 | 1.04 | 0.91 | 1064 |
| Coefficient <br> of variation | $0.82 \%$ | $0.58 \%$ | $081 \%$ | $0.72 \%$ | $0.51 \%$ |

Table 3.2: Results of one-way ANOVA for ROI after digitisation of a radiograph 10 times

|  | Sum of <br> Squares | Degrees of <br> freedom | Mean square | F value | Significance |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Between ROI's | 9729.39 | + | $2+32.348$ | 2.584 .76 | $(0)(0)()$ |
| Within ROI's | +2.35 | +5 | $09+1$ |  |  |
| Total | 9771.74 | 49 |  |  |  |

The standard deviation of the overall population is calculated to be 0.97 . The coefficient of variation (within) is presented in table 3.3

Table 3.3: The coefficient of variation (within) for each ROI after digitisation of a radiograph 10 times.

| ROI | Mean | Standard deviation <br> (population) | Coefficient of <br> variation (within) |
| :---: | :---: | :---: | :---: |
| 1 | 162.7072 | 0.97 | $0.60 \%$ |
| 2 | 134.8995 | 0.97 | $0.72 \%$ |
| 3 | 128.2635 | 0.97 | $0.76 \%$ |
| + | $127.7+57$ | 0.97 | $0.76 \%$ |
| 5 | 124.5471 | 0.97 | $0.78 \%$ |

The CV is consistently less than $1 \%$. indicating that the amount of variation is very small relative to the value of the mean.

The ICC was 0.9961 ( $95 \%$ CI 0.9882 . 0.9995 ). indicating that $99.61 \%$ of variation in mean photodensity was due to variation between ROI's and not from differences between the replications.

The statistical processes described above were performed on the angle data of the 10 images and are presented in tables 3.4 .3 .5 and 3.6

Table 3.4: Results of raw data and descriptive statistics for variation of horizontal and vertical angle after digitisation of a radiograph 10 times.

| Replicate | Horizontal angle | Vertical angle |
| :---: | :---: | :---: |
| 1 | $9(.30)$ | 89.77 |
| 2 | $9(0.3)$ | 89.91 |
| 3 | 90.26 | 89.54 |
| + | $9(0) 76$ | $9(0.47$ |
| 5 | 90.78 | 89.50 |
| 6 | 90.30 | 89.75 |
| 7 | 90.35 | 89.70 |
| 8 | 90.33 | 8972 |
| 9 | 90.31 | 89.56 |
| 10 | $9(0) 27$ | 89.78 |
| Mean | $9(0.4)$ | 89.77 |
| Standard Deviation | (0.20) | () 28 |
| Coefficient of variation | (0.22\% | 0.31\% |

Table 3.5: Results of one-way ANOVA for angle after digitisation of radiograph 10 times.

|  | Sum of <br> Squares | Degrees of <br> freedom | Mean square | F value | Significance |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Between <br> angles | 1.97 | 1 | 1.967 | 34.221 | $0 .(0)$ |
| Within angles | 1.03 | 18 | $5.7+51\left(0^{-2}\right.$ |  |  |
| total | 3.00 | 19 |  |  |  |

From this analysis the standard deviation of the overall population is calculated to be (0.2t. The coefficient of variation (within) is presented in table 6 .

Table 3.6: The coefficient of variation (within) for both horizontal and vertical angle after digitisation of a radiograph 10 times.

| Angle | Mean | Standard deviation <br> (population) | Coefficient of <br> variation within |
| :---: | :---: | :---: | :---: |
| Horizontal | $9(0.40$ | 0.24 | $0.26 \%$ |
| iertical | 89.77 | $0.2 \downarrow$ | $0.27 \%$ |

These results indicate that. for the vertical and horizontal angle as the CV is less than $0.3 \%$. the amount of variation is very small relative to the mean. The ICC was 0.7686 ( $95 \% \mathrm{CI} 0.321$ to (0.9497). This means that $76.9 \%$ of the total variation is due to differences between the 2 angle methods and $231 \%$ of the variance is due to the differences between replications

### 3.3.2 Study 2

A total of 12() ROI measurements were made from $2+$ images of 6 bones taken at varying bonc/angle combinations. The following table shows values organised by regions of interest The mean is the average photodensity of ROI values from + images for each bone/angle combination Standard deviation. coefficient of variation. pooled standard deviation and within coefficient of variation are presented in table 3.7.

Table 3.7: Descriptive statistics of varying bone/angle combinations including coefficient of variation and coefficient of variation (within).

| Angle | Bone | ROI | $\begin{gathered} \text { X-ray } \\ 1 \end{gathered}$ | $\begin{gathered} \text { X-ray } \\ 2 \end{gathered}$ | $\begin{gathered} \text { X-ray } \\ 3 \end{gathered}$ | $\begin{gathered} \text { X-ray } \\ 4 \end{gathered}$ | Mean | SD | $\begin{aligned} & \text { CV } \\ & \% \end{aligned}$ | $\begin{gathered} \mathrm{CV} \\ \left(\begin{array}{c} \text { (within) } \\ \% \end{array}\right. \\ \hline \end{gathered}$ | $\underset{(\text { pooled) }}{\text { (pD }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 9() | 1 | I | 156.6 | 161.4 | 162 | 161.6 | 16().4 | 2.55 | 1.59 | 1.19 | 1.912 |
| 9() | 2 | I | 159.1 | 157.5 | 156.1 | 159.6 | 158.1 | 1.59 | 1.()1 | 1.21 | 1.912 |
| 9() | 3 | I | 87.8 | 89.3 | 87.5 | $9(0.7$ | 88.8 | 1.48 | 1.67 | 2.15 | 1.912 |
| 85 | $+$ | I | 163.3 | 1628 | 161.8 | 163.4 | 162.8 | () 73 | 0.45 | 1.17 | 1.912 |
| 85 | 5 | I | 154.6 | 155.5 | 154.0 | 156.9 | 155.2 | 1.26 | ().81 | 1.23 | 1.912 |
| 8() | 6 | 1 | $15+3$ | 148.1 | $1+8.8$ | 152.3 | 150.9 | 2.93 | 1.97 | 1.27 | 1.912 |
| 9() | I | 2 | 130.9 | 130.5 | 13() .7 | 132 | 131.() | (). 67 | ().51 | 2.23 | 2.916 |
| 9() | 2 | 2 | 178.9 | 172.4 | 172.3 | 172.4 | $17+.0$ | 3.27 | 1.88 | 1.68 | 2.916 |
| 9() | 3 | 2 | 86.7 | 88.2 | 86.2 | 89.2 | 87.6 | 1.38 | 1.57 | 3.33 | 2.916 |
| 85 | $t$ | 2 | 130.9 | 131.5 | 13 () | 131.9 | 131.1 | () 83 | (0.63 | 2.22 | 2.916 |
| 85 | 5 | 2 | 170.5 | 168.3 | 169.6 | 172.9 | $17(0.3$ | 1.94 | 1.14 | 1.71 | 2916 |
| $8($ | 6 | 2 | $17+.7$ | 162.2 | 162.7 | 165.7 | 166.3 | 5.79 | 3.48 | 1.75 | 2.916 |
| 9() | 1 | 3 | 126.2 | 125.4 | 125.4 | 125.4 | 125.4 | ().57 | () 46 | 1.93 | 2.48 |
| 9() | 2 | 3 | $16+.3$ | 162.6 | 161.2 | 162.8 | 162.8 | 1.28 | (). 79 | 1.48 | $2+18$ |
| 9() | 3 | 3 | $8(0)$ | 82.1 | $8(0) 9$ | 81.8 | 81.8 | 1.31 | 1.6() | 2.95 | $2+18$ |
| 85 | $t$ | 3 | 129.1 | 127.7 | 124.8 | 127.7 | 127.7 | 203 | 1.59 | 1.89 | $2+18$ |
| 85 | 5 | 3 | 161.9 | 161.8 | 161.2 | 162.1 | 162.1 | ().9 4 | (0.58 | 1.49 | $2 .+18$ |
| 8() | 6 | 3 | 169.5 | 158 | 159.5 | 162.6 | 162.6 | 514 | 3.16 | 1.49 | $2+18$ |
| 9() | 1 | $t$ | 126.5 | 126.3 | $12+3$ | 1259 | 125.9 | 1.05 | ().84 | 1.51 | 1.896 |
| 9() | 2 | $+$ | 151.9 | 149.2 | 148 | $1+9.7$ | $1+9.7$ | 1.63 | 1.109 | 1.27 | 1.896 |
| 9() | 3 | $t$ | 81.6 | 83.5 | 81.7 | 82.8 | 82.8 | 1.38 | 1.66 | 2.29 | 1.896 |
| 85 | $t$ | $+$ | 127.7 | 128 | 125.7 | 127.2 | 127.2 | $1 .(1) 2$ | (0.81 | 1.49 | 1.896 |
| 85 | 5 | $+$ | 149.4 | 150 | $1+9.5$ | 150.1 | 150.1 | (0.92 | ().61 | 1.26 | 1.896 |
| 8() | 6 | $+$ | 155.9 | $1+7.9$ | $1+8.1$ | 150.8 | 150.1 | 3.74 | 2.48 | 1.26 | 1.896 |
| 9() | I | 5 | 121.4 | 121.5 | 12() .5 | 121.5 | 121.5 | ().82 | (). 67 | 1.26 | 1534 |
| 9() | 2 | 5 | 132.7 | 131 | 129.9 | 131.3 | 131.3 | 1.16 | 0.88 | 1.17 | 1.534 |
| 9() | 3 | 5 | 110.3 | 114.4 | 110.6 | 111.2 | 111.2 | 1.107 | (1).96 | 1.38 | 1.534 |
| 85 | $t$ | 5 | 123.5 | 122.7 | 121.6 | 123.() | 123.0 | 1.12 | ().91 | 1.25 | 1.534 |
| 85 | 5 | 5 | 131.2 | 130.3 | 128.2 | 13()$+$ | 130.4 | 1.61 | 1.23 | 1.18 | 1.534 |
| 8() | 6 | 5 | 132.9 | 129.1 | 126.4 | 129.5 | 129.5 | 2.67 | 2.16 | 1.18 | 1.534 |

The ICC from each region was calculated and is shown in table 3.8

Table 3.8: The intra-class coefficient for each ROI at varying bone/angle combinations

| ROI | ICC | $95 \%$ Confidence <br> Interval |
| :---: | :---: | :---: |
| 1 | $(0.9955$ | $0.98+4$ to 0.9993 |
| 2 | $(0.9925$ | 0.9737 to 0.9988 |
| 3 | $0.99+4$ | 0.9799 to 0.9991 |
| + | $0.99+8$ | 0.9811 to 0.9992 |
| 5 | 0.9612 | $(0.8312$ to 0.9941 |

These results indicate that for ROI's $1-4$ more than $99 \%$. and for ROI 5 more than $96 \%$. of the total variation observed in the data collected from different bone/angle combinations is due to
difference in bone/angle combinations. Conversely the proportion of variation in the data which can be attributed to the imaging and calibration processes is estimated for each ROI by ICC. For ROI $1-+$ this is less than $1 \%$ and for ROI 5 is less than $4 \%$.

The statistical processes described in the materials and methods were performed on the vertical and horizontal angle data and are presented in tables 3.9 and 3.10 .

Table 3.9: Results of descriptive statistics and the coefficient of variation (within) for vertical angle when the bone/angle combination is varied.

| bone | angle | $\begin{gathered} \text { X-ray } \\ 1 \end{gathered}$ | $\begin{gathered} \text { X-ray } \\ 2 \end{gathered}$ | $\begin{gathered} \text { X-ray } \\ 3 \end{gathered}$ | $\begin{gathered} \text { X-ray } \\ + \end{gathered}$ | Mean | SD | CV\% | $\begin{aligned} & \text { CV\%\% } \\ & \text { (within) } \end{aligned}$ | $\underset{\text { (pooled) }}{\mathbf{S D}}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| I | 9() | 89.66 | 9() .1() | 89.68 | 9() $.4+$ | 89.97 | (). 37 | (). +1 | (0.53 | ().478 |
| 2 | 9() | 89.18 | 89.77 | 89.68 | 9() $.4+$ | 89.77 | 0.52 | (0.58 | 0.53 | 0.478 |
| 3 | 9() | 90.56 | $9(0.48$ | 9() .46 | 9()$+4$ | 9() .48 | ().05 | ().06 | 0.53 | 0.478 |
| 4 | 85 | 84.30 | $8+80$ | 85.0() | $8+9$ | $8+75$ | (0.31 | 0.37 | 0.56 | 0.478 |
| 5 | 85 | 84.60) | 84.8() | 8+9() | $8+.6$ | $8+73$ | ().15 | (0.18 | 0.56 | (0.478 |
| 6 | 8() | 78.8 | 79.4 | $8(0.80$ | $8(0.20$ | 79.78 | ().92 | 1.15 | 0.6 | 0.478 |

The ICC for the vertical angle was $0.9874(95 \% \mathrm{CI} 0.95+2$ to (0.998). indicating that $98.74 \%$ of the variation is due to variation between bones rather than variation between radiographs.

Table 3.10: Results of descriptive statistics and the coefficient of variation (within) for horizontal angle when the bone/angle combination is varied.

| bone | angle | $\begin{gathered} \text { X-ray } \\ 1 \end{gathered}$ | $\begin{gathered} \text { X-ray } \\ 2 \end{gathered}$ | $\begin{gathered} \text { X-ray } \\ 3 \end{gathered}$ | $\begin{gathered} \text { X-ray } \\ 4 \end{gathered}$ | Mean | SD | C ${ }^{\text {\% }}$ | $\begin{aligned} & \text { CV\% } \\ & \text { (within) } \end{aligned}$ | $\underset{\text { (poolecl) }}{\text { SD }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 9() | $9(0.16$ | $9(0.38$ | 90.55 | 9() 67 | $9(0.4+$ | () 23 | (0.25 | (). 26 | (0.234 |
| 2 | 9() | 9()$.() 2$ | $9(0.33$ | 9() .63 | 9() .67 | $9(0 .+2$ | 0.3 | () 34 | (0.26 | (0)243 |
| 3 | 9() | $9(0.80$ | 9() .4 | 9() .72 | 9() 72 | 9() 68 | (0.15 | (). 16 | () 26 | 0.234 |

The ICC for the horizontal angle was (0. $18.31(95 \%$ CI 0.00$)$ to (0.9366). indicating that $18.31 \%$ of the variation is due to variation between bones rather than variation between radiographs.

### 3.4 Discussion

Once processed each image provides information on the plate-beam angle at which the radiograph was taken. in both vertical and horizontal directions. and the mean photodensity in terms of mm of aluminium of + ROI's within $C 3$ and I within $C+$ The transformation of a radiograph into a digitised image is a highly precise event as evidenced by very low coefficient of variation and coefficient of variation (within) of each ROI in study I. Although the coefficient of variation and coefficient of variation (within) assess the amount of variation within the data. they do not indicate how much of the variation results from the measuring process. The ICC seeks to determine the percentage of variation due to the measuring process. compared to inherent differences between the scanned images. The ICC in study I indicates onl. $0.39 \%$ of total variation between the ROI's is due to the measurement technique. The
excellent reproducibility is likely to be as a result of calculating the aspect ratio using a large circle. It appears that the method of calculating the aspect ratio greatly facilitates the reproducibility of the image when a large calibration circle is used, which may not be true when smaller calibration circles are used. The other factor involved in a high reproducibility is the ROI program's ability to detect the same ROI between images. The variation that did occur is likely to have arisen for 2 reasons: firstly there is always random noise when digitising an image that is uncorrelated between images. Secondly. even when digitising the same radiograph several times there are small variations in pivel placement. which affect edges and areas of fine detail and affect all aspects of image calibration and detection of ROI's,

Digitisation of the radiograph results in minimal total variation of the horizontal and vertical angles between replications as shown by the coefficient of variation and the coefficient of variation (within). The ICC indicates that $23.1 \%$ of the variation is due to measuring error between replications. This appears to be high. but is only a percentage of the total variation. which itself is very small as determined by the coefficient of variation.

Study 2 revealed when the same bone was radiographed + times at exactly the same $x$-ray beam angle using vary ing exposures the CV between radiographs taken at the same bone/angle combination was less than $4 \%$. The reliability was excellent as evidenced by the ICC for each ROI For all ROI's within C3 the CV was less than $1 \%$. indicating very little difference in radiographs resulting from measuring errors. within C + the CV was increased to just under $4 \%$. The high repeatability of this technique is due to calibration of the images and the ability of the ROI program to detect the same ROI's between images. The difference between C 3 and $C+$ mas be the way the ROI's were positioned. A consistent width of C 3 was difficult to determine as corners are smooth rather than sharp. and a specified distance was remored from all borders of the distal row of carpal bones. resulting in sharp points at which to delineate the line across the widest aspect of the C'3. ROI's I and + were extrapolated. based on a linear relationship from these points. and ROI's 2 and 3 were placed between them The centre of ROI 5 was determined drawing a line from ROI + and was dependent on the width of $\mathrm{C}+$. The fact that the ROI's within C 3 were positioned between 2 points. whereas the ROI within $C+$ was positioned based on one point may have resulted in C +4 having a higher measuring error

The second part of study 2 was to determine if plate-beam angle accurately reflected x -ray beam angle. Vertical plate-beam angle varied less than 1\% from the x-ray beam angle. and the horizontal plate-beam angle varied less than $0.3 \%$ from the x -ray beam angle as demonstrated by the coefficient of variation (within). The ICC of the vertical angle suggests that of the total variation, $1.26 \%$ is due to differences between successive radiographs that occurs as a result of
the measuring process. The ICC of the horizontal angle suggests that $81 \%$ of the total variation was due to difference between successive radiographs as a result of measuring errors. This appears to be high. but is only a percentage of the total variation. which is very small as determined by the coefficient of variation (within). The reason for variability of angle between successive radiographs is due to the dimensions of the cube. The size of the cube chosen was such that a change in $2^{\circ}$ could be detected. had the cube been larger the variation is likely to have been even smaller.

In vivo precision errors of radiographic methods of bone mineral density analysis have been emploved br a number of investigators and the precision error varies between $1 \%$ and $15 \%$ (using coefficient of variation) ${ }^{63}$ The methods employed in this research appear to have less than $1 \%$ precision error (based on coefficient of variation and intra-class coefficient) when determining the photodensity of ROI's. This is less than in some previously reported studies. ${ }^{63}$ however similar to the study by Yang et al. In both Yang et al's investigation as well as this study the same $x$-ray machine was used. by the same operator and the radiographs were processed at the same time using the same machine. In the study by Colbert ${ }^{63}$ a number of different x -ray machines were used. with vary ing techniques by differing operators and at vary ing times. thereby more accurately simulating clinical application

From this study it can be concluded that the reliability of the method of radiographic absorptiometry used in this project is very high in the circumstances in which it was used.

## RESULTS

The outcome of interest is a measurement of bone density expressed in terms of millimetres of aluminium. The experimental method and design has been described in materials and methods

Three separate analy ses were run on

1. Data generated with ROI's placed dorsally with x -rav beam angles of 6()$^{\circ}$. $65^{\circ}, 7()^{\circ}, 75^{\circ}, 8()^{\circ}$ and 9()$^{\circ}$
2. Data generated with ROI's placed dorsally with x -ray beam angles of 6()$^{\circ}, 65^{\circ} .7()^{\circ} .75^{\circ} .80^{\circ}$ and 9()$^{\circ}$

3 Data generated from the palmar placement of ROI's of radius size 2.5 mm . 3 mm and 3.5 mm at 9()$^{\circ}$ and 6()$^{\circ}$

The most complex interaction. namely angle/group/ROI interaction. was not significant Therefore no follow up statistical tests were performed on 3-way interactions. Many of the twoway interactions were significant and a number of follow-up tests were performed

All raw data is in appendix I, while the statistical analyses are in tabulated form within appendix 2 . The results are presented graphically. In the column graphs, columns that are the same colours are not statistically different from each other when $\alpha$ is set at 0.05 . Values represented by columns containing 2 colours are not significantly different from any column containing either one of those 2 colours. For example


Figure 4.1: Graph illustrating the effect of colour in reading the graph.

Numbers I and 2 are significantly different from numbers $3,4,5$ and 6 . Numbers 3 , and 5 are significantly different from 1,2 and 6 . Number 6 is significantly different from $1,2,3$ and 5 . Number 4 is significantly different from numbers I and 2.

## 4.IDorsal analysis

The raw data is presented in appendix I under the heading Dorsal analysis The mean data is presented in appendix 2 under the heading of Dorsal anal! sis.

| Source |  | Typelli Sum of Squares | Degrees of Freedom | Mean Square | F Valuc | Significance |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Interce pt | Hypothesis Error | $\begin{aligned} & 6821166(03 \\ & 96666.20 \end{aligned}$ | $\begin{aligned} & 1 \\ & 12 \end{aligned}$ | $\begin{aligned} & 6821166(0) \\ & 805.52^{a} \end{aligned}$ | $8+68.06$ | () ()()() |
| Angle | Hypothesis Error | $\begin{aligned} & 2378+(02 \\ & 2293(0+1 \end{aligned}$ | $\begin{aligned} & 6 \\ & 408 \end{aligned}$ | $\begin{aligned} & 396+()() \\ & 56.2() 2^{h} \end{aligned}$ | 70.531 | () ())() |
| Group | Hypothesis Error | $\begin{aligned} & 26718.24 \\ & 9666.20 \end{aligned}$ | $\begin{aligned} & 1 \\ & 12 \end{aligned}$ | $\begin{aligned} & 26718.24 \\ & 805.52^{\circ} \end{aligned}$ | 3317 | () ())() |
| ROI | Hypothesis Error | $\begin{aligned} & 11877.05 \\ & 2293(0.41 \end{aligned}$ | $\begin{aligned} & t \\ & 4(08 \end{aligned}$ | $\begin{aligned} & 2969.26 \\ & 56.2()^{b} \end{aligned}$ | 52.83 | () ())() |
| Horse (group) | Hypothesis Error | $\begin{aligned} & 9666.20 \\ & 22930+1 \end{aligned}$ | $\begin{aligned} & 12 \\ & +(08 \\ & \hline \end{aligned}$ | $\begin{aligned} & 8(05.517 \\ & 56.20)^{\mathrm{b}} \\ & \hline \end{aligned}$ | 14.33 | (). ())() |
| Angle/ Group | Hypothesis Error | $\begin{aligned} & 7+6.7 \\ & 2293(0 .+1 \end{aligned}$ | $\begin{aligned} & 6 \\ & +08 \end{aligned}$ | $\begin{aligned} & 12+.+5 \\ & 56.2\left(0^{h}\right. \end{aligned}$ | 2.21 | (). $0+1$ |
| Angle/ ROI | Hypothesis Error | $\begin{aligned} & 3995.00 \\ & 22930+1 \end{aligned}$ | $\begin{aligned} & 24 \\ & +(08 \end{aligned}$ | $\begin{aligned} & 166 .+6 \\ & 56.20^{\mathrm{b}} \end{aligned}$ | 2.96 | () (0)() |
| Group/ ROI | Hypothesis Error | $\begin{aligned} & 2229.99 \\ & 22930+1 \end{aligned}$ | $\begin{aligned} & t \\ & 4(0) \end{aligned}$ | $\begin{aligned} & 5.57 .5() \\ & 56.2()^{\mathrm{b}} \end{aligned}$ | 9.92 | ().()()) |
| Angle/ Group/ ROI | Hypothesis Error | $\begin{aligned} & 7+9.06 \\ & 2293(0 .+1 \end{aligned}$ | $\begin{aligned} & 2 t \\ & 4(08 \end{aligned}$ | $\begin{aligned} & 31.21 \\ & 56.2\left(0^{k}\right. \end{aligned}$ | 55 | (0).958 |

a. MS(Horse(Group))
b. MS(crror)

Table 4.1: A table of the overall ANOVA results for the dorsal analysis.

### 4.1.1 Main effect of angle

Pairwise comparisons were performed to compare the main effect of $x$-ray beam angle when ROI's were in a dorsal position. The tabulated data and actual significance values are within appendix 2 under the heading of 1.1


Figure 4.2: Column graph of the main effect of $x$-ray beam angle on the photodensity of ROI's when in a dorsal position. Error bars represent $+/-1$ standard error (s.e.m.).

The photodensity at 6()$^{\circ}$ was significantly different to $65^{\circ}(\mathrm{p}$ value $0 .(0) 2), 7()^{\circ}$ (p value $<(0.0)$ ) ), $75^{\circ}(\mathrm{p}$ value $<(0.0) 1), 80^{\circ}(\mathrm{p}$ value $<(0.0) 1), 85^{\circ}(\mathrm{p}$ value $<(0.0) 1)$ and $90^{\circ}(\mathrm{p}$ value $<(0.0() 1)$. The photodensity at $65^{\circ}$ was significantly different to 7()$^{\circ}(\mathrm{p}$ value $<() .()() 1), 75^{\circ}(\mathrm{p}$ value $<(0).(0)$ ) and $80^{\circ}\left(\mathrm{p}\right.$ value $<(0.0(0)), 85^{\circ}(\mathrm{p}$ value $<(0.0) 1)$ and $90^{\circ}(\mathrm{p}$ value $<(0.0) 1)$. The photodensity at $70^{\circ}$ was significantly different to of $85^{\circ}\left(\mathrm{p}\right.$ value $<(0.0() 1)$ and 9()$^{\circ}(\mathrm{p}$ value $<(0.0() 1)$. The photodensity at $75^{\circ}$ was significantly different to $85^{\circ}(\mathrm{p}$ value $<() .()() 1)$ and 9()$^{\circ}(\mathrm{p}$ value $<() .()() 1)$. The photodensity at $80^{\circ}$ was significantly different to $85^{\circ}(\mathrm{p}$ value $<() .()() 1)$ and $90^{\circ}(\mathrm{p}$ value $<() .0() 1)$.

These results show that when the ROI's were in a dorsal position there was significant variation in photodensity when angle was varied less than $5^{\circ}$ from $60^{\circ}$ (the $x$-ray beam angle recommended in the literature when taking the tangential view of C 3 ), or less than $10^{\circ}$ from 9()$^{\circ}$ (the x-ray beam angle at which the majority of radiographs of excised bones are taken).

### 4.1.1.1Angle at one level of ROI

Pairwise comparisons were performed to compare angle means at each level of ROI, when ROI's were in a dorsal position. The tabulated data and actual significance values are within appendix 2 under the heading of I.I.I.


Figure 4.3: Column graph of the effect of angle on photodensity of ROI 1 in a dorsal position. Error bars represent $+/-1$ s.e.m.

Variation in angle does not significantly affect the photodensity of ROI I


Figure 4.4: Column graph of the effect of angle on photodensity of ROI 2 in a dorsal position. Error bars represent $+/-1$ s.e.m.

At ROI 2 the photodensity at 6()$^{\circ}$ was significantly different to 7()$^{\circ}(\mathrm{P}$ value $<() .()() \mathrm{l}), 75^{\circ}(\mathrm{p}$ value $<() .()() 1), 8()^{\circ}(p$ value $<() .()() 1), 85^{\circ}(p$ value $<() .()() 1)$ and 9()$^{\circ}(p$ value $<() .()() 1)$. The photodensity at $65^{\circ}$ was significantly different to $8\left(0^{\circ}(P\right.$ value ()$.()() 1), 85^{\circ}(p$ value $<() .()() 1)$ and 9()$^{\circ}(p$ value $<() .()() 1)$. The photodensity at 7()$^{\circ}$ was significantly different to $85^{\circ}(p$ value $<() .()()$ l ) and 9()$^{\circ}(p$ value $<() .()() 1)$. The photodensity at $75^{\circ}$ was significantly different to $85^{\circ}(p$ value $<(0 .()() 1)$ and 9()$^{\circ}\left(p\right.$ value $<(0 .()() 1)$. The photodensity at $80^{\circ}$ was significantly different to $85^{\circ}(p$ value $(0 .() 21)$ and 9()$^{\circ}(p$ value ()$.()(01)$.


Figure 4.5:Column graph of the effect of angle on photodensity of ROI 3 in a dorsal position. Error bars represent $+/-1$ s.e.m.

At ROI 3 the photodensity at $60^{\circ}$ was significantly different to $70^{\circ}(p$ value $<(0.0) 01), 75^{\circ}(p$ value $<(0) 0(0)), 80^{\circ}(p$ value $<(0.0) 1), 85^{\circ}(p$ value $<(0.0) 1)$ and $90^{\circ}(p$ value $<(0.00)$ ). The photodensity at $65^{\circ}$ was significantly different to $70^{\circ}\left(p\right.$ value $0 .(044), 75^{\circ}(p$ value 0.006$), 80^{\circ}(p$ value $<0.001)$, $85^{\circ}\left(\mathrm{p}\right.$ value $<(0.001)$ and 9()$^{\circ}\left(\mathrm{p}\right.$ value $<(0.0)(1)$. The photodensity at $70^{\circ}$ was significantly different to $85^{\circ}\left(\mathrm{p}\right.$ value $(0.002)$ and $90^{\circ}\left(\mathrm{p}\right.$ value $<(0.001)$. The photodensity at $75^{\circ}$ was significantly different to $85^{\circ}(\mathrm{p}$ value 0.016$)$ and $90^{\circ}(\mathrm{p}$ value $0 .(0) 3)$. The photodensity at $80^{\circ}$ was significantly different $90^{\circ}(\mathrm{p}$ value ().()36).


Figure 4.6: Column graph of the effect of angle on photodensity of ROI 4 in a dorsal position. Error bars represent $+/-1$ s.e.m.

At ROI + the photodensity at $60^{\circ}$ was significantly different from $70^{\circ}\left(p\right.$ value $(0.0)(0)$ ), $75^{\circ}(\mathrm{p}$
 photodensity at $65^{\circ}$ was significantly different to $75^{\circ}(p$ value 0.042$), 80^{\circ}(p$ value 0.017$), 85^{\circ}$ ( p value $<(0.0) \mathrm{I}$ ) and $90^{\circ}\left(\mathrm{p}\right.$ value $<(0.00 \mathrm{I})$. The photodensity at $70^{\circ}$ was significantly different to $85^{\circ}\left(\mathrm{p}\right.$ value 0.0003 ) and $90^{\circ}(\mathrm{p}$ value $<0.001)$. The photodensity at $75^{\circ}$ was significantly different to $90^{\circ}\left(\mathrm{p} \text { value }(0.003) \text {. The photodensity at } 80^{\circ} \text { was significantly different to } 9\right)^{\circ}(\mathrm{p}$ value (0.008).


Figure 4.7: Column graph of the effect of angle on the photodensity of ROI 5 in a dorsal position. Error bars represent $+/-1$ s.e.m.

At ROI 5 the photodensity at 6()$^{\circ}$ was significantly different to 7()$^{\circ}(p$ value ()$\left..()) 9\right) .75^{\circ}(p$ value ()$.(0) 3), 8()^{\circ}\left(p\right.$ value $(0.0() 7), 85^{\circ}\left(p\right.$ value $<(0 .()() 1)$ and 9()$^{\circ}(p$ value $<() .()() 1)$. The photodensity at $65^{\circ}$ was significantly different to $85^{\circ}\left(p\right.$ value ().()()2) and 9()$^{\circ}(p$ value $<() .()() 1)$. The photodensitỵ at $70^{\circ}$ was significantly different to 9()$^{\circ}$ ( $p$ value $(0.0)()$ ). The photodensitỵ at $75^{\circ}$ was significantly different to 9()$^{\circ}\left(p\right.$ value ().()15). The photodensity at 8()$^{\circ}$ was significantly different to 9()$^{\circ}$ (p value ().()()7).

### 4.1.1.2 Angle at one level of group

Pairwise comparisons were performed to compare angle means while holding group (nonexercise or exercise) constant when ROI's were in a dorsal position. The tabulated data and actual significance values are within appendix 2 under the heading of I.1.2.


Figure 4.8: Column graph of the effect of angle on the photodensity of the non-exercised group when ROI's were in a dorsal position. Error bars represent $+/-1$ s.e.m.

In the non-exercised group the photodensity at $60^{\circ}$ was significantly different to $65^{\circ}(\mathrm{p}$ value $<(0 .(0) 1), 7()^{\circ}(\mathrm{p}$ value $<(0.0) 1), 75^{\circ}\left(\mathrm{p}\right.$ value $<(0.0() 1), 8\left(0^{\circ}(\mathrm{p}\right.$ value $<(0.0) 1), 85^{\circ}(\mathrm{p}$ value $<(0.0() 1)$ and 9()$^{\circ}\left(\mathrm{p}\right.$ value $<(0.0() 1)$. The photodensity at $65^{\circ}$ was significantly different to $85^{\circ}(\mathrm{p}$ value $<(0 .()() 1)$ and 9()$^{\circ}\left(\mathrm{p}\right.$ value $<(0 .()() 1)$. The photodensity at $70^{\circ}$ was significantly different to $85^{\circ}(\mathrm{p}$ value $<\left(0 .()(0)\right.$ ) and 9()$^{\circ}(\mathrm{p}$ value $<() .()() 1)$. The photodensity at $75^{\circ}$ was signif icantly different to $85^{\circ}\left(\mathrm{p}\right.$ value $(0.0() 1)$ and 9()$^{\circ}\left(\mathrm{p}\right.$ value $<(0.0)(0)$. The photodensity at $80^{\circ}$ was significantly different to $85^{\circ}\left(\mathrm{p}\right.$ value $<(0.0() 1)$ and 9()$^{\circ}(\mathrm{p}$ value $<() .()() 1)$.


Figure 4.9: Column graph of the effect of angle on the photodensity of the exercised group when ROI's were in a dorsal position. Error bars represent $+/-1$ s.e.m.

In the exercised group photodensity at $60^{\circ}$ was significantly different to $70^{\circ}(\mathrm{p}$ value ()$.()() I)$. $75^{\circ}(\mathrm{p}$ value $(0.0) 1), 8\left(0^{\circ}(\mathrm{p}\right.$ value $<(0.0) 1), 85^{\circ}(\mathrm{p}$ value $<(0.0) 1)$ and $90^{\circ}(\mathrm{p}$ value $<(0 .()() 1)$. The photodensity at $65^{\circ}$ is significantly different to $70^{\circ}(\mathrm{p}$ value 0.01$), 75^{\circ}\left(\mathrm{p}\right.$ value $(0.0(0)), 80^{\circ}(\mathrm{p}$ value $<(0.0() 1), 85^{\circ}\left(\mathrm{p}\right.$ value $<\left(0 .()()\right.$ I) and 9()$^{\circ}\left(\mathrm{p}\right.$ value $<() .()()$ I). The photodensity at 7()$^{\circ}$ was significantly different to $85^{\circ}(p$ value $<() .()() 1)$ and 9()$^{\circ}(p$ value $<() .()() 1)$. The photodensity at $75^{\circ}$ was significantly different to $85^{\circ}\left(\mathrm{p}\right.$ value $(0 .()() 1)$ and 9()$^{\circ}(\mathrm{p}$ value $<() .()() 1)$. The photodensity at $80^{\circ}$ was significantly different to $85^{\circ}\left(\mathrm{p}\right.$ value $<(0.0() 1)$ and 9()$^{\circ}(\mathrm{p}$ value $<(0.0) 1)$.

These results suggest that a variation of greater than $5^{\circ}$ from 9()$^{\circ}$ and an even smaller variation from 6()$^{\circ}$ results in a significant variation in photodensity. When radiographing the excised distal row of carpal bones between 8()$^{\circ}$ and $65^{\circ}$ variation in angle does not significantly affect photodensity:

### 4.1.2 Main effect of ROI

Pairwise comparisons were performed to compare the main effect of ROI when ROI's were in a dorsal position. The tabulated data and actual significance values are within appendix 2 under the heading of 1.2 .


Figure 4.10: Column graph demonstrating the main effect of ROI site on photodensity when ROI's were in a dorsal postion. Error bars represent + /- 1 s.e.m.

Photodensity of ROI I was significantly different from ROI 2 ( p value $<(0) .001$ ), ROI 3 ( p value $<(0.001)$, ROI 4 (p value $<0.001$ ). ROI 5 ( p value $<(0.001$ ). Photodensity of ROI 2 was significantly different from ROI 3 ( p value 0.005 ) and ROI 4 ( p value $<0.001$ ). Photodensity of ROI 3 was significantly different from ROI 5 (p value 0.001 ). Photodensity of ROI 4 was significantly different from ROI 5 (p value $<() .001$ ).

### 4.1.2.1 ROI at one level of group

Pairwise comparisons were performed comparing ROI means, holding group (non-exercise or exercise) constant when ROI's were in a dorsal position. The tabulated data and actual significance values are within appendix 2 under the heading of 1.2.1.


Figure 4.11: Column graph of the effect non-exercise on the photodensity of ROI's in a dorsal position. Error bars represent $+/-1$ s.e.m.

In the non-evercised group photodensity of ROI I was significantly different from ROI 2 (p value $<(0.00$ I), ROI 3 (p value $<0.00$ I), $\mathrm{ROI} 4(\mathrm{p}$ value $<(0.00 \mathrm{I})$, ROI 5 (p value 0.002 ). The photodensity of ROI 2 was significantly different from ROI 4 (p value 0.023 ) and ROI $5(\mathrm{p}$ value $<(0.0)(1)$. The photodensity of ROI 3 was significantly different from ROI 5 ( p value $<(0,00 \mathrm{I})$. The photodensity of ROI 4 was significantly different from ROI 5 (p value $<(0.00 \mathrm{I})$.


Figure 4.12: Column graph of the effect of exercise on the photodensity of ROI's in a dorsal position. Error bars represent $+/-1$ s.e.m.

In the exercised group photodensity of ROI I was significantly different from ROI 3 (p value $<(0 .()() 1)$, ROI $4(\mathrm{p}$ value $<() .()() 1)$, ROI $5(\mathrm{p}$ value $(0 .()() 2)$. The photodensity of ROI 2 was significantly different from ROI 3 ( p value ().()21), ROI 4 (p value ().()23) and ROI 5 ( p value ().()()ŋ) 。

### 4.1.2.2 ROI at one level of angle

Pairwise comparisons were performed to compare ROI means, holding angle constant when ROI's were in a dorsal position. The tabulated data and actual significance values are within appendix 2 under the heading of 1.2.2.


Figure 4.13: Column graph of the photodensity of ROI's in a dorsal position when x-ray beam angle was 60 degrees. Error bars represent $+/-1$ s.e.m.

At $60^{\circ}$ the photodensity of ROI I was significantly different from ROI 2 (p value $\left.<(0) .()\right)$ I). ROI $3(\mathrm{p}$ value $<()()()$ l $)$, ROI $4(\mathrm{p}$ value $<() .()() 1)$, ROI $5(\mathrm{p}$ value ()$.()() 2)$. The photodensity of ROI 3 was significantly different from ROI 5 (p value ().()4). The photodensity of ROI 4 was significantly different from ROI $5(\mathrm{p}$ value (0.()16).


Figure 4.14: Column graph of photodensity of ROI's in a dorsal position when x-ray beam angle was 65 degrees. Error bars represent $+/-1$ s.e.m.

At $65^{\circ}$ the photodensity of ROI I was significantly different from ROI 2 ( p value $<() .()()$ ) $)$, ROI 3 (p value $<(0 .()() 1)$, ROI $4(\mathrm{p}$ value $<(0 .()() 1)$ and ROI 5 (p value ().()()2). The photodensity of ROI 3 was significantly different from ROI 5 (p value ().()()7). The photodensity of ROI 4 was significantly different from ROI 5 (p value (0.()()1).


Figure 4.15: Column graph of photodensity of ROI's in a dorsal position when x-ray beam angle was at 70 degrees. Error bars represent $+/-1$ s.e.m.

At $70^{\circ}$ the photodensity of ROI I was significantly different from ROI $2(\mathrm{p}$ value 0.002 ), ROI 3 (p value $<0.001$ ), ROI 4 (p value $<0.001$ ) and ROI 5 (p value 0.011 ).


Figure 4.16: Column graph of photodensity of ROI's in a dorsal postion when $x$-ray beam angle was 75 degrees. Error bars represent $+/-1$ s.e.m.

At $75^{\circ}$ the photodensity of ROI I was significantly different from ROI 3 (p value 0.008 ) and $\mathrm{ROI}+(\mathrm{p}$ value $<(0.00$ ) $)$.


Figure 4.17: Column graph of photodensity of ROI's in a dorsal position when x-ray beam angle was $\mathbf{8 0}$ degrees. Error bars represent $+/-1$ s.e.m.

At $80^{\circ}$ the photodensity of ROI I was significantly different from ROI 4 (p value 0.004 ).


Figure 4.18: Column graph of photodensity of ROI's in a dorsal position when x-ray beam angle was 85 degrees. Error bars represent $+/-1$ s.e.m.

At $85^{\circ}$ the photodensity of ROI 2 was significantly different from ROI 4 ( p value 0.018 ).


Figure 4.19: Column graph of photodensity of ROI's in a dorsal position when x-ray beam angle was 90 degrees. Error bars represent $+/-1$ s.e.m.

At $90^{\circ}$ the photodensity of ROI 2 was significantly different form ROI 4 (p value 0.026 ).

Variation in angle appears to affect ROI photodensity. As the angle reduces from $90^{\circ}$ to $60^{\circ}$ the photodensity of each ROI decreases however the relationship between ROI's I to 5 appears similar at all angles. The change in actual value means that at some angles some ROI's is not significantly different to others while at others they are.

### 4.1.3 Main effect of group

Pairvise comparisons were performed on the main effect of group when ROI were in a dorsal position. The tabulated data and actual significance values are within appendix 2 under the heading of 1.3


Figure 4.20: Column graph of the effect of group on photodensity when ROI's were in a dorsal position. Error bars represent $+/-1$ s.e.m.

Photodensity of the non-exercised group was significantly less than the exercised group (p value <(0.001)

Pairwise comparisons were performed to compare group means when ROI's were in a dorsal position. The tabulated data and actual significance values are within appendix 2 under the heading of 1.3.1.


Figure 4.21: Column graph of the effect of group on angle when ROI's were in a dorsal position. Error bars represent $+/$ - 1 s.e.m.

Photodensity of the exercised group was significantly greater than the non-exercised group at $60^{\circ}(\mathrm{p}$ value $<0.001), 65^{\circ}(\mathrm{p}$ value $<0.001), 70^{\circ}(\mathrm{p}$ value $<0.001), 75^{\circ}(\mathrm{p}$ value $<0.001), 80^{\circ}(\mathrm{p}$ value $<0.001), 85^{\circ}(\mathrm{p}$ value $<0.001)$ and $90^{\circ}(\mathrm{p}$ value $<(0.001)$.

### 4.1.3.2 Group at one level of ROI

Pairwise comparisons were performed to compare group means, holding ROI constant when ROI's were in a dorsal position. The tabulated data and actual significance values are within appendix 2 under the heading of 1.3.2.


Figure 4.22: Column graph of the effect of group on photodensity of ROI's when in a dorsal position. Error bars represent $+/-1$ s.e.m.

Photodensity significantly increased from the non-exercised to the exercised group at ROI I (p value $<(0.0()$ l $)$, ROI $2(\mathrm{p}$ value $<(0.0()$ l $)$, ROI $3(\mathrm{p}$ value $<(0,(0)$ I), ROI $4(\mathrm{p}$ value $<(0.0()$ l ) and ROI $5(\mathrm{p}$ value $<(0 .()() 1)$. ROI 2 had the greatest increase in photodensity between groups ( $15.5 \%$ ). ROI 3 had the next largest increase in photodensity ( $14.6 \%$ ), followed by ROI 4 (13.4\%), ROI $1(9 \%)$ and ROI $5(6.5 \%)$.

### 4.2 Palmar analvsis

The raw data is presented in appendix I under the heading Palmar anal sis. The mean data is presented in appendix 2 under the heading of Palmar analysis.

| Source |  | TypeIII Sum of Squares | Degrees <br> of freedom | Mcan Square | F Value | Significance |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Intercept | Hypothesis Error | $\begin{aligned} & 818+751+4) \\ & 1688+.38 \end{aligned}$ | $\begin{aligned} & 1 \\ & 12 \end{aligned}$ | $\begin{aligned} & 818+751 \\ & 1+\left(07(0) 3^{a}\right. \end{aligned}$ | 5817.03 | ().()0) |
| Angle | Hypothesis Error | $\begin{aligned} & 6997.88 \\ & 22618.20 \end{aligned}$ | $\begin{aligned} & 6 \\ & 408 \end{aligned}$ | $\begin{aligned} & 1166.31 \\ & 55.44^{b} \end{aligned}$ | 21.04 | (0.0)() |
| Group | Hypothesis Error | $\begin{aligned} & 4(0938.81 \\ & 1688+.38 \end{aligned}$ | $\begin{aligned} & 1 \\ & 12 \end{aligned}$ | $\begin{aligned} & 4(0938.81 \\ & 1+\left(07.03^{a}\right. \end{aligned}$ | 29.09 | () ())() |
| ROI | Hypothesis Error | $\begin{aligned} & 48+8.33 \\ & 22618.2 \end{aligned}$ | $\begin{aligned} & + \\ & +(08 \end{aligned}$ | $\begin{aligned} & 1212.08 \\ & 55.44^{6} \end{aligned}$ | 21.86 | ().())() |
| Horse(group) | Hypothesis Error | $\begin{aligned} & 1688+.38 \\ & 22618.20 \end{aligned}$ | $\begin{aligned} & 12 \\ & +(1) 8 \end{aligned}$ | $\begin{aligned} & 1+() 7 .() 3 \\ & 55.44^{b} \end{aligned}$ | 25.38 | ().0)() |
| Angle/Group | Hypothesis Error | $\begin{aligned} & 47+83 \\ & 22618.20 \end{aligned}$ | $\begin{aligned} & 6 \\ & 4(0) \end{aligned}$ | $\begin{aligned} & 79.14 \\ & 55.4 t^{h} \end{aligned}$ | 1.43 | (0.203 |
| Angle/ROI | Hypothesis Error | $\begin{aligned} & 1196(07 \\ & 22618.2(0) \end{aligned}$ | $\begin{aligned} & 24 \\ & 4(1) 8 \end{aligned}$ | $\begin{aligned} & 49.83 \\ & 55 .+t^{h} \end{aligned}$ | 0.899 | (0.6)4 |
| Group/ROI | Hypothesis Error | $\begin{aligned} & 5(09(0.84 \\ & 22618.2(0) \end{aligned}$ | $\begin{aligned} & t \\ & +(0) \end{aligned}$ | $\begin{aligned} & 1272.71 \\ & 55.44^{\mathrm{b}} \end{aligned}$ | 22.96 | 0.0)() |
| Angle/Group /ROI | Hypothesis Error | $\begin{aligned} & 191.35 \\ & 22618.200 \end{aligned}$ | $\begin{aligned} & 24 \\ & 4(08 \end{aligned}$ | $\begin{aligned} & 7.97 \\ & 5.5 . t t^{h} \end{aligned}$ | $0.14+$ | $1.0(0)$ |

a. MS(Horse(Group))
b. MS(Error)

Table 4.2: A table of the overall ANOVA results for the palmar analysis.

### 4.2.1 Main effect of angle

Pairwise comparisons were performed on the main effect of angle when ROI's were in a palmar position. The tabulated data and actual significance values are within appendix 2 under the heading of 2.1


Figure 4.23: Column graph of the main effect of x -ray beam angle on photodensity when ROI's were in the palmar postion. Error bars represent $+/-1$ standard error (s.e.m.).

The photodensity at $60^{\circ}$ was significantly different to $65^{\circ}(\mathrm{p}$ value $<0.001), 70^{\circ}(\mathrm{p}$ value $<0.001), 75^{\circ}\left(\mathrm{p}\right.$ value $<(0.001), 80^{\circ}\left(\mathrm{p}\right.$ value $<(0.001), 85^{\circ}(\mathrm{p}$ value $<0.001)$ and $90^{\circ}(\mathrm{p}$ value $<0.001)$. The photodensity at $65^{\circ}$ was significantly different to $70^{\circ}(\mathrm{p}$ value 0.019$), 75^{\circ}(\mathrm{p}$ value $<(0.001), 80^{\circ}\left(\mathrm{p}\right.$ value $<(0.001)$ and $90^{\circ}\left(\mathrm{p}\right.$ value $(0.007)$. The photodensity at $70^{\circ}$ was significantly different to $75^{\circ}(\mathrm{p}$ value 0.019$)$ and $80^{\circ}$ (p value $<(0.001)$. The photodensity at $75^{\circ}$ was significantly different to $85^{\circ}\left(\mathrm{p}\right.$ value 0.002 ) and $90^{\circ}(\mathrm{p}$ value 0.046$)$. The photodensity at $80^{\circ}$ was significantly different from $85^{\circ}\left(\mathrm{p}\right.$ value $<(0.001)$ and $90^{\circ}(\mathrm{p}$ value $(0.001)$.

These results show that when the ROI's were in a palmar position there was significant variation in photodensity when angle was varied less than $5^{\circ}$ from $60^{\circ}$ (the $x$-ray beam angle recommended in the literature when taking the tangential view of C3), or less than $10^{\circ}$ from $90^{\circ}$ (the x -ray beam angle at which the majority of radiographs of excised bones are taken).

### 4.2.1.1 Angle at one level of ROI

Pairwise comparisons were performed to compare x-ray beam angle means at one level of ROI when ROI's were in a palmar position. The tabulated data and actual significance values are within appendix 2 under the heading of 2.1.1


Figure 4.24: Column graph of the effect of $x$-ray beam angle on photodensity of ROI 1 when ROI's were in a palmar position. Error bars represent $+/-1$ s.e.m.

At ROI I the photodensity of $60^{\circ}$ was significantly different to $70^{\circ}$ ( p value 0.00 I ), $75^{\circ}$ ( p value $<0.001), 80^{\circ}(\mathrm{p}$ value $<0.001), 85^{\circ}\left(\mathrm{p}\right.$ value $<(0.001)$ and $90^{\circ}(\mathrm{p}$ value $<0.001)$. Photodensity at $65^{\circ}$ was significantly different to $75^{\circ}(\mathrm{p}$ value 0.019$), 80^{\circ}$ (p value $<(0.001)$ and $90^{\circ}$ (p value 0.(029).


Figure 4.25: Column graph of the effect of $x$-ray beam angle on photodensity of ROI 2 when ROI's were in a palmar position. Error bars represent $+/-1$ s.e.m.

At ROI 2 the photodensity of $60^{\circ}$ was significantly different to $75^{\circ}(\mathrm{p}$ value 0.0() 6$)$ and $80^{\circ}(\mathrm{p}$ value (0.()02).


Figure 4.26: Column graph of the effect of $x$-ray beam angle on the photodensity of ROI 3 when ROI's were in a palmar position. Error bars represent $+/-1$ s.e.m.

At ROI 3 the photodensity at $60^{\circ}$ was significantly different to $80^{\circ}(\mathrm{p}$ value 0.011 ).


Figure 4.27: Column graph of the effect of $x$-ray beam angle on ROI 4 when ROI's were in a palmar position. Error bars represent +/- 1 s.e.m.

At ROI 4 the photodensity at $60^{\circ}$ was significantly different to 7()$^{\circ}$ (p value 0.022 ), $75^{\circ}(\mathrm{p}$ value $(0 .()() \mathrm{I})$ and $80^{\circ}(\mathrm{p}$ value $<(0.0) \mathrm{I})$.


Figure 4.28: Column graph of the effect of x -ray beam angle at ROI 5 when ROI's were in a palmar position. Error bars represent $+/-1$ s.e.m.

At ROI 5 the photodensity at $60^{\circ}$ was significantly different from $80^{\circ}$ (p value 0.015 ).

### 4.2.1.2 Angle at one level of group

Pairvise comparisons were performed to compare $x$-ray beam angle means while holding group (non-exercise or exercise) constant when ROI's were in a palmar position. The tabulated data and actual significance values are within appendix 2 under the heading of 2.1.2.


Figure 4.29: Column graph of the effect of $x$-ray beam angle on photodensity of the nonexercised group when ROI's were in a palmar position. Error bars represent $+/-1$ s.e.m.

In the non-exercised group the photodensity at $60^{\circ}$ was significantly different from $75^{\circ}(\mathrm{p}$ value $<0.001)$ and $80^{\circ}\left(\mathrm{p}\right.$ value $<(0.001)$. The photodensity at $65^{\circ}$ was significantly different from $75^{\circ}(\mathrm{p}$ value 0.024$)$ and $80^{\circ}(\mathrm{p}$ value $<0.001)$. The photodensity at $80^{\circ}$ was significantly different from $85^{\circ}$ (p value 0.013).


Figure 4.30: Column graph of the effect of $x$-ray beam angle on photodensity of the exercised group when ROI's were in a palmar position. Error bars represent $+/-1$ s.e.m.

In the exercised group the photodensity at $60^{\circ}$ was significantly different to $65^{\circ}(\mathrm{p}$ value $<(0.001), 7()^{\circ}\left(\mathrm{p}\right.$ value $<(0.001), 75^{\circ}\left(\mathrm{p}\right.$ value $<(0.001), 80^{\circ}\left(\mathrm{p}\right.$ value $<(0.001), 85^{\circ}(\mathrm{p}$ value $<(0.001)$ and $90^{\circ}(\mathrm{p}$ value $<0.001)$. The photodensity at $65^{\circ}$ was significantly different to $75^{\circ}(\mathrm{p}$ value $0.015)$ and $80^{\circ}(\mathrm{p}$ value 0.001$)$.

### 4.2.2 Main effect of ROI

Pairwise comparisons were performed to compare the main effect of ROI when ROI's were in a palmar position. The tabulated data and actual significance values are within appendix 2 under the heading of 2.2


Figure 4.31: Column graph of the main effect of ROI site on photodensity when ROI's were in a palmar position. Error bars represent $+/-1$ s.e.m.

Photodensity of ROI I was significantly different from ROI 2 ( p value $<(0)(0)$ ) ), ROI 3 ( p value $<(0 .()() 1)$, ROI $4(\mathrm{p}$ value $<() .()() 1)$, ROI $5(\mathrm{p}$ value $<() .()() 1)$. Photodensity of ROI 2 was significantly different from ROI 3 (p value (0.()()5) and ROI 4 ( $p$ value $<(0 .()() 1)$. The photodensity of ROI 3 was significantly different from ROI 5 (p value ().()()1). The photodensity of ROI 4 was significantly different from ROI 5 ( $p$ value $<() .()() 1)$.

### 4.2.2.1 ROI at one level of group

Pairwise comparisons were performed to compare ROI means, holding group (non-evercise) constant when ROI's were in a dorsal position. The tabulated data and actual significance values are within appendix 2 under the heading of 2.2.1.


Figure 4.32: Column graph of the effect of the non-exercise group on photodensity of ROI's in a palmar position. Error bars represent $+/-1$ s.e.m.

In the non-exercised group the photodensity of ROI I was significantly different from ROI 2 (p value $<(0.001$ ), ROI 3 ( p value $<(0.00$ I) and ROI 4 (p value $<(0.0)$ I). The photodensity of ROI 2 was significantly different from ROI 5 ( p value $<(0.0)$ I). The photodensity of ROI 3 was significantly different from ROI 5 (p value $<(0.0) 1)$. The photodensity of ROI 4 was significantly different from ROI 5 (p value $<0.001$ ).


Figure 4.33: Column graph of the effect of exercise on the photodensity of ROI's in a palmar position. Error bars represent $+/-1$ s.e.m.

In the exercised group the photodensity of ROI I was significantly different from ROI 3 (p value $<0.001$ ), ROI $4(\mathrm{p}$ value $<(0.001)$ and ROI $5(\mathrm{p}$ value $<(0.001)$. The photodensity of ROI 2 was significantly different from ROI 3 (p value (0.006) and ROI 5 (p value $<0.001$ ). The photodensity of ROI 4 was significantly different from ROI 5 (p value 0.009).

### 4.2.2.2 ROI at one level of angle

Pairwise comparisons were performed to compare ROI means, holding angle constant when ROI's were in a palmar position. The tabulated data and actual significance values are within appendix: 2 under the heading of 2.2.2


Figure 4.34: Column graph of the photodensity of ROI's in a palmar position when x-ray beam angle was 60 degrees. Error bars represent $+/-1$ s.e.m.

At 6()$^{\circ}$ the photodensity of ROI I was significantly different from ROI 2 (p value $<(0) .(0) 1$ ). ROI $3(\mathrm{p}$ value $<(0 .()() 1)$, ROI $4(\mathrm{p}$ value $<() .()() 1)$ and ROI $5(\mathrm{p}$ value $<() .()() 1)$.


Figure 4.35: Column graph of the photodensity of ROI's in a palmar position when x-ray beam angle was 65 degrees. Error bars represent $+/-1$ s.e.m.

At $65^{\circ}$ the photodensity of ROI I was significantly different from ROI 2 (p value 0.004 ), ROI 3 (p value 0.001 ), ROI 4 (p value 0.001 ) and ROI 5 (p value $0 .(024$ ).


Figure 4.36: Column graph of the photodensity of ROI's in a palmar position when the angle was 70 degrees. Error bars represent $+/-1$ s.e.m.

At $70^{\circ}$ the photodensity of ROI I was significantly different from ROI 3 (p value (0.019) and ROI 4 (p value (0.002).


Figure 4.37: Column graph of the photodensity of ROI's in a palmar position when x-ray beam angle was 75 degrees. Error bars represent $+/-1$ s.e.m.

When angle is $75^{\circ}$ photodensity of each ROI was not significantly different from each other.


Figure 4.38: Column graph of the photodensity of ROI's in a palmar position when the angle was 80 degrees. Error bars represent + - 1 s.e.m.

When angle is $80^{\circ}$ photodensity of each ROI was not significantly different from each other.


Figure 4.39: Column graph of photodensity of ROI's in a palmar position when angle was 85 degrees. Error bars represent $+/-1$ s.e.m.

When angle is $85^{\circ}$ photodensity of each ROI was not significantly different from each other.


Figure 4.40: Column graph of photodensity of ROI's in a palmar position when angle was 90 degrees.

When angle was $90^{\circ}$ photodensity of each ROI was not significantly different from each other

Variation in angle appears to affect ROI photodensity, however the relationship between ROI's I to 5 appears similar at all angles. At all angles ROI 2, 3, 4 and 5 did not have significantly different photodensities. ROI I's photodensity may significantly vary from the other ROI's depending on the angle.

### 4.2.3 Main effect of group

Pairwise comparisons were performed on the main effect of group when ROI were in a palmar position. The tabulated data and actual significance values are within appendix 2 under the heading of 2.3


Figure 4.41: Column graph of the main effect of group on photodensity when ROI's were in a palmar position.

Photodensity of the non-exercised group was significantly different from the exercised group ( p value $<(0.001$ ).

### 4.2.3.1 Group at one level of angle

Pairwise comparisons were performed to compare group means, at varying angles when ROI's were in a palmar position. The tabulated data and actual significance values are within appendix 2 under the heading of 2.3.1.


Figure 4.42: Column graph of the effect of $x$-ray beam angle on the photodensity of the exercised and non-exercised group.

Photodensity significantly increased between the non-exercised and the exercised group at $60^{\circ}$ ( p value $<(0.001), 65^{\circ}\left(\mathrm{p}\right.$ value $<(0.001), 70^{\circ}\left(\mathrm{p}\right.$ value $<(0.001), 75^{\circ}(\mathrm{p}$ value $<0.001), 80^{\circ}(\mathrm{p}$ value $<0.001), 85^{\circ}(\mathrm{p}$ value $<0.001)$ and $90^{\circ}(\mathrm{p}$ value $<(0.001)$.

### 4.2.3.2 Group at one level of ROI

Pairwise comparisons were performed to compare group means, at varving ROI's when ROI's were in a palmar position. The tabulated data and actual significance values are within appendix 2 under the heading of 2.3.2.


Figure 4.43: Column graph of the effect of group on the photodensity of ROI's in a palmar position.

Photodensity significantly increased from the non-exercised to the exercised group at ROI I (p
 5 (p value 0.003 ). ROI 2 had the greatest increase in photodensity ( $17.5 \%$ ) as a result of exercise. This was followed by ROI 4 ( $15 \%$ ) and ROI 3 ( $15 \%$ ), then ROI 1 (12.5\%) and finally ROI 5 (4.5\%).

### 4.3 Region of interest size analysis

The raw data is presented in appendix I under the heading ROI size analysis. The mean data is presented in appendix 2 under the heading of ROI size analysis

| Source |  | TypeIII Sum Of Squares | Degrecs of Frecdom | Mean Square | F Value | Significance |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Intercept | Hy pothesis Error | $\begin{aligned} & 7.3+1.3+1.83 \\ & 16296.99 \end{aligned}$ | $\begin{aligned} & 1 \\ & 12 \end{aligned}$ | $\begin{aligned} & 73+1.3+1.83 \\ & 1358.108^{\mathrm{a}} \end{aligned}$ | $5+(15.69$ | () ())() |
| Angle | Hypothesis Error | $\begin{aligned} & 71.30 .2 \\ & 19801.50 \\ & \hline \end{aligned}$ | $\begin{aligned} & 1 \\ & 3+8 \end{aligned}$ | $\begin{aligned} & 71.30 .20 \\ & 56.9\left(0^{\mathrm{b}}\right. \end{aligned}$ | 125.31 | (0.0)() |
| Group | Hypothesis Error | $\begin{aligned} & +3966.59 \\ & 16296.91 \end{aligned}$ | $\begin{aligned} & 1 \\ & 12 \end{aligned}$ | $\begin{aligned} & +3966.59 \\ & 1.580088^{4} \end{aligned}$ | 32.37 | ().0)() |
| ROI | Hypothesis Error | $\begin{aligned} & 5(0.5 .19 \\ & 19801.50 \end{aligned}$ | $\begin{aligned} & 4 \\ & 3+8 \end{aligned}$ | $\begin{aligned} & 1258.8(0) \\ & 56.80^{6} \end{aligned}$ | 22.12 | (0.0)() |
| Radius | Hypothesis Error | $\begin{aligned} & 22.67 \\ & 19801.50 \end{aligned}$ | $\begin{aligned} & 2 \\ & 3+8 \end{aligned}$ | $\begin{aligned} & 11.33 \\ & 56.9\left(0^{\mathrm{b}}\right. \end{aligned}$ | 0.19 | (0.819 |
| Horse (Group) | Hypothesis Error | $\begin{aligned} & 16296.91 \\ & 19801.50 \\ & \hline \end{aligned}$ | $\begin{aligned} & 12 \\ & 3+8 \\ & \hline \end{aligned}$ | $\begin{aligned} & 1.558 .08 \\ & 56.9\left(0^{6}\right. \\ & \hline \end{aligned}$ | 23.87 | () ())() |
| Angle /Group | Hypothesis Error | $\begin{aligned} & 626.37 \\ & 1980150 \\ & \hline \end{aligned}$ | $\begin{aligned} & 1 \\ & 3+8 \end{aligned}$ | $\begin{aligned} & 626.37 \\ & 56990^{6} \end{aligned}$ | 11.01 | ().0) 1 |
| Angle/ROI | Hypothesis Error | $\begin{aligned} & 2078.201 \\ & 19801.50 \end{aligned}$ | $\begin{aligned} & 4 \\ & 3+8 \end{aligned}$ | $\begin{aligned} & 519.55 \\ & 56.900^{16} \end{aligned}$ | 9.13 | (0.0)() |
| Angle /Radius | Hypothesis Error | $\begin{aligned} & +92.22 \\ & 198(01.50 \end{aligned}$ | $\begin{aligned} & 2 \\ & 3+8 \end{aligned}$ | $\begin{aligned} & 2+6.11 \\ & 56.9()^{\mathrm{b}} \end{aligned}$ | 4.32 | (0.014 |
| Group/ROI | Hypothesis Error | $\begin{aligned} & 3292.92 \\ & 1980150 \end{aligned}$ | $\begin{aligned} & + \\ & 3+8 \end{aligned}$ | $\begin{aligned} & 82323 \\ & 56,9()^{6} \end{aligned}$ | 14.47 | 0.000 |
| Group /Radius | Hypothesis Error | $\begin{aligned} & 96.39 \\ & 19801.50 \end{aligned}$ | $\begin{aligned} & 2 \\ & 3+8 \end{aligned}$ | $\begin{aligned} & 48.19 \\ & 56.90 \end{aligned}$ | 0.85 | 0.4.30 |
| ROI/Radius | Hypothesis Error | $\begin{aligned} & 29(0 .+6 \\ & 198015(0) \end{aligned}$ | $\begin{aligned} & 8 \\ & 3+8 \end{aligned}$ | $\begin{aligned} & 36.31 \\ & 56.910^{6} \end{aligned}$ | 0.64 | ().746 |
| Angle /Group/ROI | Hypothesis Error | $\begin{aligned} & 62.59 \\ & 19801.50 \end{aligned}$ | $\begin{aligned} & 4 \\ & 3+8 \\ & \hline \end{aligned}$ | $\begin{aligned} & 15.65 \\ & 569\left(0^{\mathrm{b}}\right. \end{aligned}$ | (1). 27 | (1).89+ |
| Group/ROI/ Radius | Hypothesis Error | $\begin{aligned} & 430.88 \\ & 19801.50 \end{aligned}$ | $\begin{aligned} & 8 \\ & 3+8 \end{aligned}$ | $\begin{aligned} & 56.86 \\ & 56.9\left(0^{\mathrm{b}}\right. \end{aligned}$ | 0.95 | (1).478 |
| Angle/ROI/ Radius | Hypothesis Error | $\begin{aligned} & 150.87 \\ & 19801.50 \end{aligned}$ | $\begin{aligned} & 8 \\ & 3+8 \end{aligned}$ | $\begin{aligned} & 18.86 \\ & 56.9)^{10} \end{aligned}$ | () 3.3 | 0.954 |
| Angle/Group /Radius | Hypothesis Error | $\begin{aligned} & 91 .+2 \\ & 19801.50 \end{aligned}$ | $\begin{aligned} & 2 \\ & 3+8 \end{aligned}$ | $\begin{aligned} & +5.71 \\ & 56.9()^{\mathrm{b}} \end{aligned}$ | ().80 | ().4+4 |
| Angle/Group /ROI/Radius | Hypothesis Error | $\begin{aligned} & 385 .+5 \\ & 1998(01.50) \end{aligned}$ | $\begin{aligned} & 2 \\ & 3+8 \end{aligned}$ | $\begin{aligned} & +8.18 \\ & 56.910^{6} \end{aligned}$ | ().85 | (0.562 |

a. MS(Horse(Group))
b. $\mathrm{MS}($ Error $)$

Table 4.3: A table of the overall ANOVA results for the ROI size analysis.
4.3.1 Main effect of radius size.


Figure 4.44: Column graph of the effect of ROI size when ROI's were in a palmar position.

ROI size did not significantly affect photodensity.

### 4.3.1.I Different angles at one level of radius

Pairwise comparison were performed to compare between angle means while holding size of ROI constant The tabulated data and actual significance values are within appendix 2 under the heading of 3.1.1.


Figure 4.45: Column graph of the effect of x -ray beam angle on photodensity of ROI's at varying radius sizes.

The significant change in photodensity between $60^{\circ}$ and $90^{\circ}$ is similar between the 3 different ROI sizes.

### 4.3.1.2 Different radius size at one level of angle.

Pairwise comparisons were performed to compare ROI size while holding x-ray beam angle constant. The tabulated data and actual significance values are within appendix 2 under the heading of 3.1.2.


Figure 4.46: Column graph of the effect of ROI size on photodensity while holding the angle at $\mathbf{6 0}$ degrees.

There was no significant change in photodensity between ROI size at an x -ray beam angle of $60^{\circ}$.


Figure 4.47: Column graph of the effect of ROI size while holding x-ray beam angle at 90 degrees.

There was no significant change in photodensity between ROI size when x-ray beam angle was 9()$^{\circ}$.

## DISCUSSION

The object of this study was to determine if radioabsorptiometry (RA) could be used to objectively assess the variation in BMD of the dorsal part of C3. When using RA. BMD is characterised in computer units, which are calculated from photodensity. The difficulties associated with this conversion are discussed. Clarif ing the effect of variation in angle on photodensity formed the basis of the first hypothesis. A discussion of these results is presented below. In attempting to confirm the hypothesis. additional information regarding ROI position and the effect of exercise on photodensity was considered. ROI size formed the basis of the second hypothesis and the results are analysed and discussed.

Radiographic assessment of C 3 is best achicved using the tangential view. The tangential view of the distal row of carpal bones may be taken by 1 of 2 radiographic methods. each of which is reviewed. as well as the difficulties in determining which view more accurately assesses photodensity. The relevance of this study and the clinical application of RA in detecting changes in C3 are contemplated. as is the accuracy of the subjective assessment of photodensit! of C3.

### 5.1 Photodensity in relation to BMD

Photodensity of bone can be accurately determined in terms of aluminium equivalents. because the atomic number and specific gravity of aluminium is similar to that of bone. Aluminium is homogeneous. pure and relatively stable. and therefore it has been used extensively in RA. ${ }^{616364}$

Although photodensity of bone mineral can be accurately measured by aluminium. conversion to bone mineral concentration is more comple. ${ }^{63}$ Additional factors that are involved are attenuation of photons by the bone and aluminium. the role of scatter and photon/film interactions. The predominant photon interactions that occur at the kilovoltage level used in this study are photoelectric. This type of interaction is dependent on atomic number and results in
total absorption of photons. A small number of interactions, likely to be less than $10 \%$ at the kilovoltage used in this study result from Compton interactions, which cause scatter, and reduction in the quality of the image. Therefore in order to accurately convert photodensity into bone mineral density the effect of these interactions must be taken into consideration. The advent of computer assisted RA has enabled these interactions to be accounted for by using a series of complex equations. ${ }^{63}$ However, in doing so an assumption is made that the x -ray beam is effectively homogeneous. which is unlikely to be true.

Within this study the effect of scatter and the absorption coefficient at the kilovoltage used could not been accounted for. It is suspected that Compton interactions were a constant between views. as these interactions are not affected by atomic number. rather by kilovoltage used. and in this experiment the same kilovoltage was used each time. Therefore the results of this study are discussed in terms of photodensity. using a scale of aluminium thickness. and not as BMD. using a scale of computer units. Because a measure of BMD is not being used. comparison to studies using other methods of non-invasive bone mincral anal sis is based on the assumption that photodensity in terms of millimetres of aluminium is directly proportional to BMD.

### 5.2 Effect of angle on photodensity

When performing peripheral skeletal radiography in humans the relationship betwcen .x-ray beam and object can be kept constant. However when imaging C3 using the tangential view of the carpus in horses. the object (C3)-beam angle is difficult to accurately replicate. especially in equine clinical practice conditions. Therefore it was necessary to establish if small variations in C3 beam angle significantly affected photodensity. Isolated distal rows of carpal bones lying flat on an x-ray cassette were used. and thus the plate-beam angle. C3-beam angle and x-ray beam angles were identical. The significance of variation in angle was determined at $90^{\circ}$. the recommended $x$-ray beam angle used in RA studies of human small bones ${ }^{636+}$. as well as at $60^{\circ}$. which is the C3-beam angle recommended in the literature for the tangential view of the distal row of carpal bones in the horse. ${ }^{\text {s }}$ ?

In this study the ROI's were initially placed in a dorsal position ( 6 mm from the dorsal edge at 9()$\left.^{\circ}\right)$. which is in the zone visualised by the tangential view. Variations in angle less than $10^{\circ}$ from $90^{\circ}$ significantly affected photodensity in these ROI's. This was supported by the significant main effect of angle and the angle/ ROI interaction. ROI's 2. 3. 4 and 5 all followed the same pattern, the exception being ROI I where no significant difference in photodensity with variation in angle was observed

Variation in angle of less than $10^{\circ}$ from $60^{\circ}$ appeared to significantly affect photodensity. This was supported by analysis of the angle/ ROI interaction. The results demonstrated that photodensity is minimally affected when C3 beam angle is varied between the angle $70^{\circ}$ and $80^{\circ}$. However. clinically this is not useful, because when the tangential view is taken at these angles superimposition of the proximal row of carpal bones prevents adequate visualisation of the dorsal aspect of the distal row of carpal bones.

The analysis of the dorsal ROI's demonstrated that as x-ray beam angle was reduced. photodensity decreased. It was postulated that as the x-ray beam angle decreased from 9()$^{\circ}$ the distance travelled through the bone increased. As the ROI's were placed in such a dorsal position. once the angle was less than $85^{\circ}$ the dorsodistal aspect of C3 was not penetrated by the x -ray beam. This effect increased as the angle continued to decrease. Thus it was proposed that if ROI's were placed in a more palmar site, a stepwise reduction of C 3 beam angle would result in a stepwise increase in photodensity as the distance the x -ray beam travelled though the bone increased. As discussed in the materials and methods. the calibrated images were reprocessed with the ROI's placed in a more palmar site. The results were statistically analysed and photodensity did increase as angle reduced. This was supported by the main effect of angle and angle/ROI comparisons.

Photodensity significantly changes when the angle is varied by more than $5^{\circ}$ from $90^{\circ}$ and less than $5^{\circ}$ from $60^{\circ}$. In both the dorsal and palmar ROI placements this is likely to be due to increased travelling distance of the radiographic beam through bone: at $10^{\circ}$ from $90^{\circ}$ the beam traverses $1.5 \%$ further and at $10^{\circ}$ from $60^{\circ}$ it traverses a further $7.8 \%$ through C3. The increase in distance travelled through the bone appears to be inversely proportional to Sin (x-ray beam angle). Therefore a small deviation from an $x$-ray beam angle of $90^{\circ}$. only slightly increases the distance travelled though the bone. However the same small deviation from an x -ray beam angle of $60^{\circ}$ results in a substantially greater distance travelled through the bone. This form of variation may explain why a change of less than $5^{\circ}$ from $60^{\circ}$ is required before photodensity significantly changes whereas a change of less than $I 0^{\circ}$ is required from $90^{\circ}$ before photodensity significantly changes.

Loading within C3 is predominately uniaxial, which results in the trabeculae developing a columnar structure with cylindrical symmetry. The columns of bone are orientated in a vertical direction. and thus the bone has a high stiffness and strength in the direction when loaded in a sagittal direction and reduced strength and stiffness if loaded in a transverse direction. ${ }^{87}$ The orientation of the columns results in a honeycomb like morphology. When the x-ray beam
traverses through the bone at $90^{\circ}$ and most likely at $85^{\circ}$ it is reasonable to suggest the x -ray beam travels through the columns, resulting in a lower photodensity. At greater beam angles, it traverses the trabecular columns obliquely and therefore passing through a greater volume of bone relative to the more vertical angles. This results in a higher photodensity: The morphology of C3 may explain why a variation of $10^{\circ}$ from 9()$^{\circ}$ results in a significant change in photodensity when the distance traversed through the bone compared to a variation of $10^{\circ}$ from 6()$^{\circ}$, is relatively small.

To the author's knowledge the effect of variation in angle on photodensity when applied to RA has not been documented. The findings of this study indicate that due care must be taken in application of object-beam angle (in this case C3-beam angle) when radiographing areas for analysis using RA. The findings also suggest that care should be taken when comparing tangential vieus of C3 (taken at a C3-beam angle of $65^{\circ}$ ) to radiographs of isolated C3's taken at 9()$^{\circ}$. Our results indicate that variation in angle of $25^{\circ}$ significantly affects photodensity. and objectively there is unlikely to be a good correlation between the 2 vicws. These results are in direct contrast to the study by Ulhom. ${ }^{+5}$ in which there was a significant relationship between the photodensity taken at a C3-beam angle of $65^{\circ}$ and those taken at 9()$^{\circ}$. The likely reason for this is that the radiographs were compared subjectively rather than quantitatively

### 5.3 Effect of ROI on photodensity

Five ROI's were chosen within the distal carpal row. ROI I and 2 were within the radial facet of C3 and ROI 3 and 4 were within the intermediate facet of C3. ROI 5 was within C 4 . The photodensity of the ROI's varied within C3. when the ROl's were positioned dorsally. Within this study. at 60$)^{\circ}$ (C3-beam angle of the tangential view) dorsal ROI placement resulted in photodensity of the abaxial aspect of the radial facet being significantly higher than the rest of C3. The photodensity of the axial aspect of the radial facet, and both aspects of the intermediate facet were not significantly different. When the radiographs were taken at a C3-beam angle of 9()$^{\circ}$ with ROI's placed dorsally. the photodensities of the radial facet and the axial aspect of the intermediate facet were not significantly different. The abaxial aspect of the intermediate facet had a significantly different photodensity to the axial aspect of the radial facet but not the other ROI's. The discrepancy of photodensity of the abaxial aspect of the radial facet between the 2 angles is thought to be due to the prominent transverse ridge that is present on the medial dorsocentral aspect of C3. When the C3-beam angle is at 6$)^{\circ}$ the amount of bone travelled through is significantly higher at the abaxial aspect of the radial facet when compared to the rest
of C3, whereas when the C3-beam angle is 9()$^{\circ}$ the x -ray beam does not travel through the bone on the dorsocentral aspect of the radial facet.

In all microradiographic and BMD studies. C3 has been assessed in a proximodorsal or lateromedial direction. and comparison with the present study can be made only with data collected at a C3-beam angle of 9()$^{\circ}$. A study assessing subchondral bone stiffness and bone density of C3 found no change in stiffness between the intermediate and radial facets in trained horses. ${ }^{31}$ This has also been found when objectively assessing the BMD of C3 using DXA. ${ }^{+4}$ In both studies there was only I area of interest in the radial facet and 1 in the intermediate facet of C3. In the study by Young ${ }^{31}$ the area of interest in the radial facet was between ROI 1 and 2. and between ROI 3 and 4 in the intermediate facet. In the study by Firth ${ }^{4}$ the area of interest in the radial facet was in a similar position to ROI 2 and in the intermediate facet it was in a similar position to ROI3. The results from the present study support those reported by Young ${ }^{31}$ and Firth ${ }^{++}$.

ROI 5 was within C4 and the mean photodensity as well as photodensities of individual horses was always within the range of photodensities present in C3. To the author's knowledge there have been no studies objectively assessing photodensity of $\mathrm{C} 4 . \mathrm{C} 4$ has been suggested as a control when subjectively assessing the photodensity of C3 from the tangential radiographic view. ${ }^{4850}$ which means that C 3 is classified as not sclerotic if the subjective photodensity and trabeculation is the same as that of C4. The objective assessment of photodensity at a C3-beam angle of $60^{\circ}$ in this study indicates that the photodensity of $C 4$ is similar to that of the axial aspect of the radial facet. is significantly less than the abaxial aspect of the radial facet. and is significantly more than the axial aspect of the intermediate facet. When C3-beam angle is 9()$^{\circ}$ the photodensity of C 4 is not significantly different from any ROI in C3 in this study. These findings suggest that radiographing C3 using the tangential view causes the abaxial radial facet to be more photodense than C 4 . perhaps resulting in false positive diagnoses of sclerosis in the radial facet.

### 5.4 Effect of exercise on photodensity

The bones used in this experiment came from horses used in an exercise study: one group was exercised in a training programme typical of that used to condition horses for racing in New Zealand. The other group remained in small yards for the duration of the study. The results indicate that exercise significantly affects the photodensity of all ROI's in the dorsal aspect of C3. In the exercised group of horses it appears that the axial aspect of the radial facet had the greatest increase in photodensity. followed by the intermediate facet and then the abavial aspect
of the radial facet. Therefore the 2 ROI's within the radial facet, and the 2 ROI's within the intermediate facet were not significantly different from each other, however the radial and intermediate facets were significantly different from each other. These results support those of Firth ${ }^{4+}$. ${ }^{88}$ who found that exercise resulted in increased BMD of C3.

Evercise significantly affected photodensity of C 4 and as a result C 4 post evercise had a photodensity not significantly different from the intermediate facet in this group of horses. As these horses did not appear to have pathological changes in their C3's no comment can be made as to whether C 4 continues to model or if it reaches a particular BMD and remodels only. This study indicates that C 4 responds to the same stresses as C 3 and models accordingly, which may place doubt on whether C 4 should be used as a radiographic control.

### 5.5 Effect of ROI size on photodensity

It was unknown if ROI size significantly would affect photodensity when .x-ray beam angles were varied. The ROI size was changed by $19 \mathrm{~mm}^{2}$. increasing from 2.5 mm to 3.5 mm radii. and this change in size did not significantly affect photodensity. The relationship between photodensity at $60^{\circ}$ and $90^{\circ}$ did not change with ROI size. To the author's knowledge, the effect of ROI size has not been examined when the angle of examination is $90^{\circ}$ or if object -beam angle is varied. These results suggest that in bones of the size and morphology of C3 with a relatively uniform photodensity. ROI size can be altered to suit the study.

### 5.6 View A Compared to View B - Which is the more accurate view?

View A and B both assess the dorsal margin of the distal row of carpal bones. However. it is likely that only the proximo-dorsal and centro-dorsal aspect of this row of carpal bones is imaged. Although the two views assess the same area of interest. the radiographic image of each differs markedly. This difference is due solely to plate angle, as x-ray beam angle. C3 beam angle and leg angle are the same. When using View B the plate-beam angle is not at $90^{\circ}$ to the x-ray beam as in View A and the geometry of image formation is disrupted, leading to distortion of the radiographic image and an inaccurate image of the distal row of carpal bone. Distortion results in loss of definition and blurring of the image and this affects subjective interpretation. ${ }^{89}$ When using View A the plate is at 9()$^{\circ}$ to the $x$-ray beam and minimal distortion of the image occurs. However the object film-focal distance is a relatively large distance when compared to View B and this results in magnification of the radiographic image that increases marginal blurring. ${ }^{90}$ Subjectively, View A appears to be less blurred than View B, although when compared to radiographs of isolated distal rows of carpal bones taken at the same C3 beam angle, both views are obviously blurred.

Although both View A and B are used to assess the dorsal aspect of C3, the radiographic images produced are different. In order to determine if one view more accurately assesses photodensity the exact same ROI's must be identified. Once the radiographs were digitised the images were manipulated to appear as if they were taken at the same plate-beam angle and object-film distance. The distortion of View B and the magnification of View A were thus corrected for in the digitised image. Even when the images were manipulated identical placement of ROI's was difficult to achieve and any small variation in placement resulted in error. The reason for this was that in the manipulated images the dorsal aspect of C 3 had a linear increase in photodensit! rather than the relatively uniform density quantified in the isolated C3's. The ROI size used had a radius of $I \mathrm{~mm}$. which is significantly smaller than those used in the rest of the study. Such a small size was required in order to measure the photodensity of the area of interest without including the superimposition of either MCIII or the proximal row of carpal bones. The small size of the ROI's may have resulted in a higher error associated with ROI placement than if larger ROI's had been used. In determining which view more accurately assessed photodensity. an additional proven accurate method of non-invasive bone mineral anal sis was required to establish the true BMD of the area of C3 visualised in each tangential view. This was not possible within the present study. Considering all the above-mentioned problems it was not possible to determine which view more accurately assesses photodensity:

### 5.7 Relevance of this study

This study has provided important information on the effect of variation of angle when assessing the photodensity of a bone at an object-beam angle of 9$)^{\circ}$. In many articles discussing the technique of RA the angle at which the radiograph was taken was not specified but assumed by this author to be 9()$^{\circ} .^{6-6 t}$ As this study indicates that variation in x-ray beam angle of between $5^{\circ}$ and $10^{\circ}$ significantly affects photodensity it is recommended to take duc care in determining x-ray beam angle. Difficulties may arise when different machines are used. and the inclusion of a cube in the radiograph to determine plate-beam angle may be uscful to ensure x ray beam angles are similar between operators and machines.

The clinical usefulness of this technique appears to be limited because it is imperative to ensure that C3-beam angle can be replicated within $5^{\circ}$ every time the tangential view is taken. which involves ensuring that x -ray beam angle and leg angle can be accurately replicated each time. Xray beam angle is challenging to replicate in a clinical situation when taking the tangential view. However, leg angle. which directly affects C3-beam angle, is even more difficult to accurately replicate in a clinical situation. and natural variation of C3 position within the carpus between horses may result in a differing C3-beam angle despite leg angle remaining constant. This study
indicates that because small variation in C3-beam angle significantly affects photodensity and C3-beam angle is difficult to reproduce accurately, RA may not be clinically applicable in assessment of BMD of C3 under current practical constraints involved in taking radiographs in the live animal.

### 5.8 Sources of error

A number of accuracy studies have been performed on RA in humans and the technique has been determined to be accurate. ${ }^{62}{ }^{63}$ In this study accuracy validation has not been performed because identification of ROI's with an alternate method of non-invasive bone mineral analysis was not possible. However the study has assumed a directly proportional relationship between photodensity and BMD and the results are comparable to other BMD studics performed on C3.

### 5.9 Critique of the subjective assessment of photodensity of C3

A complete radiographic series of the carpus includes the tangential view. ${ }^{4850}$ which is useful in detecting the presence of fractures and possibly the presence of lucent areas other than vascular channels. ${ }^{91}$ In the past it has been thought that the tangential view was useful for the detection of pathological changes in BMD of C3 likely to precede fracture. ${ }^{+8}$ This evaluation has been purely subjective and a number of studies have demonstrated that the subjective assessment of radiographs is relatively inaccurate method. ${ }^{\text {t }}$ but may provide a broad guide to BMD assessment. ${ }^{55}$ One study has specifically considered the accuracy of assessment of bone density using the tangential vicw and found it to be an accurate method to detect radiographic sclerosis. ${ }^{+5}$ The visual assessment of C3 sclerosis in that study was based on a subjective grading ș̦stem modified from O'Brien. ${ }^{50}$ Using a uniform point count procedure to determine bone density. the authors concluded that sclerotic C3's could be differentiated from nonsclerotic C3's. However. differentiation between mild. moderate and severe sclerosis was problematical. and it was not stated if the little variation in bone density measurements present was statistically significant. The study also found that subjectively there was good agreement between the tangential view (C3-beam angle $60^{\circ}$ ) and the proximodistal view (C3-bcam angle 9()$\left.^{\circ}\right)$. in direct contrast to the present study in which photodensities at a C3 beam angle of $60^{\circ}$ and at 9()$^{\circ}$ were significantly different. However it is possible that subjectively this difference in photodensity may not be detectable.

The aim of this study was to apply the technique of RA to the tangential view of C3. As small variation in angle significantly affects photodensity and C3-beam angle can not be accurately reproduced between horses, or on repeated radiographs of the same horse (under practice or even hospital conditions), the accurate objective assessment of photodensity of C3 is thought
not to be clinically applicable at this time. Given that objective assessment of photodensity is considered to be a more accurate assessment of BMD than subjective assessment, ${ }^{63.61}$ the indirect conclusion of this study is that the current method of subjective evaluation of photodensity of C3 using the tangential view is relatively inaccurate. Although not apparent when differentiating between radiographically sclerotic and non-sclerotic C3's. the inaccuracies of subjective assessment become obvious when distinguishing between the varying grades of sclerosis. This is an important point as some degrec of radiographic sclerosis is considered physiological and it is currently unknown when sclerosis becomes pathological. A recent retrospective study evaluating sclerosis of C 3 supports this, as no significant relationship between C3 sclerosis. lameness or prognosis was found. ${ }^{91}$

### 5.10 Further research

Although this technique docs not appear to be clinically applicable for assessment of C3. it may have other applications when object-beam angle can be accurately reproduced. In order for this to occur. accuracy studies comparing the technique to another method of non-invasive bone mineral analysis would be important.

### 5.11 Conclusion

RA does not appear to be clinically applicable in the determination of photodensity of C3 as the first null hypothesis: "photodensity is not affected by small variations in C3-beam angle" was disproved. This result also has connotations for the use of the RA in humans. This study substantiates work by other authors regarding regional differences in BMD of $C 3$ as well as the effect of evercise on C3. and it is believed to be the first study to objectively assess C4. The second hypothesis of the study. "ROI size does not significantly affect mean photodensity over a $30^{\circ}$ variation in x-ray beam angle (from $90^{\circ}$ to $60^{\circ}$ )", was sustained.

The tangential view of C3 can be taken by 1 of 2 methods. each of which has disadvantages. At this time, it remains unclear which view more accurately assesses photodensity of C3. Because of the effect of x-ray beam angle on photodensity. objective assessment of photodensity is likely to be inaccurate in the clinical situation. Therefore current methods of subjective assessment ${ }^{\text {j" }}$ are also likely to be inaccurate and should be used cautiously.

## REFERENCE LIST

1. L.Jeffcott. P.Rossdale. J.Freestone. C. J.Frank. P.F.Towers-Clark. An assessment of wastage in Thoroughbred racing from conception to 4 years of age. Equine Veterinary Journal 1982:14:185-98.
2. P. Rossdale. R.Hopes. N.Winfield Digby. K. Offord. Epidemiological study of wastage among racehorses 1982 and 1983. Veterinary Record 1985:1 16:66-9.
3. A.Lindner, P.von Wittke. A.Dingerkus. M. Temme. H.Sommer. Causes and rates of training failure in Thoroughbreds. Equine Athlete 1992:5:3-7.
4. H.O.Mohammed. T.Hill. J.Lowe Risk factors associated with injuries in Thoroughbred horses. Equine Veterinary Journal 1991:23:445-8.
5. J.H.Wilson. S.B.Howe. R.C.Jensen. R.A.Robinson. Injuries sustained during racing at racetracks in the U.S. in 1992. Proceedings of the American Association of LEquine Practitioners. 1993: 39:267-268
6. Y.Mizuno. Fractures of the carpus in racing Thoroughbreds of the Japan racing association: prevalence. location and current modes of surgical therapy: Journal of Equine Vetereinary Science 1996:16:25-31.
7. R.D.Park. J.P.Morgan. T.O'Brien. Chip fractures in the carpus of the horse: a radiographic study of their incidence and location. Journal of American V'eterinary Medical Association 1970:15:1305-1311.
8. C.W.Mcllwraith. Fractures of the carpus. In A.J.Nixon, eds. L:quine Fracture Repair. W.B.Saunders. United States of America. 1996:208-21.
9. J.M.Lucas. M.W.Ross. D.W.Richardson. Post operative performance of racing Standardbreds treated arthroscopically for carpal chip fractures: 176 cases (1986-1993). Equine Veterinary Journal 1999:31:48-52.
10. S.E.Palmer. Prevalence of carpal fractures in Thoroughbred and Standardbred racehorses. Journal of American Veterinary Association 1986:188:1171-3.
11. R.K Scluneider. L.R.Bramlage. A.A.Gabel. L.M.Barone. B.M.Kantroitz. Incidence. location and classification of 371 third carpal bone fractures in 313 horses. Equine Veterinary Journal Supplement 1988:Supplement 6:33-42.
12. P.R.Stephens, D.W.Richardson, P.A.Spencer. Slab fractures of the third carpal bone in Standardbreds and Thoroughbreds: 155 cases (1977-1984). Journal of A merican Veterinary Medical Association 1988:193:353-358.
13. G.S.Martin. P.F.Haynes, J.R.McClure. Effect of third carpal slab fracture and repair on racing performance in Thoroughbred horses:31 cases (1977-1984). Journal of American Veterinary Medical Association 1988:193:107-110.
14. C.W.Mcllwratih. J.V.Yovich. G.S.Martin. Arthroscopic surgery for the treatment of osteochondral chip fractures in the equine carpus. Journal of American Veterinary Medical Association 1987:19:531-40.
15. N.J.Kannegieter. N. Ryan. Racing performance of Thoroughbred horses after arthroscopic surgery of the carpus. Australian Veterinary Journal 1991:68:258-60.
16. D.W.Richardson. Technique for the arthroscopic repair of third carpal bone slab fractures in the horse. Journal of American Veterinary Medical Association 1986:188:288-91.
17. R.M.Moore. R.K.Schneider. Arthroscopic findings in the carpal joints of lame horses without radiographically visible abnormalities: 41 cases (1986-1991). Journal of American Veterinary Association 1995:206:1741-6.
18. M.W.Ross. D.W.Richardson. G.A.Berzoa. Subchondral lucency of the third carpal bone in Standardbred racehorses. Journal of American Veterinary Medical Association 1989:195:789-794.
19. R.J.Todhunter. Anatomy and physiology of synovial joints. In C.W.Mcllwraith. G.W.Trotter. eds. Joint Disease in the Horse. W.B.Saunders. Philadelphia. 1996:9-19.
20. R.R.Pool. Pathologic manifestations of joint disease in the athletic horse In C.W.Mcllwraith, G.W.Trotter. eds. Joint Disease in the Horse. W.B.Saunders. Phildelphia. 1996:91-6.
21. J.L.Palmer. A.L.Bertone. Joint biomechanics in the pathogenesis of traumatic arthritis. In C.W.Mcllwraith and G.W.Trotter. eds. Joint Disease in the Horse. W. B. Saunders. Philidelphia. 1996:110-1.
22. C.W.Mcllwraith. General pathobiology of the joint and response to injury. In C.W.McIlwraith. G.W.Trotter. eds. Joint disease in the Horse. W.B.Saunders. Philadelphia. 1996:40-70.
23. H.R.Kerr. B.Warbuston. Surface rheological properties of hyaluronic acid solutions. Biorheologr 1985:22:133-44.
24. E.L.Radin, H.G.Parker. J.W.Pugh. R.S.Steinberg, I.L.Paul. R.M.Rose. Response of joints to impact loading III: relationship between trabecular microfractures and cartilage degeneration. Journal of Biomechanics 1973:6:51-7.
25. D.B.Burr. M.B.Schaflet. The involvement of subchondral mineralized tissues in osteoarthrosis: Quantitative microscopic evidence. Microscopic Research and Technique 1997:37:343-57.
26. P.G.Bullough. The geometry of diarthrodial joints. its physiological maintenance and the possible significance of age-related changes in the geometry to load distribution and the development of osteoarthritis. Clinical Orthopedic Related Reseach 1981:156:61-6.
27. T.M.Keaveny, W.C.Hayes. Mechanical properties of cortical and trabecular bone. In B.K.Hall, eds. Bone Grouth - B. CRC Press Inc. United States of America, 1993:285-344.
28. D.Resnick, S.C.Mangolagas. G.Niwayama, M.D.Fallon. Histogenesis. anatomy and physiology of bone. In D.Resnick. eds. Diagnosis of Bone and Joint Disorders. W.B.Saunders. Philadelphia, 1995:617-24.
29. M.C.Michel. P.K.Zy.sset, W.C.Haves. Fatigue behaviour of trabecular bone. Transactions of the ()rthopaedic Research Society. 1991;16:156 referred to by T.M.Keaveny, W.C.Hayes. Mechanical properties of cortical and trabecular bone. In B.Hall Bone-Bone Growth-B. CRC Press, London. 1993:7:335.
30. D.R.Carter. D.M.Spengler. Mechanical properties and composition of cortical bone. Clinical ()rthopedics 1978:135:192-217.
31. D.R.Young. D.W.Richardson. M.D.Markel. D.M.Nunamaker. Mechanical and morphometric analy sis of the third carpal bone in Thoroughbreds. American Journal of Veterinary Research 1991:52:402-409.
32. R.Getty. Equine osteology: In R Getty: eds. Sisson and Grossman's The anatomy of the Domestic Animals. W.B.Saunders. London. 1975:286-9.
33. E.C.Firth. W.Hartman. An in vitro study on joint fitting and cartilage thickness in the radiocarpal joint of foals. Research in Veterinary Science 1983:34:320-6.
34. P.Colahan. T.A.Turner. P.Poulas. G.Piotrowski. Mechanical function and sources of injury in the fetlock and carpus Proceedings of the American Association of Equine Practitioners. 1988:33:689-699.
35. L.R.Bramlage. Surgical diseases of the carpus. Veterinary (linics ()f North America (Large Animal Practice) 1983:5:261-74.
36. E.C.Firth. N.Deanc. K. Gibson et al. Current studies in carpal disease and function in the horse. Nutrition and lameness in horses. New Zealand: Veterinary Continuing Education. Massey University. 1991:135:81-9.
37. L.R. Bramlage. R.K.Sclncider. A.A. Gabel. A clinical perspective on lameness originating in the carpus. l:quine ''eterinary' Journal Supplement 1988: 6:12-18.
38. S. Sisson. Equine syndesmology. In R.Getty. eds. Sisson and Grossman's The Anatomy of the Domestic Animals. W.B.Saunders. London. 1975-355-7.
39. R.C.Whitton. T.H.McCarthy. R.J.Rose. The intercarpal ligaments of the equine midcarpal joint. Part 1: the anatomy of the palmar and the dorsomedial intercarpal ligaments of the midcarpal joint. Veterinary' Sirgery 1997:26:359-66.
40. N.J.Deane. A.S.Davies. The function of the equine carpal joint: A review. New Zealand Veterinary Journal 1995:43:45-7.
41. L.A.Setton. W.Zhu. V.C.Mow. The biphasic poro-viscoelastic behaviour of articular cartilage: role of the surface zone in governing the compressive behaviour. Jorunal of Biomechanics 1993:26:581-92.
42. A.Young. T.R. O'Brien. R.R.Pool. Exercise-related sclerosis in the third carpal bone of the racing Thoroughbred. Proceedings of the American Association of Equine Practitioners 1989:34:339-346.
43. J.L.Palmer, A.L.Bertone, A.S.Litsky: Contact area and pressure distribution changes of the equine third carpal bone during loading. Equine Veterinary Journal 1994:26:197-202.
44. E.C.Firth. J.Delahunt, J.W.Wichtel. H.L.Birch. A.E.Goodship. Galloping exercise induces regional changes in bone density within the third and radial carpal bones of Thoroughbred horses. Equine Veterinary Journal 1999:31:111-115.
45. H.Uhlhorn. S.Ekman. A.Haglund. J.Carlsten. The accuracy of the dorsoproximaldorsodistal projection in assessing third carpal bone sclerosis in Standardbred trotters. Veterinary Radiology and Ultrasound 1998:39:412-417.
46. M.J.Verner. R.C.Thompson. J.L.Lewis, T.R.Oegema. Subchondral damage after acute transarticular loading: An in vitro model of joint injury. Journal of Orthopedic Research 1992:10:759-65.
47. H.Silyn-Roberts. N.D.Broom. Fracture behaviour of cartilage-on-bone in response to repeated impact loading. Connective Tissue Research 1990:24:143-56.
48. C.E.DeHaan. T.R.O'Brien. P.D.Koblik. A radiographic investigation of third carpal bone injury in 42 racing Thoroughbreds. Veterinary Radiology 1987:28:88-92.
49. D.M.Wong. D.J.Satoris. Noninvasive methods for the assessment of bone density: architecture. and biomechanical properties: fundamental concepts. In D.J.Sartoris. eds. ()steoporosis Diagnosis and Treatment. Marcel Dekker Inc. USA. 1996:201-33.
50. T.R.O'Brien. C.E.DeHaan. R.Arthur. Third carpal bone lesions of the racing Thoroughbred. Proceedings of the American Association of Equine Practitioners. 1986:31:515-24.
51. J.R.Field. J.F Zaruby. Repair of a fracture of the fourth carpal bone in a vearling Standardbred horse. Candian Veterinary Journal 1994:35:371-2.
52. J.A.Auer. J.P.Watkins. N.A.White. T.S.Taylor. Slab fractures of the fourth and intermediate carpal bones in five horses. Journal of American Veterinary Association 1986:188:595-601.
53. E.Lachmann. M.Whelan. Roentgen diagnosis of osteoporosis and its limitations. Radiology 1936:26:165-77.
54. V.Finsen. S.Andra. Accuracy of visually estimated bone mineralization in routine radiographs of the lower extremity: Skeletal Radiology 1988:17:270-5.
55. M.J.Garton. E.M.Robertson, F.J.Gilbert. L. Gomersall. D.M.Reid. Can radiologists detect osteopenia on plain radiographs? Clinical Radiology 1994:49:118-22.
56. M Jergas. H.K.Genant. Quantitative bone mineral analysis. In D.Resnick. eds. Diagnosis of Bone and Joint Disorders. W.B.Saunders. Philadelphia, 1995:1854-85.
57. R.B.Mazess. Photon Absortiometry: In S.H.Cohn. eds. Non-invasive Measurements of Bone Mass and Their Clinical Application. CRC Press. Florida. 1981:52-82.
58. S.Grampp, M.Jergas. P.Lang, H.K.Genant. C.C.Gluer. Quantitative assessment of osteoporosis: current and future status. In D.J.Sartoris, eds. Osteoporosis Diagnosis and Treatment. Marcel Dekker Inc. U.S.A. 1996:233-65.
59. H.E.Meema, S.Meema. Radiogrammetry: In S.H.Cohn. eds. Non-invasive Measurements of Bone Mass and Their Clinical Application. CRC Press Inc, United States, 1981:5-51.
60. T.H.Hughes, J. S.Yu, D.J.Sartoris. Imaging of osteoporosis. Journal of South Orthopeadic Association 1993:2:173-84.
61. A.J.Yates, P.D.Ross, R.S.Epstein. Radiographic absorptiometry in the diagnosis of osteoporosis. The American Journal of Medicine 1995:98:41-7.
62. S.Yang. S.Hagiwara. K.Engelke etal. Radiographic absorptiometry for bone mineral measurement of the phalanges: precision and accuracy study Radiology 1994:192:857-9.
63. C.Colbert. R.S.Bachtell. Radiographic absorptiometry (photodensitometry). In S.H.Cohn. eds. Non-invasive Measurements of Bone Mass and Their Clinical Application. CRC Press Inc. United States. 1981:51-85.
64. F.Cosman. B.Herrington. S.Himmelstein. R.Lindsay. Radiographic absorptiometry: a simple method for determination of bone mass. Osteoporosis International 1991:2:34-8
65. E.Scotti, L.B.Jeffcott. The hock as a potential site for non-invasive bone measurement. Equine Veterinary Journal Supplement 1988:Supplement 6:93-8.
66. L. Delaquerriere-Richardson. C.Anderson. U.M.Jorch. M.Cook. Radiographic morphometry and radiographic photodensitometry of the femur in the beagle at 13 and 21 months. American Journal of Veterinary Reseach 1982:43:2255-8.
67. J.A.Sorenson. J.R.Cameron. A reliable in vivo measurement of bone mineral content. Journal of Bone and Joint Surgery 1967:49A:481-97.
68. H.W.Walmer. I. Fogelham. The evaluation of osteoporosis: Dual energy X-ray absorptiometry in clinical practice. Cambridge U.K.: Martin Dunitz LTD. 1994.
69. R.B.Mazess. H.M.Waluner. Nuclear medicine and densitometry: In B.L.Riggs. L.J.Melton III. eds. ()steoporosis Etiology: Diagnosis and Management. Raven Press. U.S.A. 1988:251-82.

7(). M.A.Greenfield. J.D.Cravern. A.Huddleston. D.Wishko. M.L.Kehrer. R.Stern. Measurement of the velocity of ultrasound in human cortical bone in vivo. Radiology 1981:138:7()1-10.
71. S.H.W.Buckingham. L.B.Jeffcott. Osteopenic effects of forelimb immobilisation in horses. Veterinary Record 1991:128:37()-3.
72. L.B.Jeffcott. R.N.McCartney. V.C.Speirs. Single photon absorptiometry for the measurement of bone mineral content in horses. The Veterinary Record 1986:118:4995() 5.
73. L.B.Jeffcott. Photon absorptiometry in the assessment of bone quality: a pilot study: Proceedings of the Annual Convention of American Association of Equine Practitioners. 1986:31:227-4().
74. R.N.McCarthỵ, L.B.Jeffcott. Ultrasonic transmission velocity and single photon absorptiometric measurement of metacarpal bone strength: An in vitro study in the horse. Equine Veterinary Journal Supplement 1988:Supplement 6:8()-87.
75. D.J.Sartoris, D.Resnick. Current and innovative methods for noninvasive bone densitometry: Radiologic Clinics of North America 1990:28:257-78.
76. L.B.Jeffcott. S.H.W.Buckingham. R.N.McCarthy. J.C.Cleeland. E.Scotti. Non-invasive measurement of bone: A review of clinical and research applications in the horse. Equine Veterinary' Journal Supplement 1988:Supplement 6:71-9.
77. J.T.Hathcock. R.L.Stickle. Principles and concepts of computed tomography. Veterinary Clinics (Of North America (Small Animal Practice) 1993:23:399-415.
78. M.Andre. D.Resnick. Computed tomography. In D.Resnick. eds. Diagnosis of Bonc and Joint Disorders. W. B. Saunders. Philadelphia, 1995:118-56.
79. M.D.Markel. R.L. Morin. M.A.Wikenheiser. R.A.Robb. SE.Y.S.Chao. Multiplanar quantitative computed tomography for bone mineral anal! sis in dogs. American Journal of Veterinary Research 1991:52:1479-83.
80. D.T.Baran. K.G.Faulkner. H.K.Genant. P.D.Miller. R.Pacifici. Diagnosis and management of osteoporosis: guidelines for the utilization of bone densitometry. Calcified Tissue International 1997:61:433-40.
81. R.N.McCarthy. L.B.Jeffcott. Monitoring the effects of treadmill exercise on bone by noninvasive means during a progressive fitness programme. Equine Veterinary Journal Supplement 1988:Supplement 6:88-91.
82. A.Mendenhall. H.D.Cantwell. Equine radiographic procedures. Lea and Febiger. Philadelphia. 1988: 89.
83. D.G.Bailey. R.M.Hodgson. VIPS- a digital image processing algorithm development environment. Image and Vision Computing 1988:6:176-84.
84. D.G.Bailey. Pixel calibration techniques. Proceedings of the New Zealand Image and Vision Computing '95 Workshop. Lincon: 1995: 37-42.
85. J.L.Fleiss. The Design and Anall:sis of Lixperiments. John Wiley and Sons. New York. 1986.
86. P.E.Shrout. J.L.Fleiss. Intra-class correlations: Uses in assessing rater reliability. Psychological Bulletin 1979:86:420-8.
87. L.J.Gibson. The mechanical behaviour of cancellous bone. Journal of Biomechanics 1985:18:317-28.
88. E.C.Firth. P.R.Van Weeren. D.U.Pfeiffer. J.Delahunt. A.Barneveld. Effect of age. exercise and growth rate on bone mineral density (BMD) in third carpal bone and distal radius of Dutch Warmblood foals with osteochondrosis. Equine V'eterinary' Journal Supplement 1999:Supplement 31:74-78.
89. P. Sprawls Jr. The Physical Principles of Diagnostic Radiologu: University Park Press, Lonndon. 1977:196.
90. C.A.Jacobi. D.Q.Paris. Textbook of Radiologic Technologv. C.V.Mosby Company. St Louis.1972:99.
91. H.Uhlhorn, J.Carlsten. Retrospective study of subchondral sclerosis and lucency in the third carpal bone of Standardbred trotters. Equine Veterinary Journal 1999:31:500-5.

## APPENDIX 1

Dorsal data

| HORSE | ANGLE | GROUP | ROI | MEAN <br> ( 0.1 mm <br> Aluminium) |
| :---: | :---: | :---: | :---: | :---: |
| 25 | 90 | () | 1 | 129.4186 |
| 31 | 90 | () | 1 | 118.8062 |
| +1 | 90 | () | 1 | 126.6673 |
| 42 | 90 | () | 1 | 117.5052 |
| 58 | 90 | () | 1 | 122.3113 |
| 59 | 90 | () | 1 | 130.833 |
| 99 | 90 | 0 | 1 | 125.2268 |
| 25 | 90 | () | 2 | 120.6763 |
| 31 | 90 | () | 2 | $111.1+23$ |
| +1 | 90 | () | 2 | 130.4807 |
| +2 | 90 | () | 2 | 115.9835 |
| 58 | 90 | () | 2 | 114.0186 |
| 59 | 90 | () | 2 | 120.2021 |
| 99 | 90 | () | 2 | $127.0(021$ |
| 25 | 90 | () | 3 | 120.699 |
| 31 | 90 | () | 3 | 108.4577 |
| +1 | 90 | 0 | 3 | 129.596 .3 |
| +2 | 90 | () | 3 | $108.3+23$ |
| 58 | 90 | () | 3 | 113.8454 |
| 59 | 90 | ${ }^{(1)}$ | 3 | 117.3814 |
| 99 | 90 | () | 3 | 119.1155 |
| 25 | 90 | () | $+$ | 117.8 |
| 31 | 90 | () | $+$ | 111.6557 |
| +1 | 90 | () | $+$ | 126.4057 |
| +2 | 90 | () | $+$ | 112.1608 |
| 58 | 90 | () | $+$ | 113.3485 |
| 59 | 90 | () | $+$ | 115.167 |
| 99 | 90 | () | $t$ | 11+.2227 |
| 25 | 90 | () | 5 | 123.1608 |
| 31 | 90 | () | 5 | 117.2639 |
| 4 | 90 | () | 5 | 135.1826 |
| $+2$ | 9() | () | 5 | 130.4371 |
| 58 | 90 | () | 5 | 117.6021 |
| 59 | 90 | () | 5 | 133.7155 |
| 99 | 90 | () | 5 | 128.934 |
| 13 | 90 | 1 | 1 | $13+8515$ |
| $1+$ | 90 | 1 | 1 | 132.8062 |
| 37 | 90 | 1 | 1 | $1+3.9938$ |
| 50 | 90 | 1 | 1 | 125.1134 |
| 55 | 90 | 1 | 1 | $138.2+7$ t |
| 57 | 90 | 1 | 1 | $1+5.0557$ |
| 60 | 90 | 1 | 1 | 130.9794 |
| 13 | 90 | 1 | 2 | 156.8124 |
| 14 | 90 | 1 | 2 | 1+4.901 |
| 37 | 90 | 1 | 2 | 152.3959 |
| 50 | 90 | 1 | 2 | 131.9835 |


| HORSE | ANGLE | GROUP | ROI | MEAN <br> ( 0.1 mm <br> Aluminium) |
| :---: | :---: | :---: | :---: | :---: |
| 55 | 90 | 1 | 2 | $1+2.7975$ |
| 57 | 90 | 1 | 2 | 148.9381 |
| 60 | 90 | 1 | 2 | 130.8392 |
| 13 | 90 | 1 | 3 | $1+2.6557$ |
| 14 | 90 | 1 | 3 | $1+0.2577$ |
| 37 | 90 | 1 | 3 | 126.5835 |
| 50 | 90 | 1 | 3 | 123.965 |
| 55 | 90 | 1 | 3 | $13+.3272$ |
| 57 | 90 | 1 | 3 | 159.5711 |
| 60 | 90 | 1 | 3 | 120.00) +1 |
| 13 | 90 | 1 | $+$ | 1+3.367 |
| 14 | 90 | 1 | $t$ | 134.033 |
| 37 | 90 | 1 | $+$ | 107.967 |
| 50 | 90 | 1 | $+$ | 135.0392 |
| 55 | 90 | 1 | $+$ | 139.0798 |
| 57 | 90 | 1 | $+$ | $1+0.7773$ |
| 60 | 90 | 1 | $+$ | 116.876 .3 |
| 13 | 90 | 1 | 5 | $128.6+33$ |
| 14 | 90 | 1 | 5 | 149.9959 |
| 37 | 90 | 1 | 5 | 120.4577 |
| 50 | 90 | 1 | 5 | 136.9175 |
| 55 | 90 | 1 | 5 | 122.5031 |
| 57 | 90 | 1 | 5 | $132.07+2$ |
| 60 | 90 | 1 | 5 | 122.6 |
| 25 | 85 | () | 1 | 131.534 |
| 31 | 85 | () | 1 | 116.833 |
| +1 | 85 | () | 1 | 121.9856 |
| +2 | 85 | () | 1 | 117.2165 |
| 58 | 85 | () | 1 | 123.3361 |
| 59 | 85 | () | 1 | 128.8619 |
| 99 | 85 | () | 1 | 127.7876 |
| 25 | 85 | () | 2 | 120.3691 |
| 31 | 85 | 0 | 2 | $109.07+2$ |
| +1 | 85 | () | 2 | 127.2763 |
| +2 | 85 | 0 | 2 | $11+.4021$ |
| 58 | 85 | 0 | 2 | 115.1876 |
| 59 | 85 | () | 2 | 111.2928 |
| 99 | 85 | () | 2 | 127.2124 |
| 25 | 85 | () | 3 | 116.099 |
| 31 | 85 | () | 3 | 107.1814 |
| $+1$ | 85 | () | 3 | 126.6515 |
| +2 | 85 | () | 3 | 106.8124 |
| 58 | 85 | () | 3 | 115.2598 |
| 59 | 85 | () | 3 | 112.9052 |
| 99 | 85 | () | 3 | 121.5897 |
| 25 | 85 | () | 4 | 110.4186 |


| HORSE | ANGLE | GROUP | ROI | MEAN <br> ( 0.1 mm <br> Aluminium) |
| :---: | :---: | :---: | :---: | :---: |
| 31 | 85 | 0 | $+$ | 110.3629 |
| $+1$ | 85 | () | $+$ | 121.8021 |
| +2 | 85 | 0 | $+$ | 110.365 |
| 58 | 85 | 0 | + | 115.2309 |
| 59 | 85 | () | $t$ | 108.5897 |
| 99 | 85 | () | $+$ | $11+.7835$ |
| 25 | 85 | () | 5 | 119.8144 |
| 31 | 85 | () | 5 | 116.0825 |
| 11 | 85 | () | 5 | 128.6186 |
| +2 | 85 | () | 5 | 123.1608 |
| 58 | 85 | () | - | 118.899 |
| 59 | 85 | () | 5 | 127.3773 |
| 99 | 85 | () | 5 | 128.5134 |
| 13 | 85 | 1 | 1 | 133.2103 |
| 14 | 85 | 1 | 1 | 133.4783 |
| 37 | 85 | 1 | 1 | 143.7814 |
| 50 | 85 | 1 | 1 | 121.7072 |
| 55 | 85 | 1 | 1 | 138.3052 |
| 57 | 85 | 1 | 1 | $1+5.49+8$ |
| 60 | 85 | 1 | 1 | 132.3629 |
| 13 | 85 | 1 | 2 | 151.8722 |
| $1+$ | 85 | 1 | 2 | $1+2.52 .37$ |
| 37 | 85 | 1 | 2 | 152.9959 |
| 50 | 85 | 1 | 2 | 128.965 |
| 55 | 85 | 1 | 2 | 1+1.932 |
| 57 | 85 | 1 | 2 | $1+5.9835$ |
| 60 | 85 | 1 | 2 | 128.9732 |
| 13 | 85 | 1 | 3 | 139.6577 |
| 14 | 85 | 1 | 3 | 137.4.31 |
| 37 | 85 | 1 | 3 | 127.7093 |
| 50 | 85 | 1 | 3 | 122.1+23 |
| 55 | 85 | 1 | 3 | 135.0763 |
| 57 | 85 | 1 | 3 | 160.4516 |
| 60 | 85 | 1 | 3 | 119.7526 |
| 13 | 85 | 1 | $+$ | 139.0577 |
| 14 | 85 | 1 | $+$ | 130.0784 |
| 37 | 85 | 1 | $+$ | 108.9258 |
| 50 | 85 | 1 | 4 | 129.4598 |
| 55 | 85 | 1 | + | 138.9753 |
| 57 | 85 | 1 | $+$ | 140.93t |
| 60 | 85 | 1 | $t$ | 114.6227 |
| 13 | 85 | 1 | 5 | 125.0763 |
| 14 | 85 | 1 | 5 | 148.3959 |
| 37 | 85 | 1 | 5 | 118.3979 |
| 50 | 85 | 1 | 5 | 1 1.32 .4907 |
| 55 | 85 | 1 | 5 | $122.8+33$ |
| 57 | 85 | 1 | 5 | 129.0928 |
| 60 | 85 | 1 | 5 | 121.0309 |
| 25 | 80 | () | 1 | 125.4928 |


| HORSE | ANGLE | GROUP | ROI | MEAN <br> ( 0.1 mm <br> Aluminium) |
| :---: | :---: | :---: | :---: | :---: |
| 31 | 80 | () | 1 | $110.82+7$ |
| +1 | 80 | () | 1 | $11+.3753$ |
| +2 | 80 | () | 1 | 113.0062 |
| 58 | 80 | () | 1 | 116.6124 |
| 59 | 80 | () | 1 | 123.0598 |
| 99 | 80 | () | 1 | 118.5299 |
| 25 | 80 | () | 2 | 112.701 |
| 31 | 80 | () | 2 | 101.7505 |
| +1 | 80 | () | 2 | 120.3629 |
| +2 | 80 | () | 2 | $105.8+33$ |
| 58 | 80 | () | 2 | 107.3258 |
| 59 | 80 | () | 2 | 100.301 |
| 99 | 80 | () | 2 | $115.62+7$ |
| 25 | 80 | () | 3 | 108.2124 |
| 31 | 80 | () | 3 | 99.2701 |
| +1 | 80 | () | 3 | 120.1381 |
| +2 | 80 | () | 3 | 99.7629 |
| 58 | 80 | () | 3 | 107.9691 |
| 59 | 80 | () | 3 | 105.1381 |
| 99 | 80 | () | 3 | 112.0784 |
| 25 | 80 | () | $+$ | 105.7361 |
| 31 | 80 | () | $+$ | 104.2619 |
| 4 | 80 | () | $+$ | 113.5835 |
| +2 | 80 | () | $+$ | 101.666 |
| 58 | 80 | () | $+$ | $105.979+$ |
| 59 | 80 | () | $t$ | 100.3113 |
| 99 | 80 | () | $+$ | $109.0+33$ |
| 25 | 80 | () | 5 | 112.33t |
| 31 | 80 | () | 5 | 109.9732 |
| $+1$ | 80 | () | 5 | 118.1938 |
| +2 | 80 | () | 5 | 113.2722 |
| 58 | 80 | () | 5 | 111.8227 |
| 59 | 80 | () | 5 | 119.7134 |
| 99 | 80 | () | 5 | $121.82+7$ |
| 13 | 80 | 1 | 1 | 128.3093 |
| 14 | 80 | 1 | 1 | 129.9381 |
| 37 | 80 | 1 | 1 | 139.8309 |
| 50 | 80 | 1 | 1 | 115.2021 |
| 55 | 80 | 1 | 1 | 131.4+12 |
| 57 | 80 | 1 | 1 | 133.1629 |
| 60 | 80 | 1 | 1 | 127.8289 |
| 13 | 80 | 1 | 2 | 139.6516 |
| 14 | 80 | 1 | 2 | 132.3484 |
| 37 | 80 | 1 | 2 | $1+4.4907$ |
| 50 | 80 | 1 | 2 | $12+.3155$ |
| 55 | 80 | 1 | 2 | 132.9608 |
| 57 | 80 | 1 | 2 | 129.7072 |
| 60 | 80 |  | 2 | 119.0433 |
| 13 | 80 | 1 | 3 | 130.(0784 |


| IてZ8 +() I | $\bar{\sim}$ | （） 0 | OL | $\bigcirc$ |
| :---: | :---: | :---: | :---: | :---: |
| てと0）Iで | I | （） | OL | 66 |
| †－80てを近 | I | （） | OL | 65 |
| LLETIてI | I | （） | OL | 85 |
| S0991 I | I | （） | （0） | て† |
| ＋9666 61 | I | （） | OL | It |
| 2ZLLSII | I | （） | OL | IC |
| て0こぐ0¢1 | I | （） | OL | $\bigcirc$ |
| 18560）I | 5 | I | $\leq L$ | （0） |
| L＋20） 611 | 5 | I | SL | LS |
| 2908 ${ }^{\text {L II }}$ | 5 | I | SL | 5 |
| †088．9てI | 5 | I | SL | （）S |
| －8tでど1 | 5 | I | SL | LE |
| $89+$ Cl I | 5 | I | $\leq L$ | tI |
| c800 $8+1$ | ¢ | I | SL | EI |
| 19cc゙て（）I | $\dagger$ | I | $\leq L$ | （）9 |
| ＋St9 92I | ＋ | 1 | SL | LS |
| $66+1$ IcI | $\dagger$ | I | SL | 5 |
| 89でャてI | t | I | SL | OS |
| tci $0^{(0) 1}$ | $\dagger$ | I | SL | L： |
| $9616 \bigcirc$ II | $\dagger$ | I | SL | ＋I |
| ¢8t6 $1+1$ | $\dagger$ | I | SL | EI |
| S516－01 | ¢ | I | $\leq$ | （0） |
| 816c゙けt1 | ¢ | I | SL | LS |
| ¢58ごこてI | $\varepsilon$ | I | SL | 5 |
| 998 ¢ $^{\text {LII I }}$ | $\varepsilon$ | I | SL | （）S |
| ¢c8C6 61 | E | I | $\leq L$ | LE |
| ＋9＋1．6II | \＆ | I | SL | ＋1 |
| IOLt＋cil | $\varepsilon$ | I | SL | ¢1 |
| 169C゙III | $\stackrel{\rightharpoonup}{2}$ | I | SL | （）9 |
| ＋6LSでで | て | I | SL | LS |
| 169E゙くてI | て | I | SL | S |
| 816E゙IてI | て | I | SL | OS |
| L9L6EI | て | I | SL | LE |
| L888 5 こ1 | て | 1 | SL | ＋I |
| ¢8t1 ¢ ¢ I | て | I | SL | ¢1 |
| L68ご9で | I | I | SL | （0） |
| Iてが1 | I | 1 | SL | LS |
| $696 て ゙ て$ ¢1 | I | I | SL | S |
| SIS0 +1 | I | I | SL | OS |
| ＋9ts゙6E1 | 1 | 1 | SL | LE |
|  | I | 1 | SL | ＋1 |
| L96てご | I | I | $\leq L$ | $\bigcirc 1$ |
| 6て91「しII | 5 | 0 | SL | 66 |
| ＋5tでで1 | 5 | （） | SL | 85 |
| 66で 0 （1） | 5 | （） | SL | 65 |
| ＋9＋6．91 I | $\bigcirc$ | （） | SL | て† |
|  | 5 | 0 | $\leq L$ | It |
| 8LてごけII | 5 | （） | SL | Is |
| $\begin{array}{r} \hline \text { (um!u!umiv } \\ \text { uuı I (0) } \\ \text { NVGW } \\ \hline \end{array}$ | IO | dกO¢૭ | ヨ7〇NV | BSEOH |


| 892でくII | 5 | （） | $\leq L$ | $\bigcirc$ |
| :---: | :---: | :---: | :---: | :---: |
| 9くら9 $\dagger$（）I | t | （） | S $L$ | 66 |
| I（ ）＜9 ${ }^{\text {＋}}$（）I | t | （） | SL | 85 |
| 19Es66 | t | （） | $5 L$ | 65 |
| ccocol | t | （） | SL | て† |
| カccoll | t | （） | 51 | It |
| て＋L0で）I | $\dagger$ | （） | SL | IS |
| 98It「S）I | t | （） | SL | ¢ |
| Sc8c゙ol | ¢ | （） | SL | 66 |
| 8096 80 I | ¢ | （） | SL | 85 |
| Sc8LCoI | E | （） | SL | 65 |
| くけて9 0 （）I | $\mathcal{E}$ | （） | SL | て† |
| カごぐくII | $\varepsilon$ | （） | SL | It |
| 86ごて6 | $\varepsilon$ | （） | SL | IC |
| とけtI LOI | ¢ | （） | CL | $\bigcirc$ |
| ＋9†6＇0II | て | （） | EL | 66 |
| てごく60！ | c | （） | SL | 85 |
| Iて）で66 | て | （） | SL | 65 |
| 6960）${ }^{\text {（）I }}$ | て | （） | SL | く† |
| 68てで6I I | て | （） | SL | It |
| てL0E゙て）I | て | （） | SL | Iと |
| 9IてL＇0II | て | （） | SL | $\stackrel{\text { ¢ }}{ }$ |
| でLO\％ 61 | I | （） | SL | 66 |
| とでじててI | I | （） | SL | 85 |
| 6で91矿 | 1 | （） | SL | 65 |
| ¢9L（）をII | I | （） | SL | 2t |
| て80でら11 | I | （） | $\leq L$ | It |
| 60）で† I I | I | （） | SL | IE |
| ¢91t（）EI | I | （） | SL | ¢く |
| 8L2660） | 5 | I | （08 | （1） |
| col9611 | 5 | I | （08 | LS |
| colでしII | 5 | 1 | 08 | 5 |
| S0） 6 CZI | $\bigcirc$ | I | 08 | （）S |
| 9＋56．111 | 5 | I | （08 | LE |
| 9てごで・1 | $\underline{5}$ | I | 08 | ＋I |
| 9028611 | 5 | I | 08 | \＆1 |
| 10ごら01 | t | I | 08 | （）9 |
| でLでIEI | $\dagger$ | I | （08 | LS |
| 656L\％ 6 I | t | I | 08 | 5 |
| L9S1「こてI | ＋ | I | （08 | （）S |
| I（0LでですI | ＋ | 1 | （08 | LE |
| ＋てI | t | I | 108 | ＋1 |
| 8096．821 | ＋ | I | 08 | ¢ I |
| Ctts゙oll | E | I | 08 | （）9 |
| て6とでISI | $\varepsilon$ | I | 08 | LS |
| ててしでして1 | $\varepsilon$ | I | 08 | S5 |
| ¢606 911 | ¢ | I | 08 | OS |
| 958ざでI | $\varepsilon$ | I | 08 | LE |
| しIてぐ8てI | $\varepsilon$ | I | 08 | †I |
| $\begin{array}{r} \text { (um!uium IV } \\ \text { uu I }()) \\ \text { NVEW } \\ \hline \end{array}$ | IO4 | dПO¢O | 370nv | BSEOH |


| HORSE | ANGLE | GROUP | ROI | MEAN <br> ( 0.1 mm <br> Aluminium |
| :---: | :---: | :---: | :---: | :---: |
| 31 | 70 | () | 2 | $1(1.9537$ |
| 41 | 70 | () | 2 | 123.4875 |
| +2 | 70 | () | 2 | 107.3879 |
| 58 | 70 | () | 2 | 111.7936 |
| 59 | 70 | () | 2 | $97.91+6$ |
| 99 | 70 | () | 2 | 108.85+1 |
| 25 | 70 | () | 3 | 102.968 |
| 31 | 70 | () | 3 | $97.6+06$ |
| 4 | 70 | () | 3 | 12.3 .21 |
| +2 | 70 | () | 3 | 101.4662 |
| 58 | 70 | () | 3 | 107.722t |
| 59 | 70 | () | 3 | 97.2171 |
| 99 | 70) | () | 3 | 108.7971 |
| 25 | 70 | () | $+$ | 97.9893 |
| 31 | 70 | () | $+$ | 97.3203 |
| +1 | 70) | () | 4 | 112 |
| +2 | 70 | () | $+$ | 104.8399 |
| 58 | 70 | () | 4 | 101.669 |
| 59 | 70 | () | 4 | 97.0214 |
| 99 | 7) | () | $+$ | $1(1) 2.6939$ |
| 25 | 70 | () | 5 | 109.9786 |
| 31 | 70 | () | 5 | 110.95 .37 |
| +1 | 70) | () | 5 | 121.5267 |
| +2 | 70) | () | 5 | 116.6762 |
| 58 | 70) | () | 5 | 109.2029 |
| 59 | 70 | () | 5 | 116.8256 |
| 99 | 70 | () | 5 | 112.7651 |
| 13 | 70 | 1 | 1 | $130.91+6$ |
| 14 | 70 | 1 | 1 | 138.4164 |
| 37 | 70 | 1 | 1 | $1+(0.7+() 2$ |
| 50 | 70 | 1 | 1 | 119.6192 |
| 55 | 70 | 1 | 1 | 135.2206 |
| 57 | 70 | 1 | 1 | 130.8221 |
| 60 | 70 | 1 | 1 | 130.5552 |
| 13 | 70 | 1 | 2 | 126.3025 |
| $1+$ | 7() | 1 | 2 | $12+.10 .32$ |
| 37 | 70 | 1 | 2 | 139.(0)391 |
| 50 | 70 | 1 | 2 | 127.3808 |
| 55 | 70 | 1 | 2 | $125.4(1) 5$ |
| 57 | 70 | 1 | 2 | 123.7829 |
| 60 | 70 | 1 | 2 | 112.4769 |
| 13 | 70 | 1 | 3 | 117.9858 |
| $1+$ | 70 | 1 | 3 | 121.5765 |
| 37 | 70 | 1 | 3 | 117.7971 |
| 50 | 70 | 1 | 3 | $122.91+6$ |
| 55 | 70 | 1 | 3 | 120.6655 |
| 57 | 70 | 1 | 3 | 1+3.1139 |
| 60 | 70 | 1 | 3 | 107.9609 |
| 13 | 70 | 1 | 4 | 119.9004 |


| HORSE | ANGLE | GROUP | ROI | MEAN (0.1 m m Aluminiunn) |
| :---: | :---: | :---: | :---: | :---: |
| 14 | 7) | 1 | 4 | 123.5552 |
| 37 | 7) | 1 | $+$ | 103.359t |
| 50 | 70 | 1 | $+$ | 125.79 |
| 55 | 70 | 1 | $+$ | $125.85+1$ |
| 57 | 7) | 1 | $+$ | 125.0569 |
| 60 | 7) | 1 | $+$ | 102.81+9 |
| 13 | 7) | 1 | 5 | 119.968 |
| $1+$ | 7) | 1 | 5 | $1+3.85+1$ |
| 37 | 7) | 1 | 5 | 115.0854 |
| 50 | 70) | 1 | 5 | 127.3559 |
| 55 | 7) | 1 | 5 | 116.1566 |
| 57 | 70) | 1 | 5 | 120.1851 |
| 60 | 70 | 1 | 5 | 112.5587 |
| 25 | 65 | () | 1 | 123.2+2 |
| 31 | 65 | () | 1 | 112.1103 |
| +1 | 65 | () | 1 | 118.2527 |
| +2 | 65 | () | 1 | 117.0961 |
| 58 | 65 | () | 1 | 124.7789 |
| 59 | 65 | () | 1 | 128.395 |
| 99 | 65 | () | 1 | 1.30 .3488 |
| 25 | 65 | () | 2 | 96.2669 |
| 31 | 65 | () | 2 | 90.6406 |
| +1 | 65 | () | 2 | $11+.4093$ |
| +2 | 65 | () | 2 | 102.0783 |
| 58 | 65 | () | 2 | 107.7053 |
| 59 | 65 | () | 2 | 93.1566 |
| 99 | 65 | () | 2 | 110.6904 |
| 25 | 65 | () | 3 | 95.7331 |
| 31 | 65 | () | 3 | 86.0036 |
| +1 | 65 | () | 3 | 107.3986 |
| +2 | 65 | () | 3 | 99.6584 |
| 58 | 65 | () | 3 | $98.6+56$ |
| 59 | 65 | () | 3 | 89.8897 |
| 99 | 65 | () | 3 | $105.3+52$ |
| 25 | 65 | () | $t$ | 89.032 |
| 31 | 65 | () | + | 87.8363 |
| +1 | 65 | 1 | $+$ | 99.7865 |
| +2 | 65 | () | $t$ | 102.3701 |
| 58 | 65 | () | $+$ | 100.8175 |
| 59 | 65 | () | $+$ | 90.089 |
| 99 | 65 | 0 | 4 | 106.3167 |
| 25 | 65 | () | 5 | 101.5623 |
| 31 | 65 | () | 5 | 99.8292 |
| $+1$ | 65 | () | ) 5 | 113.6584 |
| +2 | 65 | () | ) 5 | 113.7687 |
| 58 | 65 | 0 | 5 | 5111.993 |
| 59 | 65 | () | ) 5 | $5109.06+1$ |
| 99 | 65 | 1 | ) 5 | 5 119.5765 |
| 13 | 65 | , | 1 | 1 129.6014 |


| †ご6でし | $\underline{5}$ | I | （）9 | CI |
| :---: | :---: | :---: | :---: | :---: |
| Lてこで96 | t | I | （）9 | （）9 |
| 8こてご6（）！ | $\dagger$ | 1 I | （0） | LS |
| で619＊6て1 | $\dagger$ | I | （）9 | －5 |
| くでぐoてI | † | I | （）9 | （） |
| L8SS 16 | $\dagger$ | 1 | （）9 | LE |
| しでてII | $\dagger$ | I | （0） | $\dagger 1$ |
| ごItナ S（）I | $\dagger$ | I | （0） | Cl |
| 6ちごで（）） | C | $I$ | （0） | （）9 |
| ［6さや91］ | C | I | （0） | LS |
| ちでのけで | ¢ | I | （0） | ¢5 |
| †Iて（）91 I | ¢ | I | （0） | （）S |
| LLET L6 | ¢ | I | （0） | LC |
| 9615 ごて | ¢ | 1 | （0） | †1 |
| $9+16 \dagger 01$ | ¢ | 1 | （0） | EI |
| 9615900 | $\stackrel{\rightharpoonup}{c}$ | I | （）9 | （）9 |
| L9てご111 | $\stackrel{\rightharpoonup}{c}$ | I | （0） | LS |
| †ど¢6てI | $\bar{\sim}$ | I | （0） | ご |
| $99+6 \angle 11$ | $\stackrel{\rightharpoonup}{c}$ | I | （0） | （）S |
| て¢6880］ | て | I | （0） | LC |
| $686 て ゙ \downarrow 11$ | $\bar{\sim}$ | I | （0） | †I |
| Lt $20 . L 0$ I | $\bar{\sim}$ | I | （0） | CI |
| ＋CS（）8てI | I | I | （0） | （）9 |
| LL†）SてI | I | I | （0） | LS |
| 26I9 ctI | I | I | （）9 | S¢ |
| 6とIItcI | I | I | （）9 | （）S |
| とItナ çI | I | I | （）9 | LS |
| LS（）tこど | I | I | （0） | †I |
| 8901 Lで | I | I | （0） | CI |
| 6LSぐきII | 5 | （） | （0） | 66 |
| ごら6で1 | $\underline{5}$ | （） | （0） | 65 |
| でてLし「6 | $\underline{5}$ | （） | （0） | 85 |
| 1て19†6 | $\underline{5}$ | （） | （0） | で |
| $1+9068$ | 5 | （） | （0） | It |
| Icc゙て（）］ | 5 | （） | （0） | 15 |
|  | $\underline{5}$ | （） | （0） | ごて |
|  | $\dagger$ | （） | （0） | 66 |
| で50．66 | t | （） | （）9 | 65 |
| てIL（） 58 | $\dagger$ | （） | （0） | 85 |
| †ご0 68 | t | （） | （）9 | で |
| $86 こ て ゙ \leq 8$ | $\dagger$ | （） | （）9 | It |
|  | $\dagger$ | （） | （0） | 1 ¢ |
| †とs（）$\dagger$ ¢ | t | （） | （0） | $\leq$ ¢ |
| †I9S゙く6 | c | （） | （）9 | 66 |
| 99S1 L6 | c | （） | （）9 | 65 |
| ごぐャ 28 | $\varepsilon$ | （） | （）9 | 85 |
| 182I 58 | $\varepsilon$ | （） | （0） | て† |
| －809068 | $\varepsilon$ | （） | （0） | It |
| Z（）$+\angle L 8$ | ¢ | （） | （）9 | I ¢ |
| $\begin{array}{r} \text { (um!u!uın「V } \\ \text { uuI I (0) } \\ \text { NVEW } \\ \hline \end{array}$ | IO | d | ヨ79nv | EStOH |


| 2（）＋L．8 | $\varepsilon$ | （） | （）9 | $\leq 2$ |
| :---: | :---: | :---: | :---: | :---: |
| $981^{\circ} 901$ | $乙$ | （） | （）9 | 66 |
| LLt9 ${ }^{\circ}()$（） | $\stackrel{\rightharpoonup}{c}$ | （） | （）9 | 65 |
| 8ナナナ（）6 | $\stackrel{\rightharpoonup}{c}$ | （） | （）9 | 85 |
| 6けて（）98 | $\stackrel{\rightharpoonup}{c}$ | （） | （）9 | て† |
| 1t90）86 | $\stackrel{\rightharpoonup}{c}$ | （） | （）9 | It |
| $6 己() て ゙ 16$ | て | （） | （）9 | I C |
| 1988 c8 | て | （） | （0） | ごて |
| L99††てI | I | （） | （0） | 66 |
| ＋8けナヤで | I | （） | （0） | 65 |
| IL6L＇90］ | I | （） | （）9 | 85 |
| LSI9 80） | I | （） | （0） | で |
| 6ちこで9（）！ | I | （） | （0） | It |
| 8（）8ご0）I | I | （） | （）9 | 15 |
| L09ごら0｜ | I | （） | （）9 | ごて |
| Cご（）6で1 | 5 | I | －5） | （0） |
| 9 ）でぐくII | 5 | I | －5） | LS |
| C9て9 LII | 5 | I | －9） | ご |
| L9EL9て1 | 5 | I | ¢9） | （）S |
| 6ct6 ごI | 5 | I | －5） | LE |
| $816{ }^{\circ} 9 \mathrm{Cl}$ | ¢ | I | ¢9） | †I |
| 9881611 | $\stackrel{5}{5}$ | I | 59 | EI |
| 568L96 | $\dagger$ | I | ¢9） | （）9 |
| 6ごごで1 | $\dagger$ | I | ¢） | LS |
| どけナ・です | $\dagger$ | I | －9） | －5 |
| L（）］（）L Z I | $\dagger$ | I | ¢） | （）¢ |
| 89E1 L6 | $\dagger$ | I | －9） | LE |
| 19889（）I | t | I | －9） | †I |
| 8 EO （6゙II | $\dagger$ | I | －9） | CI |
| 91と8＊）（ | 5 | I | －9） | （）9 |
| でてでけて！ | $\mathcal{E}$ | I | ¢9） | LS |
|  | C | I | －9） | S¢ |
| ご（）8ごくす | ¢ | I | S9 | （）s |
|  | $\varepsilon$ | I | －9） | LE |
| ELS†（）I | C | I | ¢9 | †I |
| ごて9ご601 | $\mathscr{C}$ | I | －9） | CI |
| 8てZごん（）I | て | I | －9） | （）9 |
| こて86 111 | て | I | S9 | LS |
| 6c06911 | $\checkmark$ | I | －9） | S¢ |
| 8てて9ごく1 | て | I | 59 | （）S |
| 6ごだで， | て | I | －9） | LS |
| S（）9＇s0I | て | I | S9 | ＋I |
|  | て | I | －99 | CI |
| t10 csi | I | I | S9 | （0） |
| ¢818ごT | I | I | －9） | LS |
| 85LこcI | I | I | 59 | SS |
| こて86「ご | I | I | －9） | （0） |
| CてIご9ぐ1 | I | I | －9） | LE |
| S6てLしで | I | I | S9 | †I |
| （un！u！u！ $1 \forall$ <br> uui I（） <br> $\mathrm{N} \forall \exists \mathrm{F}$ | IOY | dПO¢D | ヨ7ONV | BSUOH |


| HORSE | ANGLE | GROUP | ROI | MEAN <br> $(0.1 \mathrm{~mm}$ <br> Aluminium) |
| ---: | ---: | ---: | ---: | ---: |
| 14 | 60 | 1 | 5 | 129.605 |
| 37 | 60 | 1 | 5 | 102.1779 |


| 50 | 60 | 1 | 5 | 123.484 |
| ---: | ---: | ---: | ---: | ---: |
| 55 | 60 | 1 | 5 | 135.7117 |
| 57 | 60 | 1 | 5 | 115.9893 |
| 60 | 60 | 1 | 5 | 110.5338 |

## Palmar data

| HORSE | GROUP | ANGLE | ROI | $\begin{array}{l}\text { MEAN } \\ (0.1 \text { nun }\end{array}$ |
| ---: | ---: | ---: | ---: | ---: |
| Aluminiun) |  |  |  |  |$)$


| HORSE | ANGLE | GROUP | ROI | MEAN <br> ( 0.1 mm <br> Aluminium) |
| :---: | :---: | :---: | :---: | :---: |
| 55 | 1 | 80 | 1 | $1+0.4+12$ |
| 60 | 1 | 80 | 1 | 129.7959 |
| $+1$ | 0 | 75 | 1 | $117.48+5$ |
| +2 | 0 | 75 | 1 | $11+.412 t$ |
| 59 | () | 75 | 1 | 129.74+3 |
| 25 | 0 | 75 | 1 | 130.1814 |
| 58 | 0 | 75 | 1 | 12+.(1)7+2 |
| 31 | () | 75 | 1 | 116.8351 |
| 99 | () | 75 | 1 | 121.6887 |
| 57 | 1 | 75 | 1 | 149.7485 |
| $1+$ | 1 | 75 | 1 | 136.5299 |
| 13 | 1 | 75 | 1 | 137.6371 |
| 37 | 1 | 75 | 1 | 149.278t |
| 50 | 1 | 75 | 1 | 123.93t |
| 55 | 1 | 75 | 1 | 1+4.266 |
| 60 | 1 | 75 | 1 | 1.31 .0928 |
| +1 | () | 90 | 2 | 122.7809 |
| +2 | () | 90 | 2 | 113.567 |
| 59 | () | 90 | 2 | 121.5057 |
| 25 | () | 90 | 2 | $116.3+4.3$ |
| 58 | 0 | 90 | 2 | $113.35+6$ |
| 31 | () | 90 | 2 | 115.5248 |
| 99 | () | 90 | 2 | 126.8351 |
| 57 | 1 | 90 | 2 | $150.21+4$ |
| 14 | 1 | 90 | 2 | $1+3.3567$ |
| 13 | 1 | 90 | 2 | 152.0227 |
| 37 | 1 | 90 | 2 | 146.167 |
| 50 | 1 | 90 | 2 | $123.3+4.3$ |
| 55 | 1 | 90 | 2 | 1+1.5184 |
| 60 | 1 | 90 | 2 | $130.28+5$ |
| $+1$ | () | 85 | 2 | 122.6247 |
| +2 | () | 85 | 2 | 112.9093 |
| 59 | () | 85 | 2 | 120.012t |
| 25 | () | 85 | 2 | 119.0784 |
| 58 | () | 85 | 2 | 114.3567 |
| 31 | () | 85 | 2 | 110.2268 |
| 99 | () | 85 | 2 | $128.9+() 2$ |
| 57 | 7 | 85 | 2 | 153.9+2.3 |
| $1+$ | - 1 | 85 | 2 | $1+5.88+5$ |
| 13 | 1 | 85 | 2 | 154.8247 |


| HORSE | ANGLE | GROUP | ROI | $\begin{aligned} & \text { MEAN } \\ & \text { (0.1 mm } \\ & \text { Aluminium) } \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: |
| 37 | 1 | 85 | 2 | 148.680) |
| 50 | 1 | 85 | 2 | $125.49+8$ |
| 55 | 1 | 85 | 2 | $1+1.0866$ |
| 60 | 1 | 85 | 2 | 131.9753 |
| +1 | 0 | 80 | 2 | 117.8392 |
| +2 | 0 | 80 | 2 | 106.501 |
| 59 | () | 80 | 2 | 112.06 .39 |
| 25 | () | 80 | 2 | 112.701 |
| 58 | () | 80 | 2 | 107.332 |
| 31 | () | 80 | 2 | 103.7588 |
| 99 | () | 80 | 2 | 119.6309 |
| 57 | 1 | 80 | 2 | $1+5.132$ |
| $1+$ | 1 | 80 | 2 | 139.5753 |
| 13 | 1 | 80 | 2 | 1+9.1588 |
| 37 | 1 | 80 | 2 | 1+4.4.371 |
| 50 | 1 | 80 | 2 | 122.6289 |
| 55 | 1 | 80 | 2 | $135.5+2.3$ |
| 60 | 1 | 80 | 2 | 124.8928 |
| 4 | () | 75 | 2 | 121.1711 |
| +2 | () | 75 | 2 | 108.8062 |
| 59 | () | 75 | 2 | 110.3216 |
| 25 | 0 | 75 | 2 | 113.3526 |
| 58 | () | 75 | 2 | 112.4887 |
| 31 | () | 75 | 2 | 105.7381 |
| 99 | () | 75 | 2 | 118.7526 |
| 57 | 1 | 75 | 2 | $1+1.8928$ |
| 14 | 1 | 75 | 2 | $1+2.0+12$ |
| 13 | 1 | 75 | 2 | $1+6.16+9$ |
| 37 | 1 | 75 | 2 | $1+8.3526$ |
| 50 | 1 | 75 | 2 | 123.2619 |
| 55 | 1 | 75 | 2 | 1.37 .7155 |
| 60 | 1 | 75 | 2 | 124.16+9 |
| +1 | () | 90 | 3 | 126.6 |
| +2 | () | 90 | 3 | $10+8557$ |
| 59 | () | 90 | 3 | 121.5057 |
| 25 | () | 90 | 3 | 117.2165 |
| 58 | () | 90 | 3 | 112.0825 |
| 31 | () | 90 | 3 | 109.4588 |
| 99 | 0 | 90 | 3 | $117.00+1$ |
| 57 | 1 | 90 | 3 | 156.4 .371 |
| 14 | 1 | 90 | 3 | $1+4.8206$ |
| 13 | 1 | 90 | 3 | $1+2.9917$ |
| 37 | 1 | 90 | 3 | 129.746t |
| 50 | 1 | 90 | 3 | $120.87+2$ |
| 55 | 1 | 90 | 3 | 128.2372 |
| 60 | 1 | 90 | 3 | 118.4804 |
| +1 | () | 85 | 3 | 125.299 |
| +2 | () | 85 | 3 | $105.3+02$ |
| 59 | () | 85 | 3 | 112.534 |


| HORSE | ANGLE | GROUP | ROI | $\begin{array}{\|l\|} \hline \text { ME AN } \\ (0.1 \mathrm{~mm} \\ \text { Aluminium) } \\ \hline \end{array}$ |
| :---: | :---: | :---: | :---: | :---: |
| 25 | 0 | 85 | 3 | 120.8536 |
| 58 | () | 85 | 3 | $11+.4227$ |
| 31 | 0 | 85 | 3 | 106.8515 |
| 99 | 0 | 85 | 3 | $120.812+$ |
| 57 | 1 | 85 | 3 | $162.89+9$ |
| 14 | 1 | 85 | 3 | $1+5.8557$ |
| 13 | 1 | 85 | 3 | $1+3.3608$ |
| 37 | 1 | 85 | 3 | 128.5134 |
| 50 | 1 | 85 | 3 | 122.1196 |
| 55 | 1 | 85 | 3 | $130.87+2$ |
| 60 | 1 | 85 | 3 | 120.9835 |
| $+1$ | () | 80 | 3 | 122.9773 |
| +2 | () | 80 | 3 | 101.4.371 |
| 59 | () | 80 | 3 | 108.9629 |
| 25 | () | 80 | 3 | 115.2371 |
| 58 | 0 | 80 | 3 | 107.868 |
| 31 | 0 | 80 | 3 | 100.5918 |
| 99 | () | 80 | 3 | $111.6+12$ |
| 57 | 1 | 80 | 3 | 157.299 |
| 14 | 1 | 80 | 3 | 139.7814 |
| 13 | 1 | 80 | 3 | $137.8+7+$ |
| 37 | 1 | 80 | 3 | 122.8 |
| 50 | 1 | 80 | 3 | $118.07+2$ |
| 55 | 1 | 80 | 3 | 128.167 |
| 60 | 1 | 80 | 3 | 116.72 .58 |
| 41 | () | 75 | 3 | 125.1485 |
| +2 | 0 | 75 | 3 | $10+.2227$ |
| 59 | () | 75 | 3 | 112.8515 |
| 25 | () | 75 | 3 | 116.47 ) 1 |
| 58 | () | 75 | 3 | $11+.0825$ |
| 31 | () | 75 | 3 | 103.2103 |
| 99 | () | 75 | 3 | $115.7+4.3$ |
| 57 | 1 | 75 | 3 | 156.9629 |
| 14 | 1 | 75 | 3 | 1+4.1+()2 |
| 13 | 1 | 75 | 3 | 137.5918 |
| 37 | 1 | 75 | 3 | 122.7175 |
| 50 | 1 | 75 | 3 | 120.7567 |
| 55 | 1 | 75 | 3 | 132.7+2.3 |
| 60 | 1 | 75 | 3 | 117.9773 |
| $+1$ | () | $9(0)$ | $+$ | 126.6 |
| $+2$ | () | 90 | $t$ | $10+.035$ |
| 59 | () | 90 | 4 | 121.5057 |
| 25 | () | 90 | + | 120.6247 |
| 58 | () | 90 | + | 112.767 |
| 31 | () | 90 | $t$ | 109.4588 |
| 99 | 0 | 90 | + | 114.6928 |
| 57 | 1 | 90 | $+$ | 151.8 |
| $1+$ | 1 | 90 | $t$ | + 143.8247 |
| 13 | 1 | 90 | 4 | 156.1505 |


| HORSE | ANGLE | GROUP | ROI | MEAN <br> (0.1 mm <br> Aluminium) |
| :---: | :---: | :---: | :---: | :---: |
| 37 | 1 | 90 | $+$ | 11+.233 |
| 50 | 1 | 90 | 4 | 138.3237 |
| 55 | 1 | 90 | $+$ | $138.67+9$ |
| 60 | 1 | 90 | $+$ | 121.2536 |
| +1 | () | 85 | $+$ | 126.3732 |
| +2 | () | 85 | $t$ | 109.8021 |
| 59 | () | 85 | $+$ | 115 |
| 25 | () | 85 | $+$ | 122.0021 |
| 58 | () | 85 | $t$ | 116.5773 |
| 31 | 0 | 85 | $+$ | $112.179+$ |
| 99 | () | 85 | $+$ | 120.9546 |
| 57 | 1 | 85 | $+$ | 152.5381 |
| $1+$ | 1 | 85 | $+$ | $1+3.1299$ |
| 13 | 1 | 85 | $+$ | $15+.1402$ |
| 37 | 1 | 85 | $+$ | 113.7691 |
| 50 | 1 | 85 | $t$ | 139.5629 |
| 55 | 1 | 85 | $+$ | $1+4.1216$ |
| 60 | 1 | 85 | $+$ | 123.8536 |
| +1 | () | 80 | $+$ | 121.1917 |
| +2 | () | 80 | $+$ | 105.1113 |
| 59 | () | 80 | $+$ | 110.666 |
| 25 | () | 80 | $+$ | 116.5753 |
| 58 | () | 80 | $+$ | 111.0103 |
| 31 | () | 80 | $+$ | 106.3216 |
| 99 | () | 80 | $+$ | 112.4866 |
| 57 | 1 | 80 | $+$ | $1+3.132$ |
| $1+$ | 1 | 80 | $t$ | 138.1072 |
| 13 | 1 | 80 | $+$ | $1+6.2619$ |
| 37 | 1 | 80 | $+$ | $107.27+2$ |
| 50 | 1 | 80 | $+$ | $1.3+.5876$ |
| 55 | 1 | 80 | $+$ | $1+0.1608$ |
| 60 | 1 | 80 | $+$ | $11+.9505$ |
| $+1$ | () | 75 | $+$ | $120.5+6+$ |
| +2 | () | 75 | $+$ | 108.9505 |
| 59 | () | 75 | $+$ | 110.6598 |
| 25 | () | 75 | $t$ | 117.068 |
| 58 | () | 75 | $t$ | 116.7+4. |
| 31 | () | 75 | $t$ | $110.0+33$ |
| 99 | () | 75 | $+$ | 111.8083 |
| 57 | 1 | 75 | $+$ | $1+1.7979$ |
| $1+$ | 1 | 75 | $+$ | $1+7.0495$ |
| 13 | 1 | 75 | $+$ | 131.7753 |
| 37 | 1 | 75 | $+$ | 107.501 |
| 50 | 1 | 75 | + | 138.4103 |
| 55 | 1 | 75 | + | $1+4.6165$ |
| 60 | 1 | 75 | $t$ | 112.6206 |
| $+1$ | () | 90 | 5 | 139.6511 |
| +2 | 0 | 90 | 5 | 130.4165 |
| 59 | 0 | 90 | 5 | 133.7155 |


| HORSE | ANGLE | GROUP | ROI | MEAN (0.1 mm Aluminium) |
| :---: | :---: | :---: | :---: | :---: |
| 25 | () | 90 | 5 | 123.2206 |
| 58 | () | 90 | 5 | 118.1856 |
| 31 | () | 90 | 5 | 122.1629 |
| 99 | () | 90 | 5 | 126.87()1 |
| 57 | 1 | 90 | 5 | $132.878+$ |
| $1+$ | 1 | 90 | 5 | $151.14(02$ |
| 13 | 1 | 90 | 5 | 128.6+3.3 |
| 37 | 1 | 90 | 5 | $121.27+2$ |
| 50 | 1 | 90 | 5 | 136.2309 |
| 55 | 1 | 90 | 5 | 122.96 .32 |
| 60 | 1 | 90 | 5 | 122.5072 |
| +1 | () | 85 | 5 | 137.1299 |
| $+2$ | () | 85 | 5 | 130.033 |
| 59 | () | 85 | 5 | 129.9052 |
| 25 | () | 85 | 5 | 122.4165 |
| 58 | () | 85 | 5 | 120.4124 |
| 31 | () | 85 | 5 | $128.7+85$ |
| 99 | () | 85 | 5 | 135.7588 |
| 57 | 1 | 85 | 5 | 137.1485 |
| $1+$ | 1 | 85 | 5 | 153.3938 |
| 13 | 1 | 85 | 5 | 128.765 |
| 37 | 1 | 85 | 5 | 126.7629 |
| 50 | 1 | 85 | 5 | 132.3588 |
| 55 | 1 | 85 | 5 | 12+.88+5 |
| 60 | 1 | 85 | 5 | 123.1031 |
| +1 | () | 80 | 5 | 129.9588 |
| +2 | () | 80 | 5 | 122.5753 |
| 59 | () | 80 | 5 | 123.9278 |
| 25 | () | 80 | 5 | 117.3155 |
| 58 | () | 80 | 5 | 11+.3134 |
| 31 | () | 80 | 5 | $122.49+8$ |
| 99 | () | 80 | 5 | 125.3134 |
| 57 | 1 | 80 | 5 | 132.4227 |
| $1+$ | 1 | 80 | 5 | $1+8.7917$ |
| 13 | 1 | 80 | 5 | 123.4619 |
| 37 | 1 | 80 | 5 | 117.7031 |
| 50 | 1 | 80 | 5 | 132.9629 |
| 55 | 1 | 80 | 5 | 123.035 |
| 60 | 1 | 80 | 5 | 118.2866 |
| +1 | 0 | 75 | 5 | 127.6 |
| $+2$ | 0 | 75 | 5 | 127.2227 |
| 59 | 0 | 75 | 5 | 129.3876 |
| 25 | () | 75 | 5 | $119.67+2$ |
| 58 | 0 | 75 | 5 | 1 120.1629 |
| 31 | () | 75 | 5 | $125.3+(02$ |
| 99 | () | 75 | 5 | 125.2103 |
| 57 | 1 | 75 | 5 | -1.32.2206 |
| 14 | 1 | 75 | 5 | ) 1+8.967 |
| 13 | 1 | 75 | 5 | ) 125.466 |


| ISCL\％ $6+1$ | $\tau$ | S9 | I | EI |
| :---: | :---: | :---: | :---: | :---: |
| ScSt Lel | て | ¢） | I | †I |
| 6 cll ${ }^{\text {cto }}$ | $\tau$ | ¢） | I | LS |
| ＋8＋6てI | $\tau$ | S） | （） | 66 |
| $99+6 \leq 01$ | $\tau$ | S9 | （） | 15 |
| coIt でI | て | ¢9 | （） | 85 |
| ¢L9I SII | て | ¢） | （） | $\bigcirc て$ |
| Iヒてご80］ | $\tau$ | S9 | （） | 65 |
| 1960\％611 | $\tau$ | S） | （） | て† |
| c898 621 | て | ¢9 | （） | It |
| ごてILT $\dagger$ | I | S9 | I | （）9 |
|  | I | ¢） | I | S |
| LIEI6EI | I | －9 | I | （）S |
| ¢9てぐ9く1 | I | S） | I | LE |
| 280L＇9†1 | I | S9 | I | E 1 |
|  | I | S9 | 1 | ＋1 |
| 66ItosI | I | S9 | I | LS |
| †91ナ9¢1 | I | S9 | （） | 66 |
| てらけこで | I | S9 | （） | IS |
| †ごLE゙（）†I | I | S9 | （） | 85 |
| $8+98+51$ | I | S9 | （） | $\bigcirc$ |
| ＋LII8EI | I | S9 | （） | 65 |
| てZLLごて1 | I | －9 | （） | て† |
| L9てらでて | 1 | 59 | （） | It |
| く＋8（）ZI | $\bigcirc$ | （）L | 1 | （0） |
| LLけ9゙こで | $\bigcirc$ | （）L | I | S¢ |
| ¢cI | $\bigcirc$ | （1） | 1 | （）S |
| て86けでで | Ş | （）L | I | LE |
| L91ビ6て1 | S | （）L | 1 | EI |
| と8LOけご | ¢ | OL | I | ＋1 |
| coze゙scl | $\bigcirc$ | （）L | 1 | LS |
| II6＋92I | S | OL | （） | 66 |
| ¢6E6611 | $\bigcirc$ | （OL | （） | 15 |
| L6L981I | $\underline{ }$ | OL | （） | 85 |
| 978881 I | S | （）L | （） | ¢̧ |
| 6L8ごくてI | $\bigcirc$ | OL | （） | $6 \leq$ |
| 90てで9て1 | ¢ | OL | （） | て† |
| I6けでIEI | $\bigcirc$ | OL | （） | It |
| 9288911 | ＋ | OL | I | （0） |
| L92ら゙らけ1 | t | OL | I | SS |
| 8968 6E1 | $\dagger$ | （0） | 1 | （）S |
| 5090001 | $\dagger$ | OL | I | LE |
| L（）IOて†I | t | （OL | I | EI |
| て） 66 －+1 | t | （0） | 1 | ＋1 |
| ¢ち（）8て†1 | $\dagger$ | （）L | I | LS |
| L8ごビII | ＋ | （）L | （） | 66 |
| 9288 てII | t | （OL | （） | IS |
| ¢60t 911 | t | OL | （） | 8 S |
| 82て9 ¢ II | $\dagger$ | OL | （） | －て |
|  | IO | d $\cap 040$ | 370n | 3StOH |


| 9ぐャでてII | t | （）L | （） | 65 |
| :---: | :---: | :---: | :---: | :---: |
| ＋966 ¢1I | t 0 | （）L | （） | て† |
| －818†で | $\dagger$ O | （）L | （） | It |
| 680ごで， | ¢ | OL | I | （0） |
| S090 $0^{\circ} \mathrm{CEI}$ | ¢ | （）L | I | S |
| ＋6LL 8てI | £ | OL | I | （）S |
| ご9ご9て1 | $\varepsilon$ | OL | I L | LE |
| 9 こん $て+1$ | $\varepsilon$ | （）L | I | ¢ I |
| Iて）+ ＋†1 | \＆ | OL | I | ＋1 |
| 816で191 | ¢ | OL | 1 | LS |
| －599 811 | ¢ | OL | （） | 66 |
| †－80）801 | E | OL | （） | IS |
| $929+$－II | ¢ | （）L | （） | 85 |
| てらけでsII | S | （）L | （） | $\bigcirc$ |
| It－8で1 | ¢ | （）L | （） | $6 \leq$ |
| 9660 ） 801 | 5 | OL | （） | て† |
| ¢0こ8てご1 | ¢ | OL | （） | It |
| 6 ¢ 20 8て1 | て | OL | 1 | （0） |
| 80LI $0+1$ | て | OL | 1 | SS |
| 986ごくて1 | て | （）L | I | （）S |
| こて（）＋ISI | て | （）L | I | LE |
| c9c8csi | 乞 | OL | 1 | EI |
| LC91家け | て | （）L | 1 | ＋1 |
| ＋LI「ごす | て | （）L | I | LS |
| 9288 I21 | $\tau$ | OL | （） | 66 |
|  | $\tau$ | （）L | （） | Iと |
| でで†11 | $\tau$ | OL | （） | 85 |
| 15t6ご11 | て | OL | （） | －て |
| 6L80） 1 | て | （）L | （） | $6 \leq$ |
| $91+$ c゙ol｜ | て | （）L | （） | て† |
| ccco 8 21 | $\tau$ | （）L | （） | It |
| ＋¢゙6で9 1 | I | OL | I | （0） |
| 92L9 ISI | I | OL | I | S¢ |
| 6け181E1 | I | （）L | 1 | （）S |
| と0てぐ「ご | I | OL | I | LE |
| IS9くで1 | I | OL | I | \＆ |
| ＋8S9 + ＋1 | I | OL | I | tI |
| I0 LC゙ $6+1$ | I | （）L | 1 | LS |
| ¢LS6こで | I | OL | （） | 66 |
| LE91て1 | I | OL | （） | IS |
| $929+$ L | I | （）L | （） | 8S |
| 2619 ${ }^{\text {cid }}$ | I | （）L | （） | $\bigcirc$ |
| c9c8－cil | I | （）L | （） | $6 \leq$ |
| tI0 9\％6II | I | （0） | （） | で |
| ＋118で1 | 1 | （）L | （） | It |
| ＋08t81I | $\bigcirc$ | SL | 1 | （0） |
| 6S゙6LCで | $\bigcirc$ | $\leq L$ | 1 | － |
| 88S1 ¢ ¢ | $\bigcirc$ | SL | 1 | OS |
| 6190 でI | $\bigcirc$ | SL | 1 | LE |
| $\begin{array}{r} \hline \text { (um!u!umiv } \\ \text { uum I ( ) } \\ \text { NVEW } \end{array}$ | IOY | d／1O4D | ヨ70nv | BStOH |


| HORSE | ANGLE | GROUP | ROI | MEAN <br> (0. 1 mm Aluminium) |
| :---: | :---: | :---: | :---: | :---: |
| 37 | 1 | 65 | 2 | $149.9+39$ |
| 50 | 1 | 65 | 2 | 13.3 .5516 |
| 55 | 1 | 65 | 2 | $1+3.0605$ |
| 60 | 1 | 65 | 2 | 131.3965 |
| +1 | 0 | 65 | 3 | 131.8185 |
| +2 | 0 | 65 | 3 | $113.38+3$ |
| 59 | () | 65 | 3 | 112.3167 |
| 25 | 0 | 65 | 3 | 115 |
| 58 | 0 | 65 | 3 | 122.3684 |
| 31 | () | 65 | 3 | 109.7295 |
| 99 | 0 | 65 | 3 | 125.288 .3 |
| 57 | 1 | 65 | 3 | $162.0+98$ |
| 14 | 1 | 65 | 3 | 1.39 .8577 |
| 13 | 1 | 65 | 3 | 1.38 .694 |
| 37 | 1 | 65 | 3 | 127.2351 |
| 50 | 1 | 65 | 3 | $1.3+452$ |
| 55 | 1 | 65 | 3 | $1+2.7()+6$ |
| 60 | 1 | 65 | 3 | $125.3+() 3$ |
| +1 | 0 | 65 | $+$ | 122.2883 |
| +2 | 0 | 65 | $t$ | 119.452 |
| 59 | 0 | 65 | $+$ | 112.2135 |
| 25 | 0 | 65 | $t$ | 113.8327 |
| 58 | () | 65 | $t$ | $126.56+9$ |
| 31 | () | 65 | $t$ | 115.8577 |
| 99 | ) | 65 | $t$ | 124.6.37 |
| 57 | 1 | 65 | $+$ | $1+3.4733$ |
| $1+$ | 1 | 65 | $+$ | $1+3.3381$ |
| 13 | 1 | 65 | $+$ | $1+4.8327$ |
| 37 | 1 | 65 | $+$ | $11+.1263$ |
| 50 | 1 | 65 | $t$ | 151.3986 |
| 55 | 1 | 65 | $+$ | 153.3665 |
| 60 | 1 | 65 | $+$ | 121.0772 |
| +1 | () | 65 | 5 | $127.86+8$ |
| +2 | () | 65 | 5 | 129.2918 |
| 59 | () | 65 | 5 | 130.6833 |
| 25 | () | 65 | 5 | 119.2527 |
| 58 | () | 65 | 5 | $127.28+2$ |
| 31 | () | 65 | 5 | 121.74 .38 |
| 99 | () | 65 | 5 | 136.0854 |
| 57 | 1 | 65 | 5 | 132.8612 |
| 14 | 1 | 65 | 5 | $153.49+7$ |
| 13 | 1 | 65 | 5 | 135.5196 |
| 37 | 1 | 65 | 5 | 125.4526 |
| 50 | 1 | 65 | 5 | 140.1139 |
| 55 | 1 | 65 | 5 | 132.8114 |
| 60 | 1 | 65 | 5 | 125.6 |
| $+1$ | () | 60 | 1 | 126.21 |
| +2 | () | ) 60 | 1 | 131.0498 |
| 59 | () | ) 60 | 1 | $146.38+3$ |


| HORSE | ANGLE | GROUP | ROI | MEAN <br> $(0.1 \mathrm{~mm}$ <br> Aluminium $)$ |
| :---: | :---: | :---: | :---: | :---: |
| 25 | 0 | 60 | 1 | 136.7()+6 |
| 58 | () | 60 | 1 | 139.8577 |
| 31 | () | 60 | 1 | 128.5765 |
| 99 | 0 | 60 | 1 | 143.7509 |
| 57 | 1 | 60 | 1 | 157.9822 |
| 14 | 1 | 60 | 1 | 159.69()4 |
| 13 | 1 | 60 | 1 | 151.3665 |
| 37 | 1 | 60 | 1 | 166.7722 |
| 50 | 1 | 60 | 1 | 153.9359 |
| 55 | 1 | 60 | 1 | 170.8363 |
| 61 | 1 | 61 | 1 | 147.2954 |
| +1 | 0 | 60 | 2 | 129.3381 |
| +2 | 0 | 60 | 2 | 114.779t |
| 59 | 0 | 60 | 2 | 128.3025 |
| 25 | 0 | 60 | 2 | 111.8826 |
| 58 | 0 | 60 | 2 | 118.0783 |
| 31 | $1)$ | 60 | 2 | 114 |
| 99 | 0 | 60 | 2 | $135.88+2$ |
| 57 | 1 | 60 | 2 | $1+8.6299$ |
| 14 | 1 | 6 () | 2 | 15+.2527 |
| 13 | 1 | 60 | 2 | 150.7117 |
| 37 | 1 | 61 | 2 | 152.4164 |
| 50 | 1 | 60 | 2 | 139.1957 |
| 55 | 1 | 60 | 2 | 162.+235 |
| 60 | 1 | 60 | 2 | 138.5872 |
| +1 | 0 | 60 | 3 | $12+8754$ |
| +2 | () | 60 | 3 | 110.8256 |
| 59 | () | 60 | 3 | 121.5303 |
| 25 | () | 60 | 3 | 115.1922 |
| 58 | () | 60 | 3 | 117.7651 |
| 31 | () | 60 | 3 | 111.0783 |
| 99 | () | 60 | 3 | 127.4.351 |
| 57 | 1 | 60 | 3 | 16-+.7117 |
| 14 | 1 | 60 | 3 | 150.69() 4 |
| 13 | 1 | 60 | 3 | 1.37.9324 |
| 37 | 1 | 60 | 3 | 126.2562 |
| 5 () | 1 | 60 | 3 | $138.33+5$ |
| 55 | 1 | 60 | 3 | 150.5338 |
| 60 | 1 | 60 | 3 | 129.8327 |
| 11 | () | 60 | 4 | 120.9644 |
| $+2$ | () | 60 | $t$ | 117.6797 |
| 59 | () | 60 | $t$ | 131.4555 |
| 25 | () | 60 | $t$ | 107.452 |
| 58 | () | 60 | $t$ | 117.10996 |
| 31 | () | 60 | $t$ | 117.8719 |
| 99 | () | 60 | t | 126.4035 |
| 57 | 1 | 60 | $t$ | + 151.79 |
| 14 | 1 | 60 |  | $t \quad 160.3+52$ |
| 13 | 1 | 60 | + | 4150.4804 |


| HORSE | ANGLE | GROUP | ROl | MEAN <br> ( 0.1 mm <br> Aluminium) |
| :---: | :---: | :---: | :---: | :---: |
| 37 | 1 | 60 | $+$ | 117.4733 |
| 50 | 1 | 60 | $+$ | 158.6584 |
| 55 | 1 | 60 | $+$ | 173.1281 |
| 60 | 1 | 60 | $+$ | $130.0+6.3$ |
| +1 | 0 | 60 | 5 | 124.4982 |
| +2 | () | 60 | 5 | $130.2+2$ |
| 59 | 0 | 60 | 5 | 1.38 .2135 |
| 25 | () | 60 | 5 | 120.5267 |
| 58 | 0 | 60 | 5 | 125.1922 |
| 31 | 0 | 60 | 5 | 127.3772 |
| 99 | 0 | 60 | 5 | 137.5614 |
| 57 | 1 | 60 | 5 | 139.0071 |
| 14 | 1 | 60 | 5 | 160.2669 |
| 13 | 1 | 60 | 5 | 138.8221 |
| 37 | 1 | 60 | 5 | 130.8114 |
| 50 | 1 | 60 | 5 | $1+6.1922$ |
| 55 | 1 | 60 | 5 | $136.86+8$ |
| 60 | 1 | 60 | 5 | 131.2562 |


| I（）IL $\dagger$＋I | $\mathrm{s}^{\prime}$＇ | 2 | I | 06 | tI |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 928 c゙ナE | $\bigcirc$ | I | I | （）6 | tI |
| ＋（）＋C゙851 | $\bigcirc 9$ | 5 | I | （）9 | ＋1 |
| て＋86でっ1 | $\bigcirc$ | ＋ | I | （0） | ＋1 |
| ¢L8I てSI | $\bigcirc$ | E | I | （0） | tI |
| 6＋585S1 | $\bigcirc$ | 2 | I | （）9 | tI |
| とて8で091 | ¢ | I | I | （）9 | ＋1 |
| 699 で（）91 | $\varepsilon$ | 5 | I | （）9 | ＋1 |
| 2ธちぐ（）91 | $\varepsilon$ | ＋ | I | （0） | ＋1 |
| ＋（069（）S | ¢ | E | I | （）9 | ＋1 |
| Lてさで†可 | $\varepsilon$ | 2 | I | （0） | ＋I |
| ＋（）69\％ 6 － | E | 1 | I | （）9 | ＋1 |
| LEちで091 | $\bigcirc$ | ¢ | I | （0） | ＋I |
| ct $8 z^{\circ}+51$ | $\bigcirc$ | ＋ | I | （0） | ＋1 |
| $616 L 5+1$ | $\bigcirc$ | E | I | （0） | ＋1 |
| ＋2910 0 － | $\bigcirc$ | 2 | I | （0） | ＋1 |
| LE＋で8S1 | ¢゙て | 1 | I | （0） | ＋I |
|  | ¢゙¢ | ！ | I | （06 | \＆1 |
|  | ¢゙S | ＋ | 1 | O6 | ¢1 |
| L882＇1ヶ1 | $\bigcirc$ | E | I | （1）6 | EI |
| S98L 8 ＋I | ¢ | 2 | I | （0） | E1 |
| $16 \underline{0} 1+1$ | ¢ | I | I | （0） | EI |
| S0SI9SI | E | 5 | I | 106 | EI |
| S0S19S1 | $\varepsilon$ | ＋ | 1 | 06 | \＆I |
| LI66で「1 | $\varepsilon$ | $\varepsilon$ | 1 | （0） | ¢I |
| Lてて0てざ1 | E | 2 | I | （0） | ¿I |
| 9L81「で1 | 5 | 1 | 1 | （1） 6 | EI |
| 629＊6て1 | $\bigcirc$ | $\pm$ | 1 | （）6 | EI |
| 9S1 | －\％ | ＋ | I | 06 | EI |
| ＋9＋8ctl | $\bigcirc$ | E | I | 06 | $\varepsilon 1$ |
| I6E1 SSI | $\bigcirc$ | 2 | I | （0） | $\varepsilon 1$ |
| 6＋tL $0+1$ | $\bigcirc$ | I | I | 06 | EI |
| 6 El | ¢ | 5 | I | （0） | ¢ I |
| て19で9く1 | ¢ | ＋ | I | （0） | \＆I |
| ELLC゚をけ1 | ¢ | ¢ | I | （0） | EI |
| で6ことI | 5 | 2 | 1 | 09 | ¢1 |
| く8＋ごてら1 | $\bigcirc$ | I | 1 | （0） | ：I |
| 12788E1 | $\varepsilon$ | S | I | （0） | \＆ 1 |
| ＋（）8t 0 ） 1 | ¢ | ＋ | I | （0） | \＆ 1 |
| ＋で6 LEI | $\varepsilon$ | ¢ | I | （0） | \＆ 1 |
| LIIL＊） | $\varepsilon$ | 2 | I | （0） | EI |
| ¢99E゙IS1 | ¢ | 1 | 1 | （0） | EI |
| 6090）6E1 | $\bigcirc$ | 5 | I | （0） | EI |
| くらけでしけI | 5 | ＋ | I | （0） | SI |
|  | $\bigcirc$ | C | I | 09 | EI |
| ¢619 L | $\bigcirc$ | $\tau$ | I | （0） | $\varepsilon$ I |
| IItL＇8tI | $\bigcirc$ | I | 1 | （0） | $\varepsilon 1$ |
| $\begin{array}{r} \text { (um!u!umIV } \\ \text { uIUI () } \\ \text { N } \forall \exists \mathrm{EN} \\ \hline \end{array}$ | （umu）S¢IGV¢ | IO 4 | dొO¢Ы | B7ONV | 3S8OH |


| ¢9Lぐ8てI | $\varepsilon$ | 10 | （） | （09 | IS |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 68さで9てI | $\bigcirc$ | $\bigcirc 0$ | （） | （0） | IE |
| ¢9EL911 | －こ | $\dagger 0$ | （） | （）9 | IS |
| てEIOII | －\％ | ¢ 0 | （） | （）9 | IS |
| LI8L｀てI | $\bigcirc$ | $\overline{2}$ | （） | （0） | IS |
| 692İLてI | $\bigcirc$ | 10 | （） | （0） | IS |
| ¢018で， | $\bigcirc$ | ¢ 0 | （） | 06 | ¢て |
| ¢919 ${ }^{\text {LII }}$ | $\bigcirc$ | † 0 | （） | （1） | $\leq$ ¢ |
| S919 LII | $\bigcirc$ | ¢ 0 | （） | 06 | ¢て |
| ¢919＊LI | $\bigcirc$ | て 0 | （） | （0） | $\bigcirc$ |
| S919＊LI | $\bigcirc$ | 10 | （） | （0） | $\bigcirc$ |
| L＋て9＊）てI | ¢ | $\bigcirc 0$ | （） | 06 | $\leq$ ¢ |
| くナて9＊）て1 | E | $\dagger 0$ | （） | 06 | $\bigcirc$ |
| ¢9IでしII | ¢ | ¢ 0 | （） | 06 | $\leq$ ¢ |
| ¢ちtc゙911 | ¢ | て | （） | （0） | $\bigcirc$ |
| L9Sビくて1 | ¢ | 1 | （） | 06 | $\leq$ ¢ |
| こ9ç゙くで | －－ | $\underline{\square}$ | （） | 06 | $\bigcirc$ |
| 1＋80でて | －－ | $\dagger$ | （） | 06 | $\bigcirc$ |
| ¢LZ1\％611 | －¢ | E | 0 | 06 | $\bigcirc$ |
| ＋6ごぐく11 | $\bigcirc$ | $\checkmark$ | 0 | 06 | －て |
| ¢6けで8て1 | $\bigcirc$ | 1 | （） | 06 | －て |
| ¢19ぐ1て1 | $\bigcirc$ | $\bigcirc$ | （） | （）9 | $\bigcirc$ ¢ |
| 8SIOてII | $\bigcirc$ | ＋ | （） | （0） | － |
| 6こ9で911 | $\bigcirc$ | E | （） | （0） | $\bigcirc$ ¢ |
| ¢8tc゙sII | $\bigcirc$ | て | （） | （）9 | ¢て |
| 9čL＇9E1 | $\bigcirc$ | 1 | （） | （）9 | こて |
| L9てS＊）てI | ¢ | 5 | （） | （0） | －て |
| てらナ＊Lol | $\varepsilon$ | $\dagger$ | （） | 109 | －－ |
| 2261 511 | $\varepsilon$ | E | （） | 109 | － |
| 9788 III | ¢ | て | （） | （0） | ¢ $¢$ |
| $9+\left(0 L^{\circ} 9 \mathrm{Cl}\right.$ | ¢ | 1 | （） | （）9 | ¢て |
| $9+\angle 6 \angle 1 I$ | $\bigcirc$ | $\bigcirc$ | （） | （09 | －－ |
| ¢L8tcol | $\bigcirc$ | ＋ | （） | 09 | －¢ |
| でナ6で1 | ¢゙て | 5 | （） | （09 | －¢ |
| 80¢（）＇601 | $\bigcirc$ | て | （） | 109 | －－ |
| 861 ¢cı | $\bigcirc$ | I | （） | 09 | － |
| 9＋81＊） | $\bigcirc$ | 5 | I | 106 | ＋I |
| 8LIでGけ | 5 | ＋ | I | 06 | ＋I |
| 91I） 0 ¢ | $\bigcirc$ | E | 1 | O6 | tI |
| $9110{ }^{\text {a }}$－ | $\bigcirc$ | $\stackrel{\rightharpoonup}{2}$ | 1 | 106 | ＋I |
| 911001 | $\bigcirc$ | 1 | 1 | 106 | tI |
| $\angle+て 8 . \mathrm{ctI}$ | $\varepsilon$ | 5 | I | 106 | tI |
| L†て8．$¢$＋1 | ¢ | ＋ | I | （0） | tI |
|  | $\varepsilon$ | c | 1 | （0） | tI |
| L95c゙etI | ¢ | て | I | 106 | tI |
| $998+$＋cI | ¢ | 1 | I | 106 | tI |
| 6ttLis！ | －゙て | 5 | I | 106 | tI |
| ttol＇EtI | $\bigcirc$ | ＋ | I | 106 | tI |
| Ct（）LSt | $\bigcirc$ | S | I | 106 | tI |
|  | （umu）S＠IGV4 | IOt | dกO\％ | 3＇IONV | ESYOH |


| HORSE | ANGLE | GROUP | ROI | RADIUS (mm) | MEAN (0. I mm Aluminium) |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 31 | 60 | () | 2 | 3 | 114 |
| 31 | 60 | () | 3 | 3 | 111.0783 |
| 31 | 60 | () | 4 | 3 | 117.8719 |
| 31 | 60 | () | 5 | 3 | 127.3772 |
| 31 | 60 | 0 | 1 | 3.5 | 128.7256 |
| 31 | 60 | 0 | 2 | 3.5 | 115.4776 |
| 31 | 60 | () | 3 | 3.5 | 111.5515 |
| 31 | 60 | () | $+$ | 3.5 | 120.3615 |
| 31 | 60 | () | 5 | 3.5 | 127.8232 |
| 31 | 90 | () | 1 | 2.5 | 119.9681 |
| 31 | 90 | () | 2 | 2.5 | 111.6957 |
| 31 | 90 | 0 | 3 | 2.5 | 108.1333 |
| 31 | 90 | () | $+$ | 2.5 | 112.2087 |
| 31 | 90 | () | 5 | 2.5 | 128.3913 |
| 31 | 90 | () | 1 | 3 | 115.5248 |
| 31 | 90 | () | 2 | 3 | 115.5248 |
| 31 | 90 | () | 3 | 3 | 109.4588 |
| 31 | 90 | () | $t$ | 3 | 109.4588 |
| 31 | 90 | () | 5 | 3 | 109.4588 |
| 31 | 90 | 0 | 1 | 3.5 | 111.2148 |
| 31 | 90 | () | 2 | 3.5 | 111.2148 |
| 31 | 90 | () | 3 | 3.5 | $111.21+8$ |
| 31 | 90 | () | $+$ | 3.5 | 111.2148 |
| 31 | 90 | () | 5 | 3.5 | 121.8632 |
| 37 | 60 | 1 | 1 | 2.5 | 165.25 |
| 37 | 60 | 1 | 2 | 2.5 | $150.23+7$ |
| 37 | 60 | 1 | 3 | 2.5 | 123.1327 |
| 37 | 60 | 1 | $+$ | 2.5 | $115.8+69$ |
| 37 | 60 | 1 | 5 | 2.5 | 129.8725 |
| 37 | 60 | 1 | 1 | 3 | 166.7722 |
| 37 | 60 | 1 | 2 | 3 | $152.416+$ |
| 37 | 60 | 1 | 3 | 3 | 126.2562 |
| 37 | 60 | 1 | $+$ | 3 | 117.4733 |
| 37 | 60 | 1 | 5 | 3 | 130.8114 |
| 37 | 60 | 1 | 1 | 3.5 | 169.3958 |
| 37 | 60 | 1 | 2 | 3.5 | $15+.24$ ()1 |
| 37 | 60 | 1 | 3 | 3.5 | 128.248 |
| 37 | 60 | 1 | + | 3.5 | 120.248 |
| 37 | 60 | 1 | 5 | 3.5 | 132.058 |
| 37 | 9() | 1 | 1 | 2.5 | 148.7971 |
| 37 | 9() | 1 | 2 | 2.5 | $1+7.7159$ |
| 37 | 9() | 1 | 3 | 2.5 | 128.4087 |
| 37 | 9() | 1 | + | + 2.5 | 113.7()+3 |
| 37 | 90 | 1 | 5 | 5 | 121.3+78 |
| 37 | 90 | 1 |  | - 3 | 1 $1+7.8557$ |
| 37 | 9() | 1 | - 2 | 23 | 146.167 |
| 37 | 90 | 1 | , 3 | 3 | 129.7464 |
| 37 | 9() | 1 | + | 4 | 11+233 |
| 37 | 90 | 1 | 1 5 | 5 | 3 11+233 |


| HORSE | ANGLE | GROUP | ROI | RADIUS (mm) | MEAN <br> (0. 1 mm <br> Aluminium) |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 37 | 90 | 1 | 1 | 3.5 | 133.5226 |
| 37 | 90 | 1 | 2 | 3.5 | 133.5226 |
| 37 | 90 | 1 | 3 | 3.5 | 133.5226 |
| 37 | 90 | 1 | $+$ | 3.5 | 133.5226 |
| 37 | 90 | 1 | 5 | 3.5 | 121.1729 |
| +1 | 60 | () | 1 | 2.5 | 125.6599 |
| +1 | 60 | 0 | 2 | 2.5 | 128.7157 |
| $+1$ | 60 | () | 3 | 2.5 | 120.7614 |
| $+1$ | 60 | () | $+$ | 2.5 | $118.228+$ |
| $+1$ | 60 | 0 | 5 | 2.5 | 122.9594 |
| +1 | 60 | 0 | 1 | 3 | 126.21 |
| +1 | 60 | () | 2 | 3 | 129.3381 |
| $+1$ | 60 | () | 3 | 3 | $12+8754$ |
| +1 | 60 | () | $+$ | 3 | $120.96+4$ |
| $+1$ | 60 | () | 5 | 3 | 12+.4982 |
| +1 | 60 | () | 1 | 3.5 | 127.0185 |
| $+1$ | 60 | 0 | 2 | 3.5 | 130.3509 |
| +1 | 60 | 0 | 3 | 3.5 | 127.314 |
| +1 | 60 | 0 | $+$ | 3.5 | 122.7573 |
| +1 | 60 | () | 5 | 3.5 | 126.905 |
| +1 | 90 | 0 | 1 | 2.5 | 128.5362 |
| $+1$ | 90 | () | 2 | 2.5 | $12+.7+2$ |
| +1 | 90 | 0 | 3 | 2.5 | $126.6+35$ |
| $+1$ | 90 | 0 | $+$ | 2.5 | 129.7507 |
| +1 | 90 | () | 5 | 2.5 | 1+0.22.32 |
| $+1$ | 90 | () | 1 | 3 | 127.284 |
| +1 | 90 | () | 2 | 3 | 122.7809 |
| $+1$ | 90 | () | 3 | 3 | 126.6 |
| $+1$ | 90 | () | $+$ | 3 | 126.6 |
| +1 | 90 | () | 5 | 3 | 126.6 |
| $+1$ | 90 | () | 1 | 3.5 | 123.2916 |
| +1 | 90 | () | 2 | 3.5 | 12.3 .2916 |
| 41 | 90 | () | 3 | 3.5 | 123.2916 |
| +1 | 90 | () | $+$ | 3.5 | 123.2916 |
| +1 | 90 | () | 5 | 3.5 | 139.1158 |
| +2 | 60 | () | 1 | 2.5 | 129.92 .39 |
| +2 | 60 | () | 2 | 2.5 | 111.3553 |
| +2 | 60 | () | 3 | 2.5 | 108.198 |
| +2 | 60 | () | $+$ | 2.5 | 116.2081 |
| +2 | 60 | () | 5 | 2.5 | 129.3858 |
| +2 | 60 | () | 1 | 3 | 131.0498 |
| +2 | 60 | () | 2 | 3 | 114.7794 |
| $+2$ | 60 | () | 3 | 3 | 110.8256 |
| +2 | 60 | () | $+$ | 3 | 117.6797 |
| +2 | 60 | () | 5 | 3 | 130.242 |
| +2 | 60 | () | 1 | 3.5 | 131.715 |
| +2 | 60 | () | ) 2 | 3.5 | $116.6+91$ |
| $+2$ | 60 | () | ) 3 | 3.3 .5 | $112.08+4$ |
| +2 | 60 | () | + | + 3.5 | 119.9631 |


| HORSE | ANGLE | GROUP | ROI | RADIUS (mm) | MEAN <br> (0. 1 mm <br> Aluminium) |
| :---: | :---: | :---: | :---: | :---: | :---: |
| +2 | 60 | () | 5 | 3.5 | 131.4617 |
| +2 | 90 | () | 1 | 2.5 | 116.229 |
| +2 | 90 | () | 2 | 2.5 | 113.8174 |
| +2 | 90 | () | 3 | 2.5 | 106.1072 |
| +2 | 90 | () | $t$ | 2.5 | 108.3333 |
| +2 | 90 | () | 5 | 2.5 | 131.078 .3 |
| +2 | 90 | () | 1 | 3 | $116.29+8$ |
| $+2$ | 90 | 0 | 2 | 3 | 113.567 |
| +2 | 90 | () | 3 | 3 | $10+8557$ |
| +2 | 90 | () | $t$ | 3 | $10+.035$ |
| +2 | 90 | () | 5 | 3 | 104.035 |
| +2 | 90 | () | 1 | 3.5 | 110.7817 |
| $+2$ | 90 | () | 2 | 3.5 | 110.7817 |
| +2 | 90 | () | 3 | 3.5 | 110.7817 |
| +2 | 90 | () | 4 | 3.5 | 101.7098 |
| +2 | 90 | () | 5 | 3.5 | 129.6677 |
| 5() | 60 | 1 | 1 | 2.5 | 153.8673 |
| 50 | 60 | 1 | 2 | 2.5 | 138.6275 |
| 50 | 60 | 1 | 3 | 2.5 | 137.2857 |
| 50 | 60 | 1 | $t$ | 2.5 | 157.23.47 |
| 50 | 60 | 1 | 5 | 2.5 | 1+7.148 |
| 50 | 60 | 1 | 1 | 3 | 153.9359 |
| 5() | 60 | 1 | 2 | 3 | 139.1957 |
| 50 | 60 | 1 | 3 | 3 | 138.3345 |
| 50 | 60 | 1 | $t$ | 3 | $158.658 t$ |
| 50 | 60 | 1 | 5 | 3 | $1+6.1922$ |
| 50 | 60 | 1 | 1 | 3.5 | $15+.0185$ |
| 5() | 60 | 1 | 2 | 3.5 | 1.39 .3 .377 |
| 50 | 60 | 1 | 3 | 3.5 | 139.4.301 |
| 5() | 60 | 1 | $+$ | 3.5 | 161.438 |
| 5() | 60 | 1 | 5 | 3.5 | $1+5.8628$ |
| 50 | 90 | 1 | 1 | 2.5 | 127.3565 |
| 50 | 90 | 1 | 2 | 2.5 | 125.3362 |
| 50 | 90 | 1 | 3 | 2.5 | 121.2551 |
| 50 | 90 | 1 | $+$ | 2.5 | 138.9971 |
| 50 | 90 | 1 | 5 | 2.5 | 136.5565 |
| 50 | 9() | 1 | 1 | 3 | 126.9072 |
| 50 | 90 | 1 | 2 | 3 | $123.3+4.3$ |
| 50 | 90 | 1 | 3 | 3 | $120.87+2$ |
| 50 | 90 | 1 | $+$ | 3 | 138.32 .37 |
| $5)$ | 9() | 1 | 5 | 3 | 138.32 .37 |
| 50 | $9(0$ | 1 | 1 | 3.5 | 126.4387 |
| 50 | 9() | 1 | 2 | 3.5 | 121.3268 |
| 50 | 9() | 1 | 3 | 3.5 | 120.2905 |
| 50 | 90 | 1 | 4 | 3.5 | 137.177 |
| $5)$ | 90 | 1 | 5 | 3.5 | 135.5688 |
| 55 | 60 | 1 | 1 | 2.5 | 169.6205 |
| 55 | 60 | 1 | 2 | 2.5 | 162.9897 |
| 55 | 60 | 1 | 3 | - 2.5 | 151.1385 |


| †tIで0） | c | 2 | 1 | （）6 | LS |
| :---: | :---: | :---: | :---: | :---: | :---: |
| て＋L8でご | $\varepsilon$ | 1 | I | （）6 | LS |
| ¢¢8E．E¢I | $\bigcirc$ | $\bigcirc 1$ | I | （）6 | LS |
| 82680sI | $\bigcirc$ | t | 1 | （）6 | LS |
| 91It8－1 | $\bigcirc$ | ¢ | 1 | （）6 | LS |
| てけでてくす | $\bigcirc$ | て | 1 | （1） 6 | LS |
| ¢Lてぐくら1 | $\bigcirc$ | 1 | 1 | （）6 | LS |
| てE¢98E1 | $\bigcirc$ | $\bigcirc$ | I | （）9 | LS |
| ¢8＋C゙くら1 | $\bigcirc$ | $\dagger$ ， | I | （）9 | LS |
| －859 ${ }^{\text {c91 }}$ | $\bigcirc$ | $\varepsilon$ | I | （0） | LS |
| 65 c80 01 | $\bigcirc$ | て | I | （）9 | LS |
| 885 C゙6SI | $\bigcirc$ | 1 | I | （0） | LS |
| ILOO） 6 SI | S | 5 | I | （0） | LS |
| 6L＇ISI | $\varepsilon$ | $\dagger$ | I | （0） | LS |
| LIIL＇9 ${ }^{\text {a }}$ | $\varepsilon$ | c | I | （0） | LS |
| 6629 8t1 | E | て | I | （0） | LS |
| 2286 LSI | $\varepsilon$ | 1 | 1 | （0） | LS |
| ＋9589 ${ }^{\circ}$ | $\bigcirc$ | $\bigcirc$ | I | （0） | LS |
|  | $\bigcirc$ | $\dagger$ | I | （0） | LS |
| 6Sc゙091 | $\bigcirc$ | $\varepsilon$ | I | （0） | LS |
| Iて8でらけ1 | $\bigcirc$ | て | 1 | （0） | LS |
| 69L（）＇tS1 | $\bigcirc$ | I | 1 | （0） | LS |
| 8816．てZ1 | $\bigcirc$ | 5 | 1 | （06 | 5 |
| 80909 9 1 | $\bigcirc$ | ＋ | I | （06 | S |
| 8090 （0）${ }^{\text {c }}$ | $\subseteq \mathcal{L}$ | ¢ | I | （）6 | 5 |
| 8090 （0） 91 | ¢ֻ | て | 1 | （1） | 5 |
| 8090 （0） 9 E | Sc | I | 1 | （1）6 | 5 |
| 6＋L9．8E1 | ¢ | $\bigcirc$ | 1 | （1）6 | 5 |
| $6+\angle 9.851$ | ¢ | $\dagger$ | 1 | 06 | 5 |
| てLEで8て1 | ¢ | E | 1 | （1） | 5 |
| ＋81 S゙1 $\dagger 1$ | c | て | 1 | 06 | 5 |
| ＋8IS゙ItI | $\mathcal{E}$ | 1 | 1 | 06 | 5 |
| 9 956．でI | $\bigcirc$ | 5 | I | 06 | S |
| S9560） 1 | $\bigcirc$ | ＋ | I | 06 | 5 |
| IL6L 82I | $\bigcirc$ | 5 | I | 06 | 5 |
| ILI ItI | ごて | て | I | （0） | 5 |
| tosset | $\bigcirc$ | 1 | I | （06 | 5 |
| csoz＇9E1 | $\bigcirc$ | 5 | 1 | 09 | 5 |
| Lt6S゙LLI | $\bigcirc$ | ＋ | 1 | 09 | 5 |
| でです | ¢ | $\varepsilon$ | I | 09 | 5 |
| しててごく91 | $\bigcirc$ | て | I | （0） | SS |
| Cs0802 | $\bigcirc$ | 1 | I | （0） | 5 |
| 8＋98．9E1 | ¢ | 5 | 1 | 09 | 5 |
| 18219LI | $\varepsilon$ | ＋ | 1 | （）9 | 5 |
| 8 ccsosi | ¢ | E | 1 | （）9 | 5 |
| çででて91 | $\varepsilon$ | ＜ | I | （）9 | 5 |
| ¢9E80しI | ¢ | 1 | I | （）9 | 5 |
| IZ8t＊9EI | $\bigcirc$ | $\leq$ | I | （）9 | 5 |
|  | $\bigcirc$ | $\dagger$ | 1 | 09 | S |
|  | （umu）SOIGV¢ | IO | dกO\％ | 日70n | ヨSEOH |


| HORSE | ANGLE | GROUP | ROI | RADIUS (mm) | MEAN <br> (0. 1 mm <br> Aluminium) |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 57 | 90 | 1 | 3 | 3 | 156.4371 |
| 57 | 90 | 1 | $t$ | 3 | 151.8 |
| 57 | 90 | 1 | 5 | 3 | 151.8 |
| 57 | 90 | 1 | 1 | 3.5 | 152.1128 |
| 57 | 90 | 1 | 2 | 3.5 | 148.3955 |
| 57 | 90 | 1 | 3 | 3.5 | $153.85+1$ |
| 57 | 90 | 1 | $+$ | 3.5 | 152.6075 |
| 57 | 90 | 1 | 5 | 3.5 | 132.4165 |
| 58 | 60 | () | 1 | 2.5 | 138.8265 |
| 58 | 60 | () | 2 | 2.5 | 118.1173 |
| 58 | 60 | () | 3 | 2.5 | 11+.4.37 |
| 58 | 60 | () | $+$ | 2.5 | 115.1939 |
| 58 | 60 | 0 | 5 | 2.5 | 125.2653 |
| 58 | 60 | () | 1 | 3 | 139.8577 |
| 58 | 60 | () | 2 | 3 | 118.0783 |
| 58 | 60 | 0 | 3 | 3 | 117.7651 |
| 58 | 60 | 0 | $+$ | 3 | 117.0996 |
| 58 | 60 | () | 5 | 3 | 125.1922 |
| 58 | 60 | () | 1 | 3.5 | 139.67() 2 |
| 58 | 60 | 0 | 2 | 3.5 | 119.5198 |
| 58 | 60 | () | 3 | 3.5 | 118.6385 |
| 58 | 60 | 0 | $+$ | 3.5 | $120.66+9$ |
| 58 | 60 | 0 | 5 | 3.5 | 125.10633 |
| 58 | 90 | () | 1 | 2.5 | $121.28+1$ |
| 58 | 90 | () | 2 | 2.5 | 113.8377 |
| 58 | 90 | () | 3 | 2.5 | 112.8319 |
| 58 | 90 | () | $+$ | 2.5 | $115.23+8$ |
| 58 | 90 | () | 5 | 2.5 | 118.4261 |
| 58 | 90 | () | 1 | 3 | 120.701 |
| 58 | 90 | () | 2 | 3 | $113.35+6$ |
| 58 | 90 | () | 3 | 3 | 112.0825 |
| 58 | 90 | () | $+$ | 3 | 112.767 |
| 58 | 90 | () | 5 | 3 | 112.767 |
| 58 | 9() | () | 1 | 3.5 | 11.3 .9398 |
| 58 | 90 | () | 2 | 3.5 | 113.9398 |
| 58 | 9() | () | 3 | 3.5 | 113.9398 |
| 58 | 90 | () | ) + | 3.5 | 113.9398 |
| 58 | 9() | () | 5 | 3.5 | $117.9+89$ |
| 59 | 60 | () | 1 | 2.5 | $1+5.7817$ |
| 59 | 60 | () | ) 2 | 2.2 .5 | 125.7868 |
| 59 | 60 | () | 3 | 3 2.5 | 119.3299 |
| 59 | 60 | () | 4 | + 2.5 | 128.7005 |
| 59 | 60 | () | ) 5 | 52.5 | 139.665 |
| 59 | 60 | () | 1 | 3 | $1+6.38+3$ |
| 59 | 60 | () | ) 2 | 2 3 | 128.3025 |
| 59 | 60 | () | ) 3 | 3 | 121.5303 |
| 59 | 60 | () | ) + | + 3 | 131.4555 |
| 59 | 60 | () | ) 5 | 5 3 | 138.2135 |
| 59 | 60 | (0) | ) 1 | 1 3.5 | 1+6.4()) |


| HORSE | ANGLE | GROUP | ROI | RADIUS (mm) | MEAN <br> (0. 1 mm <br> Aluminium) |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 59 | 60 | 0 | 2 | 3.5 | 130.124 |
| 59 | 60 | 0 | 3 | 3.5 | 121.9921 |
| 59 | 60 | () | $+$ | 3.5 | $132.3+56$ |
| 59 | 60 | () | 5 | 3.5 | 137.7599 |
| 59 | 90 | 0 | 1 | 2.5 | 131.2899 |
| 59 | 90 | () | 2 | 2.5 | 124.79+2 |
| 59 | 90 | () | 3 | 2.5 | $11+8.837$ |
| 59 | 90 | 0 | $+$ | 2.5 | 117.8319 |
| 59 | 90 | () | 5 | 2.5 | $1.3+.5652$ |
| 59 | 90 | 0 | 1 | 3 | 121.5057 |
| 59 | 90 | 0 | 2 | 3 | 121.5057 |
| 59 | 90 | () | 3 | 3 | 121.5057 |
| 59 | 90 | () | $+$ | 3 | 121.5057 |
| 59 | 90 | 0 | 5 | 3 | 121.5057 |
| 59 | 90 | () | 1 | 3.5 | 120.2667 |
| 59 | 90 | () | 2 | 3.5 | 120.2667 |
| 59 | 90 | 0 | 3 | 3.5 | 120.2667 |
| 59 | 90 | () | $+$ | 3.5 | 120.2667 |
| 59 | 90 | () | 5 | 3.5 | 132.8539 |
| 60 | 60 | 1 | 1 | 2.5 | $1+5.7(1) 26$ |
| 60 | 60 | 1 | 2 | 2.5 | 137.1333 |
| 60 | 60 | 1 | 3 | 2.5 | 128.9231 |
| 60 | 60 | 1 | $+$ | 2.5 | 128.7128 |
| 60 | 60 | 1 | 5 | 2.5 | 131.3179 |
| 60 | 60 | 1 | 1 | 3 | 1+7.2954 |
| 60 | 60 | 1 | 2 | 3 | 1.38 .5872 |
| 60 | 60 | 1 | 3 | 3 | 129.8327 |
| 60 | 60 | 1 | $+$ | 3 | $130.0+6.3$ |
| 60 | 60 | 1 | 5 | 3 | 1.31 .2562 |
| 60 | 60 | 1 | 1 | 3.5 | $1+7.5937$ |
| 60 | 60 | 1 | 2 | 3.5 | 1+1.2296 |
| 60 | 60 | 1 | 3 | 3.5 | 130.1715 |
| 60 | 60 | 1 | $+$ | 3.5 | $1.32 .79+2$ |
| 60 | 60 | 1 | 5 | 3.5 | 131.1372 |
| 60 | 90 | 1 | 1 | 2.5 | 132.0696 |
| 60 | 90 | 1 | 2 | 2.5 | 131.6754 |
| 60 | 90 | 1 | 3 | 2.5 | 119.5304 |
| 60 | 90 | 1 | 4 | 2.5 | 123.113 |
| 60 | 90 | 1 | 5 | 2.5 | 122.8957 |
| 60 | 90 | 1 | 1 | 3 | 131.9052 |
| 60 | 90 | 1 | 2 | 3 | $130.28+5$ |
| 60 | 90 | 1 | 3 | 3 | 118.4804 |
| 60 | 90 | 1 | 4 | 3 | 121.25 .36 |
| 60 | 90 | 1 | 5 | 3 | 121.25 .36 |
| 60 | 90 | 1 | 1 | 3.5 | 126.0 .336 |
| 60 | 90 | 1 | 2 | 3.5 | 126.03 .36 |
| 60 | 90 | 1 | 3 | 3.5 | 126.03 .36 |
| 60 | 90 |  | 4 | + 3.5 | $119.2+96$ |
| 60 | 90 | 1 | 5 | 53.5 | 122.2752 |


| HORSE | ANGLE | GROUP | ROI | RADIUS (mm) | MEAN <br> ( 0.1 mm <br> Aluminium) |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 99 | 60 | 0 | 1 | 2.5 | 143.2915 |
| 99 | 60 | () | 2 | 2.5 | 13+.1457 |
| 99 | 60 | () | 3 | 2.5 | $12+2965$ |
| 99 | 60 | 0 | $+$ | 2.5 | 122.7588 |
| 99 | 60 | 0 | 5 | 2.5 | 137.3015 |
| 99 | 60 | () | 1 | 3 | $1+3.7509$ |
| 99 | 60 | () | 2 | 3 | $135.88+2$ |
| 99 | 60 | () | 3 | 3 | 127.4.351 |
| 99 | 60 | () | $+$ | 3 | 126.4035 |
| 99 | 60 | () | 5 | 3 | 137.5614 |
| 99 | 60 | 0 | 1 | 3.5 | $1+4.4+3.3$ |
| 99 | 60 | () | 2 | 3.5 | 1.38.4855 |
| 99 | 60 | () | 3 | 3.5 | 129.7678 |
| 99 | 60 | () | $+$ | 3.5 | $127.5+62$ |
| 99 | 60 | () | 5 | 3.5 | 1.37 .7678 |
| 99 | 90 | () | 1 | 2.5 | 125.4116 |
| 99 | 90 | () | 2 | 2.5 | 127.7275 |
| 99 | 90 | () | 3 | 2.5 | 117.7391 |
| 99 | 90 | () | $+$ | 2.5 | 116.2493 |
| 99 | 90 | () | 5 | 2.5 | 130.0928 |
| 99 | 90 | 0 | 1 | 3 | 125.468 |
| 99 | 90 | () | 2 | 3 | 126.8351 |
| 99 | 90 | () | 3 | 3 | $117.00+1$ |
| 99 | 90 | () | $+$ | 3 | $11+.6928$ |
| 99 | 90 | () | 5 | 3 | 11+.6928 |
| 99 | 90 | () | 1 | 3.5 | 120.1827 |
| 99 | 90 | () | 2 | 3.5 | 120.1827 |
| 99 | 90 | () | 3 | 3.5 | 120.1827 |
| 99 | 90 | () | $+$ | 3.5 | 120.1827 |
| 99 | 90 | () | 5 | 3.5 | 128.2376 |

## APPENDIX 2

## 1. Dorsal data

Tabulated data prior to statistical analysis

| Average of mean |  | ROI | ROI | ROI | ROI | ROI |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| angle | group | 1 | 2 | 3 | + | 5 |
| 60 | () | 112.3291857 | $93.6366+286$ | 89.33692857 | $88.8+59$ | 98.25855714 |
|  | 1 | 132.484 | 113.5861571 | 110.3599571 | $109.2511+29$ | 117.8281571 |
| 60) Total |  | 122.4065929 | 103.6114 | $99.8+8+4286$ | 99.04852143 | $108.0+33571$ |
| 65 | () | 122.0319714 | $102.1353+29$ | $97.52+88571$ | $96.606871+3$ | $109.9217+29$ |
|  | 1 | $131.459+1+3$ | $11+.77251+3$ | $112.2377+29$ | 110.7317286 | 119.130+571 |
| 65 Total |  | 126.7456929 | 108.4539286 | 104.8813143 | 103.6693 | 11+.5261 |
| 70) | () | 122.49+1286 | 108.0305 | $105.57+4857$ | 101.9334 | 113.9898286 |
|  | 1 | 132.3269 | 125.4987286 | 121.716.3286 | 118.0472714 | 122.1662571 |
| 7 () Total |  | 127.41051+3 | $116.76+61+3$ | $113.6+5+() 71$ | 109.99033357 | 118.078()$+29$ |
| 75 | () | 120.8t+471t | $108.176+429$ | 106.78+3714 | 104.27+2286 | 116.37+9714 |
|  | 1 | $128.92871+3$ | $125.93051+3$ | 123.7682 | 120.6786571 | $121.353+571$ |
| 75 Total |  | $12+.8865929$ | $117.053+786$ | 115.2762857 | $112.476++29$ | $118.86+21+3$ |
| 80 | () | 117. $+1+4+29$ | 109.1298857 | 107.5098714 | 105.7973571 | $115.30+8571$ |
|  | 1 | 129.3876286 | 131.7882143 | $126.7072+29$ | 120.7081 | 121.3181 |
| 8 80 Total |  | 123.4010.357 | $120 .+5905$ | 117.1085571 | 113.2527286 | $118.311+786$ |
| 85 | () | 123.93638557 | 117.8306+29 | 115.21+1+29 | 113.0789571 | $12.3 .209+286$ |
|  | 1 | 135.4771571 | $1+1.89221+3$ | 134.6035571 | $128.86+81+3$ | 128.1896857 |
| 85 Total |  | 129.7067714 | 129.861+286 | 124.90885 | 120.9718857 | 125.6995571 |
| 90 | () | 12+.395+857 | 119.9293714 | 116.7768 | 115.8229143 | 126.6137143 |
|  | 1 | $135.86 .391+3$ | 1+4.0953714 | 135.3377571 | 131.0199+29 | $130 .+559571$ |
| 9() Total |  | 130.1297 | 132.012.371-t | 126.0572786 | 123. $+21+286$ | 128.53+8357 |

### 1.1 Main effect of angle

Pairwise comparisons comparing the main effect of angle when ROl's are in a dorsal position.
Dependent Variable: MEAN

| Angle (I) | Angle (J) | Mcan difference (I-J) | Standard error | Significance ${ }^{\text {a }}$ |
| :---: | :---: | :---: | :---: | :---: |
| 60 | 65 | -5.064* | 1.267 | ().()02 |
|  | 70 | -10.586* | 1.267 | <().0) 1 |
|  | 75 | -11.120* | 1.267 | <().0) 1 |
|  | 80 | -11.915* | 1.267 | $<(0.0) 1$ |
|  | 85 | -19.638* | 1.267 | <().0) 1 |
|  | 90 | -21.4.39* | 1.267 | <().0) 1 |
| 65 | 60 | 5.064* | 1.267 | (0.0)2 |
|  | 70 | -5.523* | 1.267 | <().0) 1 |
|  | 75 | -6.056* | 1.267 | $<(0.00)$ |
|  | 80 | -6.851* | 1.267 | <().)(0) |
|  | 85 | -1+.574* | 1.267 | <().0) 1 |
|  | 90 | -16.376* | 1.267 | <().0) 1 |
| 70 | 60 | 10.586* | 1.267 | <().0) 1 |
|  | 65 | 5.523* | 1.267 | <().()) 1 |
|  | 75 | $-5.34{ }^{\text {b }}$ | 1.267 | 1.0)() |
|  | 80 | $-1.329^{\text {b }}$ | 1.267 | $1.000)$ |
|  | 85 | -9.(0)2* | 1.267 | $<(0.0)$ ) |
|  | 9() | -10.853* | 1.267 | <().)() 1 |
| 75 | 60 | 11.120* | 1.267 | <().0) 1 |
|  | 65 | 6.056* | 1.267 | <().0) ${ }^{\text {l }}$ |
|  | 7) | (0.5.34 | 1.267 | $1.000)$ |
|  | 80 | -().795 ${ }^{\text {b }}$ | 1.267 | $1.000)$ |
|  | 85 | -8.518* | 1.267 | $<(0.0) 1$ |
|  | 9() | -10.32()* | 1.267 | <() ()0) |
| 80 | 60 | 11.195* | 1.267 | <().0) ${ }^{\text {a }}$ |
|  | 65 | 6.851* | 1.267 | <().0) 1 |
|  | 70 | $1.329^{\text {b }}$ | 1.267 | $1.000)$ |
|  | 75 | $0.795{ }^{\text {b }}$ | 1.267 | $1.000)$ |
|  | 85 | -7.72.3* | 1.267 | <().)(0) |
|  | 90 | -9.525* | 1.267 | <().)() 1 |
| 85 | 60 | 19.6.38* | 1.267 | <().0) 1 |
|  | 65 | 1+.57+* | 1.267 | <().0) 1 |
|  | 7() | 9.052* | 1.267 | <().)(0) |
|  | 75 | 8.518* | 1.267 | <().)() 1 |
|  | 80 | 7.72.3* | 1.267 | <().()) 1 |
|  | 9() | $-1.801^{\text {b }}$ | 1.267 | $1.000)$ |
| 9() | 60 | 21.4.39* | 1.267 | <().0) 1 |
|  | 65 | 16.376* | 1.267 | <().0) 1 |
|  | 7) | 10.853* | 1.267 | <().0) 1 |
|  | 75 | 10.32)* | 1.267 | <().0) 1 |
|  | 80 | 9.525* | 1.267 | <().()0) |
|  | 85 | $1.801^{\text {b }}$ | 1.267 | $1.000)$ |

Based on estimated marginal means
*. The mean difference is significant at the 0.5 level
a. Adjustment for multiple comparisons: Bonferroni
b. An estimate of the modified population marginal mean (l)

### 1.1.1 Angle at one level of ROI

Pairwise comparisons to compare angle means at each level of ROI when ROI's are in a dorsal position.

Dependent Variable: MEAN

| ROI | (I) ANGLE | (J) ANGLE | Mcan Difference (I-J) | Std. Error | t value | Degrees of freedom | Significance ${ }^{\text {a }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 61 | 65 | -4.339 | 2.834 | -1.531 | +()8 | 0.334 |
|  |  | 7) | -5.)()+ | 2.834 | -1.766 | +()8 | 1.000 |
|  |  | 75 | -2.480 | $2.83+$ | -(0.875 | +()8 | 1.000 |
|  |  | 80 | -0.99+ | $2.83+$ | -0.351 | +()8 | $1.000)$ |
|  |  | 85 | -7.3()) | $2.83+$ | -2.576 | $4(1)$ | 0.217 |
|  |  | 9() | -7.72.3 | $2.83+$ | -2.726 | +()8 | (0.1+1 |
|  | 65 | 60 | +..3.39 | $2.83+$ | 1.531 | +()8 | 1.000 |
|  |  | 71 | -0.655 | $2.83+$ | -0.235 | +(1) | 1.000 |
|  |  | 75 | 1.859 | 2.834 | 0.656 | +()8 | 1.000 |
|  |  | 8() | $3.3+5$ | $2.83+$ | 1.181 | +()8 | 1.000 |
|  |  | 85 | -2.961 | $2.83+$ | -1.0+5 | +()8 | 1.000 |
|  |  | $9(1)$ | -3.38t | $2.83+$ | -1.19t | +(1) | 1.000 |
|  | 7) | 60 | 5.004 | $2.83+$ | 1.766 | +()8 | 1.000 |
|  |  | 65 | 0.665 | $2.83+$ | 0.235 | +(1) | 1.000 |
|  |  | 75 | 2.252 | $2.83+$ | 0.795 | +()8 | 1.000 |
|  |  | 80 | +.()1() | $2.83+$ | 1.415 | +(1) | 1.000 |
|  |  | 85 | -2.296 | 2.834 | -0.81() | +()8 | 1.000 |
|  |  | 90 | -2.719 | $2.83+$ | -0.960 | +(1) | 1.000 |
|  | 75 | 60 | 2.480 | $2.83+$ | 0.875 | +()8 | 1.000 |
|  |  | 65 | -1.859 | $2.83+$ | -0.656 | +()8 | 1.000 |
|  |  | 71 | -2.252 | $2.83+$ | -0.795 | +()8 | 1.000 |
|  |  | 80 | 1.486 | $2.83+$ | 0.52t | +()8 | 1.000 |
|  |  | 85 | -4.820) | $2.83+$ | -1.701 | +(1) | 1.000 |
|  |  | 9() | -5.24 | 2.834 | -1.850) | +()8 | 1.000 |
|  | 80 | 60 | 0.994 | $2.83+$ | 0.351 | +(1) | 1.000 |
|  |  | 65 | -3.33+ | $2.83+$ | -1.177 | +()8 | 1.000 |
|  |  | 70 | -4.) 10 | $2.83+$ | -1.415 | +()8 | 1.000 |
|  |  | 75 | -1.486 | 2.834 | -(0.52t | +()8 | 1.000 |
|  |  | 85 | $-6.306$ | 2.83. | -2.225 | +()8 | 0.558 |
|  |  | 9() | -6.729 | 2.834 | -2.375 | +()8 | 0.378 |
|  | 85 | 60 | $7.300)$ | 2.834 | 2.576 | +()8 | ().217 |
|  |  | 65 | 2.961 | $2.83+$ | 1.045 | +188 | 1.000 |
|  |  | 7) | 2.296 | 2.83 t | (0.810 | +()8 | 1.000 |
|  |  | 75 | -1.486 | $2.83+$ | -(0.524 | +()8 | 1.000 |
|  |  | 80 | 6.306 | $2.83+$ | 2.225 | +()8 | 0.558 |
|  |  | 9() | -().42.3 | 2.834 | -().149 | +()8 | 1.000 |
|  | 9() | 60 | 7.723 | $2.83+$ | 2.726 | +()8 | ().1+1 |
|  |  | 65 | $3.38+$ | $2.83+$ | $1.19+$ | +()8 | 1.000 |
|  |  | 7) | 2.719 | $2.83+$ | (0.960 | +()8 | 1.000 |
|  |  | 75 | $5.2+3$ | $2.83+$ | 1.850 | +()8 | 1.000 |
|  |  | 80 | 6.729 | $2.83+$ | 2.375 | $4(18$ | 0.378 |
|  |  | 85 | (). +23 | $2.83+$ | ().14) | +()8 | 1.000 |
| 2 | 60 | 65 | -4.8+3 | 2.83 .4 | -1.709 | +()8 | $1.000)$ |
|  |  | 7 () | -13.154 | $2.83+$ | -4.6+2 | 408 | <().0) 1 |


|  |  | 75 | $-13 .+42$ | 2.8 .34 | $-4.74+$ | 4() 8 | <().()) ${ }^{\text {( }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 8() | -16.8+8 | 2.834 | -5.946 | +()8 | <().()()] |
|  |  | 85 | -26.25() | 2.834 | -9.264 | +()8 | $<() .()()]$ |
|  |  | 9() | -28.4()1 | 2.834 | -10.()23 | +()8 | < ().()()] |
|  | 65 | 60 | +.48+ | 2.834 | 1.582 | +()8 | $1 .(0)(0)$ |
|  |  | $71)$ | -8.311 | 2.834 | -2.933 | +()8 | ().()7 |
|  |  | 75 | -8.599 | 2.8 .34 | -3.0.35 | +()8 | ().05+ |
|  |  | 8() | -12.005 | 2.8 .34 | $-4.2 .37$ | +()8 | ().()) 1 |
|  |  | 85 | -21.4()7 | 2.834 | -7.555 | +()8 | $<(0.0)(1$ |
|  |  | 9() | -2.3.558 | 2.834 | -8.314 | +()8 | <(0.)()) |
|  | $71)$ | 60 | 13.154 | 2.834 | +.642 | +()8 | <(0.)()) |
|  |  | 65 | 8.311 | $2.83+$ | 2.933 | +()8 | ().07t |
|  |  | 75 | -(0.288 | 2.83 .1 | -().1()2 | +()8 | $1.0(0)$ |
|  |  | 8() | -3.694 | 2.834 | -1.3()4 | +()8 | $1 .(0)(0)$ |
|  |  | 85 | -13.096 | 2.83 .4 | -4.622 | +()8 | $<(0)()$. |
|  |  | 9() | -15.247 | 2.83 H | -5.381 | +()8 | <().()()] |
|  | 75 | 6 () | $13.4+2$ | 2.834 | +.74+ | +()8 | < ().()()] |
|  |  | 65 | 8.559 | 2.83 .4 | $3 .(1) 1$ | +()8 | 0.056 |
|  |  | 7) | ().228 | 2.83 .4 | (0.)8() | +()8 | 1.0)() |
|  |  | 8() | $-3.406$ | $2.83+$ | -1.202 | +()8 | $1 .(0)(0)$ |
|  |  | 85 | -12.8()8 | $2.83+$ | -4.52() | +()8 | <().)()] |
|  |  | 9() | -14.959 | 2.83 .4 | -5.279 | +(1)8 | $<(0.0)(1)$ |
|  | 8() | 60 | 16.848 | 2.8 .34 | $5.9+6$ | +()8 | $<(0).(0)$ |
|  |  | 65 | 12.005 | 2.834 | 4.237 | +()8 | ().0) 1 |
|  |  | 7) | $3.69+$ | 2.834 | 1.304 | +()8 | $1.0(0)$ |
|  |  | 75 | 3.4() 6 | $2.83+$ | 1.202 | +()8 | 1.000 |
|  |  | 85 | $-9 .+() 2$ | 2.834 | -.3.318 | +()8 | 0.021 |
|  |  | 9() | -11.553 | $2.83+$ | -4. 077 | +()8 | ().()) 1 |
|  | 85 | 60 | 2.625 | $2.83+$ | 0.926 | +()8 | $1.0(0)$ |
|  |  | 65 | 21.4() 7 | 2.834 | 7.555 | +()8 | < ().()()] |
|  |  | 7() | 13.096 | $2.83+$ | 4.622 | +()8 | <().()()] |
|  |  | 75 | 12.808 | $2.83+$ | +.52() | +(1) | <().()()] |
|  |  | 80 | 9.4() 2 | 2.834 | 3.318 | +()8 | ().()21 |
|  |  | 90 | -2.151 | 2.834 | -(0.759 | +()8 | $1.0(0)$ |
|  | $9(1)$ | 6() | 28.4()1 | $2.83+$ | 1().023 | +(0) | <().()() 1 |
|  |  | 65 | 23.558 | $2.83+$ | 8.314 | $4(0)$ | $<(0.0)(1$ |
|  |  | 7() | $15.2+7$ | 2.83+ | 5.381 | +()8 | <().()() 1 |
|  |  | 75 | $1+.959$ | 2.834 | 5.279 | +(0) | <().()()] |
|  |  | 80) | 11.553 | $2.83+$ | 4.077 | +()8 | ().0()1 |
|  |  | 85 | 2.151 | $2.83+$ | (0.759 | +()8 | 1.(0)() |
| 3 | 60 | 65 | -5.033 | 2.834 | -1.776 | +()8 | $1.0(0)$ |
|  |  | 7() | -13.797 | $2.83+$ | $-4.869$ | +()8 |  |
|  |  | 75 | -15.428 | 2.83 .4 | $-5.4+5$ | +()8 | <().()() 1 |
|  |  | 8() | -17.261 | $2.83+$ | -6.092 | +()8 | <().()()] |
|  |  | 85 | -25.061 | 2.834 | -8.8+4 | +()8 | <().()() 1 |
|  |  | 90 | -26.209 | 2.834 | -9.250 | +()8 | <().()() 1 |
|  | 65 | 60 | 5.033 | $2.83+$ | 1.776 | +()8 | $1.00)$ |
|  |  | 7() | -8.764 | $2.83+$ | -3.093 | +()8 | ().0 +4 |
|  |  | 75 | -10.395 | $2.83+$ | -3.669 | +()8 | ().0)6 |
|  |  | 8() | -12.228 | 2.83t | -4.315 | +()8 | < ().()()] |
|  |  | 85 | -20.()28 | $2.83+$ | -7.068 | +()8 | <().()()] |
|  |  | 9() | -21.176 | $2.83+$ | -7.473 | +()8 | <().()) ] |


| $0000^{\circ} \mathrm{I}$ | $80+$ | ＋$\left.\angle Z^{\circ}\right)^{-}$ | ＋E8て | LLL＇$)^{-}$ | 08 |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $000{ }^{\circ} \mathrm{I}$ | $80+$ | LL8 ${ }^{\text {（ }}$ |  | $98+$＇ | （）L |  |  |
| て＋0） 0 | $80 \dagger$ | 8015 | ＋ 58 \％ | L088 | S9 |  |  |
| I（）0）${ }^{\circ}$ ） | $80 \dagger$ | 6EL＇$\dagger$ | ＋ 58 \％ | LてけとI | 09 | SL |  |
| I（）0 ${ }^{\circ}(1)$ | $80 \dagger$ | （）$+\mathrm{L}^{+}{ }^{-}$ | ＋ 58 \％ | ICtci－ | 06 |  |  |
| $8000^{\circ}$ | $80+$ | $9 \mathrm{L8} \mathrm{C}^{-}$ | ＋i8て | 286 ${ }^{\circ} \mathrm{IF}^{-}$ | 58 |  |  |
| $000{ }^{\circ} \mathrm{I}$ | $80 \dagger$ | てS1「 ${ }^{-}$ | ＋ 58 て | ¢9でき－ | 08 |  |  |
| $000)^{\circ}$ | $80+$ | LL8（）－ | ＋ c8\％$^{\text {c }}$ | $98+$ 「－ | SL |  |  |
| ISS00 | $80 \dagger$ | Iこでて | ＋ 58 \％ | Iてど9 | S9 |  |  |
| C0） 0 （） | $80+$ | 198： | ＋58て | It6（）I | （）9 | （）L |  |
| I（0）${ }^{\circ}$（）＞ | 80t | IL69－ | ＋ 58 \％ | 2SL゙6I－ | 06 |  |  |
| I（0）$)^{\circ}$（） | 80t | L（）199－ | ＋ 58 | ¢0c゙く1－ | 58 |  |  |
| LIO） | $80 \dagger$ | 28ごぐ | ＋18\％ | ＋85\％${ }^{-}$ | 08 |  |  |
| 2＋0） 0 | 80）$\dagger$ | 801）${ }^{\text {c－}}$ | ＋58て | L08 $8^{-}$ | $\bigcirc$ |  |  |
| 15000 | 80）$\dagger$ | リとでで | ＋ 58 | Iてご9－ | （）L |  |  |
| $00(0)^{\circ}$ | 80 ＋ | 0¢9「1 | ＋ 58 \％ | （）て9「† | （）9 | 59 |  |
| I（）0（）${ }^{\text {a }}$ | $80+$ | I（09 8－ | ＋ 58 \％ | てくごやで | 06 |  |  |
| I（）0）（）＞ | 80）+ | LEL＇L－ | ＋ 58 て | こて6「で | 58 |  |  |
| I（）0（）$>$ | $80 \dagger$ | EIO¢ | ＋58て | ＋（）で†－ | 08 |  |  |
| 100） 0 （ $>$ | $80+$ | 6EL＋ | ＋58て | Lて＋ご「 | SL |  |  |
| co（） 0 | $80 \dagger$ | 198こ－ | ＋ 58 \％ | $1+60)^{-}$ | （）L |  |  |
| $000{ }^{\circ} \mathrm{I}$ | 80） | （）c9 ${ }^{\text {r }}$ | ＋c8て | （029 ${ }^{+-}$ | S9 | （0） | ＋ |
| 100） 0 | $80 \dagger$ | ISO）$\dagger$ | ＋¢8て | 08 t 1 I | 58 |  |  |
| $99^{\circ} 0$ | 80） | 8S15 | ＋c8て | $8+6.8$ | （）8 |  |  |
| co（） 0 | $80+$ | ¢08E | ＋¢8て | 1810） | $\bigcirc$ |  |  |
| ［（0）（） 0 | $80+$ | （）cで† | ＋c8て | ご0でて | （）L |  |  |
| I0） 0 （0） | 80） | ELT | ＋¢8て | 9 91「Iて | c） |  |  |
| I0） 0 （）＞ | $80 \dagger$ | 0こです | ナ¢8て | 60297 | （）9 | 06 |  |
| 100）（） | 80） | IS（）${ }^{\text {¢ }}$ | ナこ8て | （）8＋${ }^{\text {I }}{ }^{-}$ | （）6 |  |  |
| O¢50 | 80）$\dagger$ | csl | ナこ8て | $0088^{\circ}$ | 08 |  |  |
| 9100 | 80t | $00+5$ | ＋c8て | cc9 6 | $\leq L$ |  |  |
| 2000 | 80）$\dagger$ | 2L6E | ナと8て | scでII | （）L |  |  |
| I0） 0 （0） | 80） | 890 L | ナ +8 て | 8 80） 0 て | S9 |  |  |
| 10）（）${ }^{\text {（1）}}$ | 80） | ＋188 | ＋58て | $190 \bigcirc$ ¢ | （0） | S8 |  |
| 9800 | $80 \dagger$ | 8SIG－ | ＋c8て | 8＋6 8－ | 06 |  |  |
| OSI（ ） | 80）+ | CSLで |  | $008 \mathrm{~L}^{-}$ | 58 |  |  |
| 0000 I | 80t | L＋9 ${ }^{\text {（ }}$ | ＋88て | cc81 | $\subseteq$ |  |  |
| $000{ }^{\circ} \mathrm{I}$ | 80t | $61 て ゙ 1$ | ＋こ8て | ¢stc | （）L |  |  |
| I（））${ }^{\circ}(0)$ | 80t | ¢！ビ† | ナ¢8て | 8てでて1 | S9 |  |  |
|  | $80+$ | 260＇9 | ＋c8て | $19 て ゙ く 1$ | （）9 | 08 |  |
| c00） 0 | $80+$ | ¢08 ${ }^{\text {c－}}$ |  | 18L＊）${ }^{-}$ | 06 |  |  |
| $9 \mathrm{I} 0^{\circ} 0$ | $80 \dagger$ | $00+{ }^{\circ} \mathrm{C}$ | ＋ 58 | cc9 $6^{-}$ | ¢8 |  |  |
| $0000^{\circ} \mathrm{I}$ | $80+$ | Lt9 ${ }^{\text {（）－}}$ |  | cc8 ${ }^{-}$ | 08 |  |  |
| $000)^{\circ} \mathrm{I}$ | $80 \dagger$ | てLS゙0 | ＋c8て | て291 | （）L |  |  |
| 9000 | $80 \dagger$ | 699 － | tc8て | S6E（）I | S9 |  |  |
| I（0） $0^{\circ}(0)$ | $80+$ | Stt＇s | ナ¢8て | $8 て+51$ | （）9 | SL |  |
| I（0）${ }^{\circ}$（）＞ | $80+$ | LLE゙†－ | ナ¢8て | cot ${ }^{\text {co }}$ | 06 |  |  |
| 20000 | $80 \dagger$ | 2L6「－ | ＋c8て | ¢くでII－ | 58 |  |  |
| $0000^{\circ} \mathrm{I}$ | $80 \dagger$ | 6Iで「－ | ＋ 58 て | S¢tc－ | （08 |  |  |
| $000{ }^{\circ} \mathrm{I}$ | 80t | てLS゙（）－ |  | 229 ${ }^{\text {－}}$ | 5 |  |  |
| t＋（）＇0 | $80 \dagger$ | ¢60 ¢ | ＋ 58 て | ＋9L8 | S9 |  |  |
| I（）（）（）＞ | 80t | $698+$ | tc8て | LGL＇EI | （0） | （）L |  |


|  |  | 85 | -8.496 | $2.83+$ | -2.998 | +()8 | (0.060 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 9() | -10.9+5 | $2.83+$ | -3.863 | +()8 | ().())3 |
|  | 8() | 6() | 14.2()4 | 2.834 | $5 .(1)$ | +()8 | $<() .()() 1$ |
|  |  | 65 | 9.584 | $2.83+$ | 3.382 | +()8 | ().()17 |
|  |  | 7() | 3.263 | 2.834 | 1.152 | +()8 | 1.000 |
|  |  | 75 | (). 777 | 2.834 | (0.274 | +()8 | $1.0(0)$ |
|  |  | 85 | -7.719 | 2.8 .34 | -2.724 | 4() 8 | ().1+1 |
|  |  | 9() | -10.168 | 2.834 | -3.588 | 4() 8 | ().()()8 |
|  | 85 | 60 | 21.923 | 2.834 | 7.737 | 4() 8 | < ().()) 1 |
|  |  | 65 | 17.303 | 2.834 | 6.107 | 4() 8 | < ().)() 1 |
|  |  | 7) | 10.982 | 2.834 | 3.876 | $4(1)$ | ().0()3 |
|  |  | 75 | 8.496 | 2.8 .34 | 2.998 | $4(1)$ | ().06() |
|  |  | 8() | 7.719 | 2.834 | 2.724 | 4() 8 | ().141 |
|  |  | 9() | -2.449 | 2.834 | -(0.864 | 4() 8 | $1.0(0)$ |
|  | 9() | 6() | 24.372 | 2.8 .34 | 8.601 | +()8 | <().()() 1 |
|  |  | 65 | 19.752 | 2.834 | 6.971 | 4() 8 | <().()()] |
|  |  | 7) | 13.431 | 2.834 | 4.74 () | 4() 8 | <().()()] |
|  |  | 75 | $10.9+5$ | 2.834 | 3.863 | $4(0)$ | ().())3 |
|  |  | 8() | 10.168 | 2.834 | 3.588 | 4() 8 | ().0()8 |
|  |  | 85 | 2.449 | 2.834 | ().864 | $4(1)$ | $1.0(0)$ |
| 5 | 6 () | 65 | -6.483 | 2.834 | -2.288 | 4()8 | 0.476 |
|  |  | $71)$ | -10.035 | 2.834 | $-3.5+2$ | 4() 8 | ().0)9 |
|  |  | 75 | -10.821 | 2.834 | -3.819 | $4(1) 8$ | 0.0)3 |
|  |  | 8() | -10.268 | 2.834 | -3.624 | $4(1)$ | ().0) 7 |
|  |  | 85 | -17.668 | 2.834 | -6.235 | $4(08$ | <0.0) () |
|  |  | 9() | -20.492 | 2.834 | -7.232 | 4() 8 | $<(0.0)(1)$ |
|  | 65 | 6() | 6.483 | 2.834 | 2.288 | $4(1)$ | 0.476 |
|  |  | $71)$ | -3.552 | 2.834 | -1.254 | +()8 | $1.0(0)$ |
|  |  | 75 | -4.338 | 2.834 | -1.531 | +()8 | $1 .(0)()$ |
|  |  | 8() | -3.785 | 2.834 | $-1.336$ | $4(1)$ | $1.0(0)$ |
|  |  | 85 | -11.184 | 2.834 | $-3.9+7$ | $4(1) 8$ | ().0)2 |
|  |  | 9() | -14.(0) 0 | 2.8 .34 | $-4.9+4$ | $4(1) 8$ | <().()()] |
|  | 7 () | 60 | 10.0.35 | 2.834 | $3.5+2$ | $4(1)$ | ().0()9 |
|  |  | 65 | 3.552 | 2.834 | 1.254 | $4(18$ | $1.0(0)$ |
|  |  | 75 | -().786 | 2.834 | -(). 277 | 4() 8 | 1.0()() |
|  |  | 80 | -().2.3. | 2.834 | -().()82 | $4(08$ | 1.00() |
|  |  | 85 | -7.622 | 2.834 | -2.69() | $4(1) 8$ | (). 156 |
|  |  | 9() | -10.457 | 2.834 | -3.69() | $4(18$ | (0.0)5 |
|  | 75 | 6() | 10.821 | 2.834 | 3.819 | $4(1) 8$ | ().(0)3 |
|  |  | 65 | 4.338 | 2.834 | 1.531 | +()8 | $1 .(0)()$ |
|  |  | 7() | (0.786 | 2.834 | (0.277 | $4(08$ | 1.000 |
|  |  | 8() | (0.553 | 2.834 | 0.195 | +()8 | 1.000 |
|  |  | 85 | -6.847 | 2.834 | $-2.416$ | 4() 8 | (0.338 |
|  |  | 9() | -9.671 | 2.834 | -3.413 | 4() 8 | (0.) 015 |
|  | 8() | 60 | 10.268 | 2.834 | 3.624 | $4(08$ | ().())7 |
|  |  | 65 | 3.785 | 2.834 | 1.336 | 4() 8 | 1.()()) |
|  |  | 7) | ().233 | 2.834 | (0.082 | 4() 8 | 1.0()() |
|  |  | 75 | ().553 | 2.834 | ().195 | +()8 | 1.()()) |
|  |  | 85 | -7.369 | 2.834 | -2.6()] | +()8 | ().2()2 |
|  |  | 9() | -10.204 | 2.834 | -3.6()1 | +()8 | ().007 |
|  | 85 | 6 () | 17.668 | $2.83+$ | 6.235 | +()8 | <().)()] |
|  |  | 65 | 11.184 | 2.83+ | $3.9+7$ | 4() 8 | (0.0) 2 |


|  | 7) | 7.622 | 2.834 | 2.690) | $4(1) 8$ | 0.156 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 75 | 6.847 | 2.834 | 2.416 | +()8 | 0.338 |
|  | 80 | 7.369 | 2.834 | 2.601 | $4(1)$ | (0.2)2 |
|  | 9() | -2.835 | 2.834 | -1.00) | +()8 | 1.000 |
| 9() | 60 | 20.492 | 2.834 | 7.232 | +()8 | $<(0.0)$ () |
|  | 65 | 14.009 | 2.834 | +.9+4 | +()8 | <().)() 1 |
|  | 7 ) | 10.457 | 2.834 | 3.690 | $4(0)$ | (0.005 |
|  | 75 | 9.671 | 2.834 | 3.413 | +()8 | 0.015 |
|  | 80 | 10.20) | 2.834 | 3.601 | $4(0)$ | (0.0) 7 |
|  | 85 | 2.835 | 2.834 | 1.001 | +()8 | 1.000 |

Based on estimated marginal means
a. Adjustment for multiple comparisons: Bonferroni
b. An estimate of the modified population marginal mean (I)

### 1.1.2 Angle at one level of group

Pairwise comparisons to compare angle while holding group (non-exercise) constant.
Dependent Variable: MEAN

| Angle(I) | Angle(J) | Mean Difference (I-J) | Std. Error | $t$ value | Degrees of freedom | Significance ${ }^{\text {a }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 6() | 65 | $-9.16 .3$ | 1.780 | -9.163 | $4(18$ | <().()) 1 |
|  | 7) | -13.923 | 1.780 | -13.923 | $4(1)$ | <(0)(0) 1 |
|  | 75 | -1+.81() | 1.780 | -14.81 | $4(18$ | <(0.0) ${ }^{\text {l }}$ |
|  | 80 | -1+.55) | 1.780 | -14.55 | 408 | <().)(0) |
|  | 85 | -22.173 | 1.780 | -22.173 | $4(1)$ | < ().)(0) |
|  | 90 | -2+.227 | 1.780 | $-2+227$ | $4(18$ | <().0) 1 |
| 65 | 60 | 9.163 | 1.780 | 9.163 | $4(1)$ | <0.0) ${ }^{\text {a }}$ |
|  | 71 | -4.760) | 1.780 | -4.76 | $4(18$ | 0.164 |
|  | 75 | -5.647 | 1.780 | -5.647 | +()8 | $0.03+$ |
|  | 8() | -5.387 | 1.780 | -5.387 | +()8 | ().055 |
|  | 85 | -13.01() | 1.780 | -13.01 | $4(1)$ | <(0.)(0) 1 |
|  | 9() | -15.064 | 1.780 | -15.064 | $4(1)$ | <().()) 1 |
| 7) | 60 | 13.923 | 1.780 | 13.923 | $4(1)$ | <().0) 1 |
|  | 65 | +.760) | 1.780 | +.76 | 408 | ().164 |
|  | 75 | -0. 887 | 1.780 | -(0.887 | 418 | $1.000)$ |
|  | 80 | -0.627 | 1.780 | -0.627 | +(1)8 | $1.000)$ |
|  | 85 | -8.250) | 1.780 | -8.25 | 408 | <0.)(0) |
|  | 90 | -10.30) | 1.780 | -10.304 | +(1)8 | <().()) 1 |
| 75 | 60 | 14.810 | 1.780 | $1+81$ | 408 | <().)(0) |
|  | 65 | $5.6+7$ | 1.780 | 5.647 | +(1) | $0.03+$ |
|  | 71 | 0.887 | 1.780 | (0.887 | $4(18$ | 1.0)() |
|  | $8($ | 0.260 | 1.780 | 0.26 | 408 | $1.000)$ |
|  | 85 | -7.36.3 | 1.780 | -7.363 | 408 | (0.0) 1 |
|  | $9(1)$ | -9.417 | 1.780 | -9.417 | 408 | <(0.)(0) 1 |
| 80 | 60 | 1+.550) | 1.780 | $1+.55$ | $4(1)$ | <().()) 1 |
|  | 65 | 5.387 | 1.780 | 5.387 | $4(1)$ | 0.055 |
|  | 7) | 0.627 | 1.780 | 0.627 | 408 | 1.0)() |
|  | 75 | -(0.260) | 1.780 | -0.26 | $4(1)$ | $1.000)$ |
|  | 85 | -7.62.3 | 1.780 | -7.623 | $4(1)$ | <(0.)(0) |
|  | 90 | -9.677 | 1.780 | -9.677 | +()8 | <0.0) ${ }^{\text {a }}$ |
| 85 | 60 | 22.173 | 1.780 | 22.173 | $4(18$ | <(0.0) 1 |
|  | 65 | 13.010 | 1.780 | 13.01 | $4(1)$ | <(0.)() 1 |
|  | 71 | 8.250 | 1.780 | 8.25 | $4(18$ | <0.0) 01 |
|  | 75 | 7.363 | 1.780 | 7.363 | +(1) | 0.001 |
|  | 80 | 7.623 | 1.780 | 7.623 | +()8 | <(0.)(0) |
|  | 90 | -2.054 | 1.780 | -2.05 + | $4(1)$ | 1.0000 |
| 9() | 60 | 24.227 | 1.780 | 24.227 | $4(1)$ | $<(0.0)$ ) |
|  | 65 | 15.064 | 1.780 | 15.064 | $4(18$ | $<() .0()]$ |
|  | 70 | 10.304 | 1.780 | 10.304 | $4(1)$ | <(0.)() ${ }^{\text {l }}$ |
|  | 75 | 9.417 | 1.780 | 9.417 | 408 | <().)(0) |
|  | 80 | 9.677 | 1.780 | 9.677 | 408 | <(0.)(0) |
|  | 85 | 2.054 | 1.780 | 2.054 | 408 | $1.000)$ |

Based on estimated marginal means
a. Adjustment for multiple comparisons: Bonferroni

Pairwise comparisons to compare angle while holding group (exercise) constant
Dependent Variable: MEAN

| Angle(l) | Angle(J) | Mean Difference(l-J) | Std. Error | t value | Degrees of freedom | Significance ${ }^{\text {a }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 60 | 65 | 0.964 | 1.780 | (0.964 | 408 | $1.000)$ |
|  | 7 ) | -7.249 | 1.780 | -7.249 | $4(18$ | (0.0)1 |
|  | 75 | -7.4.3() | 1.780 | -7.4.30 | +()8 | 0.00) |
|  | 80 | -9.280) | 1.780 | -9.280) | $4(1)$ | <().)(0) |
|  | 85 | -17.103 | 1.780 | -17.103 | $4(18$ | <().0) 1 |
|  | 9() | -18.653 | 1.780 | -18.653 | +()8 | <().0) ${ }^{\text {l }}$ |
| 65 | 60 | -0.964 | 1.780 | -0.964 | +()8 | 1.0000 |
|  | 7) | -6.285 | 1.780 | -6.285 | +()8 | (0.01() |
|  | 75 | -6.466 | 1.780 | -6.466 | +()8 | (0.0) 7 |
|  | $8($ | -8.316 | 1.780 | -8.316 | +(1) | <(0.0) 1 |
|  | 85 | -16.139 | 1.780 | -16.139 | +()8 | <(0.0) 1 |
|  | 9() | -17.689 | 1.780 | -17.689 | $4(18$ | <().0) 1 |
| 7) | 60 | 7.249 | 1.780 | 7.249 | +()8 | 0.0) 1 |
|  | 65 | 6.285 | 1.780 | 6.285 | +()8 | 0.010 |
|  | 75 | -().181 | 1.780 | -().181 | +()8 | 1.000 |
|  | $8($ | -2.031 | 1.780 | -2.031 | +()8 | $1.0(0)$ |
|  | 85 | -9.854 | 1.780 | -9.854 | +()8 | <().)(0) 1 |
|  | 90 | -11.4)+ | 1.780 | -11.4)4 | $4(1)$ | <().0) 1 |
| 75 | 60 | 7.4.3) | 1.780 | 7.4.3) | +()8 | 0.001 |
|  | 65 | 6.466 | 1.780 | 6.466 | +()8 | 0.00) 7 |
|  | 7) | (0.181 | 1.780 | 0.181 | +()8 | $1.0(0)$ |
|  | 80 | -1.850) | 1.780 | -1.850 | $4(1)$ | $1.000)$ |
|  | 85 | -9.673 | 1.780 | -9.673 | $4(18$ | <().0) 1 |
|  | 90 | -11.223 | 1.780 | -11.223 | +()8 | <().)() 1 |
| 8() | 60 | 9.280 | 1.780 | 9.280 | +(0) | <().)() 1 |
|  | 65 | 8.316 | 1.780 | 8.316 | +()8 | <().()) 1 |
|  | 70 | 2.031 | 1.780 | 2.031 | +()8 | 1.0)() |
|  | 75 | 1.85 () | 1.780 | 1.850 | +(1) | $1.000)$ |
|  | 85 | -7.82.3 | 1.780 | -7.82.3 | +()8 | <(0.)(0) |
|  | 9() | -9.373 | 1.780 | -9.373 | $4(18$ | <().0) ${ }^{\text {d }}$ |
| 85 | 60 | 17.103 | 1.780 | 17.103 | +()8 | <().)(0) |
|  | 65 | 16.139 | 1.780 | 16.139 | $4(1)$ | <().0) ${ }^{\text {l }}$ |
|  | 70 | 9.854 | 1.780 | 9.854 | +()8 | <().)() 1 |
|  | 75 | 9.673 | 1.780 | 9.673 | +()8 | <().)(0) |
|  | $8($ | 7.823 | 1.780 | 7.823 | 408 | <().0) 1 |
|  | 90 | -1.55() | 1.780 | -1.55() | 4)8 | $1.000)$ |
| 9() | 60 | 18.653 | 1.780 | 18.653 | $4(18$ | <().)() 1 |
|  | 65 | 17.689 | 1.780 | 17.689 | 4)8 | <().)()] |
|  | 7) | 11.404 | 1.780 | 11.404 | 408 | <().)() 1 |
|  | 75 | 11.223 | 1.780 | 11.223 | $4(1)$ | <().)() 1 |
|  | 80 | 9.373 | 1.780 | 9.373 | $4(1)$ | <().0) 1 |
|  | 85 | 1.550 | 1.780 | 1.550 | 408 | 1.0)() |

[^0]
### 1.2 Main effect of ROI

Pairwise comparison to compare the main effect of ROl when ROl's are in a dorsal position.
Dependent variable : MEAN

| $\mathrm{ROI}(1)$ | ROI (J) | Mean difference | Std Error | Significance ${ }^{\text {a }}$ |
| :---: | :---: | :---: | :---: | :---: |
| 1 | 2 | 8.037* | 1.071 | <().()) 1 |
|  | 3 | 11.852* | 1.071 | <().)() 1 |
|  | + | 14.221* | 1.071 | <().)() 1 |
|  | 5 | 7.518* | 1.071 | <().)() 1 |
| 2 | 1 | -8.067* | 1.071 | <().)() 1 |
|  | 3 | 3.784* | 1.071 | 0.005 |
|  | $+$ | 6.484* | 1.071 | <().()) 1 |
|  | 5 | -0.549 ${ }^{\text {b }}$ | 1.071 | $1.000)$ |
| 3 | 1 | -11.852* | 1.071 | <().)() 1 |
|  | 2 | -3.784* | 1.071 | 0.005 |
|  | $+$ | $2.699^{\text {b }}$ | 1.071 | 0.121 |
|  | 5 | -4.333* | 1.071 | 0.00) |
| 4 | 1 | -1+.551* | 1.071 | <().()) 1 |
|  | 2 | -6.484* | 1.071 | <().)() 1 |
|  | 3 | $-2.699^{\text {b }}$ | 1.071 | (0.121 |
|  | 5 | -7.0.32* | 1.071 | <().0) ${ }^{\text {a }}$ |
| 5 | 1 | -7.518* | 1.071 | <().0) ${ }^{\text {( }}$ |
|  | 2 | $0.549^{\text {b }}$ | 1.071 | $1.000)$ |
|  | 3 | +.333* | 1.071 | 0.00) |
|  | $+$ | 7.032* | 1.071 | <().)() 1 |

Based on estimated marginal means
*. The mean difference is significant at the 0.5 level
a. Adjustment for multiple comparisons: Bonferroni
b. An estimate of the modified population marginal mean (l)

### 1.2.1 ROI at one level of group

Pairvise comparisons comparing ROI holding group (non-exercise) constant when ROI's are in a dorsal position.

Dependent Variable :MEAN

| ROI (I) | ROI (J) | mean difference (I-J) | Std error | T value | Degrees of freedom | Significance ${ }^{\text {a }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 2 | 12.092 | 1.515 | 7.984 | $4(1)$ | $<(0).(0) 1$ |
|  | 3 | 14.97 .3 | 1.515 | 9.886 | +()8 | <().0) ${ }^{\text {a }}$ |
|  | 4 | 16.74() | 1.515 | 11.053 | +()8 | <().0) ${ }^{\text {l }}$ |
|  | 5 | 5.687 | 1.515 | 3.755 | +()8 | 0.0)2 |
| 2 | 1 | -12.092 | 1.515 | 7.984 | +()8 | <().0) 1 |
|  | 3 | 2.88() | 1.515 | 1.902 | +()8 | 0.579 |
|  | 4 | 4.648 | 1.515 | 3.069 | $4(1)$ | 0.02.3 |
|  | 5 | -6.405 | 1.515 | -4.229 | 408 | <0.)(0) 1 |
| 3 | 1 | -14.97.3 | 1.515 | 9.886 | $4(1)$ | $<(0.0) 1$ |
|  | 2 | -2.880) | 1.515 | 1.902 | +()8 | (0.579 |
|  | 4 | 1.768 | 1.515 | 1.167 | +()8 | $1.000)$ |
|  | 5 | -9.286 | 1.515 | -6.131 | +()8 | <().)() 1 |
| 4 | 1 | -16.74) | 1.515 | 11.053 | $4(1)$ | <().()) 1 |
|  | 2 | -4.6+8 | 1.515 | 3.069 | +()8 | 0.02.3 |
|  | 3 | -1.768 | 1.515 | 1.167 | +()8 | $1.000)$ |
|  | 5 | -11.053 | 1.515 | -7.298 | +()8 | <().0) 1 |
| 5 | 1 | -5.687 | 1.515 | 3.755 | +()8 | 0.0)2 |
|  | 2 | 6.405 | 1.515 | -4.229 | +()8 | <().0) ${ }^{\text {a }}$ |
|  | 3 | 9.286 | 1.515 | -6.131 | +()8 | $<() .00) 1$ |
|  | 4 | 11.053 | 1.515 | -7.298 | +()8 | $<(0.0)$ ) |

Based on estimated marginal means
a. Adjustment for multiple comparisons: Bonferroni

Pairwise comparison comparing ROI holding group (exercise) constant when ROI's are in a dorsal position.

Dependent Variable :MEAN

| ROI (1) | ROI (J) | Mean Difference (I-J) | Std error | T value | Degrees of freedom | Significance ${ }^{\text {a }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 2 | 4.055 | 1.515 | 2.678 | 408 | (0.)77 |
|  | 3 | 8.75 () | 1.515 | 5.777 | $4(1)$ | <().)(0) |
|  | 4 | 12.386 | 1.515 | 8.178 | 408 | <().0) ${ }^{\text {a }}$ |
|  | 5 | 9.375 | 1.515 | 6.190 | +08 | <().)() ) |
| 2 | 1 | -4.055 | 1.515 | 2.678 | 408 | 0.077 |
|  | 3 | +.69+ | 1.515 | 3.099 | 408 | 0.021 |
|  | 4 | $8.3+()$ | 1.515 | 5.507 | +()8 | <().)() 1 |
|  | 5 | 5.307 | 1.515 | 3.504 | $4(1)$ | ().00) 5 |
| 3 | 1 | 8.750 | 1.515 | 5.777 | 408 | <(0.0) 1 |
|  | 2 | -4.69+ | 1.515 | 3.099 | 408 | (0.021 |
|  | 4 | 3.636 | 1.515 | 2.401 | 408 | 0.168 |
|  | 5 | 0.614 | 1.515 | ().405 | $4(1)$ | $1.000)$ |
| 4 | 1 | -12.386 | 1.515 | 8.178 | 408 | <().()) 1 |
|  | 2 | -8.3+() | 1.515 | 5.507 | 408 | <().)() 1 |
|  | 3 | -3.6.36 | 1.515 | 2.401 | +()8 | ().168 |
|  | 5 | -3.02.3 | 1.515 | -1.996 | +()8 | 0.466 |
| 5 | 1 | -9.375 | 1.515 | 6.190 | 408 | <().0) ${ }^{\text {a }}$ |
|  | 2 | -5.307 | 1.515 | 3.504 | 408 | (0.00) |
|  | 3 | -0.614 | 1.515 | (). 4 ()5 | +()8 | 1.0)() |
|  | 4 | 3.023 | 1.515 | -1.996 | +()8 | ().466 |

Based on estimated marginal means
a. Adjustment for multiple comparisons: Bonferroni

## $\underline{1.2 .2 \mathrm{ROl} \text { at one level of angle }}$

Pairwise comparisons to compare ROl means while holding angle constant when ROI's are in a dorsal position.

Dependent variable:MEANS

| ANGLE | (1) ROI | (J) ROI | Mean Difference (1-J) | Std. Error | T value | Degrees of freedom | Significance ${ }^{\text {a }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 60 | 1 | 2 | 18.796 | 2.834 | 6.6 .33 | $4(18$ | <().0) 1 |
|  |  | 3 | 22.559 | 2.834 | 7.961 | $4(1)$ | <().00) |
|  |  | 4 | 23.258 | 2.834 | 8.208 | $4(1)$ | <().)() ) |
|  |  | 5 | 14.364 | 2.834 | 5.069 | $4(1)$ | <().0) 1 |
|  | 2 | 1 | -18.796 | 2.834 | -6.633 | $4(1)$ | <().0) ${ }^{\text {l }}$ |
|  |  | 3 | 3.763 | 2.834 | 1.328 | $4(1)$ | $1.000)$ |
|  |  | $+$ | $+.562$ | 2.834 | 1.610 | $4(1)$ | $1.000)$ |
|  |  | 5 | -4.432 | 2.834 | -1.564 | +()8 | $1.000)$ |
|  | 3 | 1 | -22.559 | 2.834 | -7.961 | $4(1)$ | <().0) ${ }^{\text {l }}$ |
|  |  | 2 | -3.76.3 | 2.834 | -1.328 | $4(1)$ | $1.000)$ |
|  |  | $t$ | (0.799 | $2.83+$ | (). 282 | $4(1)$ | $1.000)$ |
|  |  | 5 | -8.195 | 2.834 | -2.892 | +()8 | ().040 |
|  | 4 | 1 | -23.258 | 2.834 | -8.208 | +()8 | <().()) 1 |
|  |  | 2 | -4.562 | 2.834 | -1.610 | +()8 | 1.0)() |
|  |  | 3 | -(0.799 | 2.834 | -(0)282 | $4(1)$ | $1.000)$ |
|  |  | 5 | -8.99+ | 2.834 | -3.174 | +()8 | (0.016 |
|  | 5 | 1 | -14.364 | 2.834 | -5.069 | +()8 | <().()) 1 |
|  |  | 2 | +. +32 | 2.834 | 1.564 | +()8 | $1.000)$ |
|  |  | 3 | 8.195 | 2.834 | 2.892 | +()8 | ().)4() |
|  |  | 4 | $8.99+$ | 2.834 | 3.174 | +()8 | (0.)16 |
| 65 | 1 | 2 | 18.292 | 2.834 | 6.456 | +()8 | <(), (0) 1 |
|  |  | 3 | 21.865 | 2.834 | 7.717 | +()8 | <(0.)(0) 1 |
|  |  | 4 | 23.077 | 2.834 | $8.14+$ | 408 | <(0.)(0) 1 |
|  |  | 5 | 12.22() | $2.83+$ | 4.313 | $4(1)$ | <().)() 1 |
|  | 2 | 1 | -18.292 | $2.83+$ | -6.456 | +()8 | <().()) 1 |
|  |  | 3 | 3.573 | $2.83+$ | 1.261 | +()8 | 1.00 () |
|  |  | 4 | 4.785 | 2.834 | 1.689 | +()8 | 0.920 |
|  |  | 5 | -6.072 | 2.834 | -2.143 | +()8 | 0.327 |
|  | 3 | I | -21.865 | 2.834 | -7.717 | $4(1)$ | <().()) 1 |
|  |  | 2 | -3.573 | 2.834 | -1.261 | +()8 | 1.0000 |
|  |  | 4 | 1.212 | 2.834 | (). 428 | $4(1)$ | $1.000)$ |
|  |  | 5 | -9.645 | 2.834 | -3.4() + | $4(1)$ | (0.)()7 |
|  | 4 | 1 | -23.()77 | 2.834 | -8.14+ | $4(1)$ | <().()) 1 |
|  |  | 2 | -4.785 | 2.834 | -1.689 | $4(1)$ | 0.920 |
|  |  | 3 | -1.212 | 2.83 .4 | -().428 | $4(1)$ | 1.000 |
|  |  | 5 | -10.857 | 2.834 | -3.832 | $4(1)$ | 0.001 |
|  | 5 | 1 | -12.220) | 2.834 | -4.313 | +()8 | <().()) 1 |
|  |  | 2 | 6.072 | 2.834 | 2.143 | 4() 8 | 0.327 |
|  |  | 3 | -0.645 | $2.83+$ | -().228 | +()8 | $1.000)$ |
|  |  | 4 | 10.857 | 2.834 | 3.832 | 4() 8 | (0.0) 1 |
| 7) | 1 | 2 | 10.646 | 2.834 | 3.757 | +()8 | ().0)2 |
|  |  | 3 | 13.766 | 2.834 | 4.858 | $4(1)$ | <().)() 1 |
|  |  | 4 | 17.511 | 2.834 | 6.180 | $4(1)$ | <().)()] |
|  |  | 5 | 9.333 | 2.834 | 3.294 | +()8 | (0.)11 |


| （）SL＇0 | $80 \dagger$ | S8L＇${ }^{-}$ | ＋+8.2 | 850 ¢－ | $\bigcirc$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $000{ }^{\circ}$ | $80 \dagger$ | 19E「「－ | ＋+8.2 | 958\％－ | $\varepsilon$ |  |  |
| 0 （）1 0 | $80 \dagger$ | 885 て－ | ＋ 58 \％ | ナどぐ | て |  |  |
| ＋（0） 0 | $80 \dagger$ | 185\％ | ＋ 58 て | 8＋10）${ }^{-}$ | I | † |  |
| 000 ＇ 1 | 80 ¢ | ＋で ${ }^{\text {（）－}}$ | ＋58て | て）で「－ | 5 |  |  |
| （0）0 ${ }^{\circ}$ | 80 ＋ | 19¢ 1 | ＋+8.2 | 958. | $\dagger$ |  |  |
| 000 I | 80 ＋ | 281 ${ }^{-}$ | ＋+8 て | （）Sc゙¢ | て |  |  |
| $697^{\circ} 0$ | $80 \dagger$ | 1てでで | ＋+8.2 | て6で9－ | I | $\varepsilon$ |  |
| $000{ }^{\circ} \mathrm{I}$ | 80 † | LSL＇） | ＋ 58.2 | くけ1゙て | 5 |  |  |
| （）0．${ }^{\circ}(0$ | 80 † | 885゙て | ＋ 58 \％ | ＋EC゙L | $\dagger$ |  |  |
| （）0）I I | $80 \dagger$ | 281 1 | ＋ 58 | 0） $0^{\circ}$ を | ¢ |  |  |
| 0 （）0 1 | 80 ） | $80^{\circ}{ }^{\circ}{ }^{-}$ | ＋ 58 \％ | てや6「で | 1 | $\tau$ |  |
| てとじ（） | $80 \dagger$ | 96L＇I | ＋58て | 060 ¢ | $\bigcirc$ |  |  |
| †（）0＇0） | $80 \dagger$ | 185゙G | ＋58て | $8+1{ }^{\circ} \mathrm{O}$ | $\dagger$ |  |  |
| $69 \chi^{\circ}()$ | $80 \dagger$ | Iてでて | ＋+8 て | て6で9 | $\varepsilon$ |  |  |
| （）00）I | $80 \dagger$ | 8こ0） | ＋ 8 ¢ | てけ6゙て | 乙 | I | $(08$ |
| しっで） | 80 ） | ＋こでて | ＋ 58 \％ | 88c゙9 | † |  |  |
| （）（0） 1 | $80 \dagger$ | 99で1 | ＋ 58 \％ | 885 | ¢ |  |  |
| （）（）） 1 | $80+$ | 6¢9（） | ＋ 58 \％ | II8．1 | $\tau$ |  |  |
| $1+¢ 0$ | $80 \dagger$ | 9でで | ＋ 58 \％ | （2）${ }^{\text {9－}}$ | I | $\succeq$ |  |
| しナで0 | $80 \dagger$ |  | ＋ 58 \％ | $88 \mathrm{CN}^{\circ} \mathrm{O}$ | 5 |  |  |
| （）（）） 1 | $80 \dagger$ | 886 ${ }^{\circ}$（－ | ＋ 58 \％ | $0088^{\circ}$ て－ | $\varepsilon$ |  |  |
| （）0）（） 1 | 80） | SI9 $\mathrm{T}^{-}$ | ＋ 58 \％ | LLS「†－ | $\checkmark$ |  |  |
| I0）（）$>$ | $80 \dagger$ | 08E ${ }^{\text {＋}}$ | ＋ 58 \％ | IIナで－ | I | † |  |
| （）（）I | $80+$ | $99 \mathrm{C}^{\circ} \mathrm{T}$ | ＋ 58 \％ | 8850 | $\bigcirc$ |  |  |
| $000 \cdot 1$ | $80+$ | 886 ${ }^{\circ}$ | ＋ 58 て | 008 \％ | † |  |  |
| 0 （）0 ${ }^{\circ}$ | $80+$ | L29（）－ | ＋ 58 | LLL＇${ }^{-}$ | 乙 |  |  |
| $8000^{\circ}$ | $80+$ | 26E゙く－ |  | 119\％${ }^{-}$ | I | $\varepsilon$ |  |
| 000 I | $80+$ | 6さ9 $\left.{ }^{\circ}\right)^{-}$ | ＋ 58 て | 1181－ | 5 |  |  |
| $000{ }^{\circ} \mathrm{I}$ | $80+$ | SI9 I | ＋ 58 \％ | LLS $\dagger$ | t |  |  |
| $000{ }^{\circ} 1$ | $80+$ | Lて9＊） | ＋ 58 \％ | LLL＇I | ¢ |  |  |
| （）90（） | $80+$ | 59L゙で | ＋ 58 \％ | ＋ ¢ $^{\text {L }}{ }^{-}$ | I | 乙 |  |
| Itc゙（） | $80+$ | 9てI「 | ＋ 58 \％ | とて（）＇9 | $\bigcirc$ |  |  |
| I（0）（）＞ | $80 \dagger$ | （）8ご† | ＋58て | 11＋てI | $\dagger$ |  |  |
| $80(0)$ | $80+$ | 26ざく | ＋58て | 1196 | ¢ |  |  |
| （990＇0） | $80+$ | ¢9L゙て | ＋58て | ＋C8． | 乙 | I | $S L$ |
| LII ${ }^{\circ}$ | $80+$ | ccsて | ＋ 58 \％ | 8LIL | t |  |  |
| （）0） 1 | $80+$ | ＋9s 1 | ＋ 58 亿 | cett | ¢ |  |  |
| $000{ }^{\circ} 1$ | $80+$ | ¢9「 ${ }^{+}$ | ＋ 58 \％ | どぐ1 | 乙 |  |  |
| IIO） | $80+$ | ＋6でき－ | ＋ 58 \％ | とこど $6^{-}$ | I | 5 |  |
| LII（） | $80+$ | çsで | ＋58て | 8LI L－ | 5 |  |  |
| $000{ }^{\circ} \mathrm{I}$ | $80+$ | ててど1－ | ＋ 58 \％ | $5+\angle{ }^{\text {co }}$ | $\varepsilon$ |  |  |
| S91 ${ }^{\circ}$ | $80+$ | L0＋て－ | ＋58て | （0289－ | 乙 |  |  |
| I（））（）＞ | $80+$ | （081 ${ }^{\circ}$ | ＋ 58 \％ | 115゙LI－ | 1 | t |  |
| $000{ }^{\circ}$ | $80+$ | ＋9¢ ${ }^{-}$ | ＋ 58 \％ | とこけt－ | 5 |  |  |
| $000{ }^{\circ} \mathrm{I}$ | $80+$ | ててご1 | ＋58て | S＋L゙く | t |  |  |
| $000)^{\circ}$ | $80+$ | I $\mathrm{I}^{\text { }} \mathrm{I}^{-}$ | ＋ 58 \％ | （）ZI 「－ | ح |  |  |
| I0）${ }^{\circ}(1)$ | $80 \dagger$ | 858 ${ }^{+}$ | ＋c8て | 99 LC | I | $\varepsilon$ |  |
| $000{ }^{\circ} \mathrm{I}$ | $80 \dagger$ | C9＋${ }^{\circ}$ | ＋ 58 て | ¢しく「－ | 5 |  |  |
| S910 | $80+$ | LOけて | ＋58て | 0289 | ＋ |  |  |
| $000{ }^{\circ} 1$ | $80 \dagger$ | I（）］I | ＋c8て | （）て1＇${ }^{\text {c }}$ | $\varepsilon$ |  |  |
| 200） 0 | $80 \dagger$ | LSL＇ | ＋ 58 | $9+9{ }^{\text {（）}}{ }^{-}$ | I | $\tau$ |  |


|  | 5 | 1 | -5.09() | 2.834 | -1.796 | $4(1) 8$ | 0.732 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 2 | -2.145 | 2.834 | -0.757 | 4() 8 | $1.000)$ |
|  |  | 3 | 1.202 | 2.834 | (0.424 | $4(1)$ | 1.000 |
|  |  | 4 | 5.058 | 2.834 | 1.785 | $4(1)$ | 0.750 |
| 85 | 1 | 2 | -(0)154 | 2.834 | -(0.054 | $4(1)$ | 1.000 |
|  |  | 3 | +.798 | $2.83+$ | 1.693 | $4(1)$ | 0.912 |
|  |  | $+$ | 8.735 | 2.834 | 3.083 | $4(0)$ | 0.022 |
|  |  | 5 | +.007 | 2.834 | 1.414 | $4(1)$ | 1.000 |
|  | 2 | 1 | 0.154 | 2.834 | 0.05t | $4(1)$ | 1.000 |
|  |  | 3 | +.952 | 2.834 | 1.748 | +()8 | 0.813 |
|  |  | 4 | 8.889 | 2.83. | 3.137 | $4(1) 8$ | 0.018 |
|  |  | 5 | +.161 | $2.83+$ | 1.468 | +()8 | 1.000 |
|  | 3 | I | -4.798 | $2.83+$ | -1.693 | $4(0)$ | 0.912 |
|  |  | 2 | -4.952 | 2.834 | -1.748 | 408 | 0.813 |
|  |  | $+$ | 3.937 | 2.834 | 1.389 | 408 | 1.000 |
|  |  | 5 | -(0.863 | 2.83 .4 | -(0.305 | 408 | 1.000 |
|  | $+$ | 1 | -8.735 | 2.834 | -3.083 | +()8 | 0.022 |
|  |  | 2 | -8.889 | 2.834 | -3.137 | 408 | (0.018 |
|  |  | 3 | -3.937 | 2.8 .34 | -1.389 | $4(0)$ | 1.000 |
|  |  | 5 | -4. +28 | 2.834 | $-1.563$ | 408 | 1.000 |
|  | 5 | 1 | -4.007 | 2.834 | -1.414 | 408 | 1.000 |
|  |  | 2 | -4.161 | 2.834 | $-1.468$ | 408 | 1.000 |
|  |  | 3 | (0.863 | 2.834 | 0.305 | 408 | 1.000 |
|  |  | + | +. +28 | $2.83+$ | 1.563 | 408 | 1.000 |
| 90 | I | 2 | -1.882 | 2.834 | -0.66t | 408 | 1.000 |
|  |  | 3 | 4.073 | 2.834 | $1 .+37$ | $4(0)$ | 1.000 |
|  |  | 4 | 6.709 | 2.834 | 2.368 | 408 | 0.18.4 |
|  |  | 5 | 1.595 | 2.834 | 0.563 | +08 | 1.000 |
|  | 2 | 1 | 1.882 | 2.834 | 0.664 | +08 | 1.000 |
|  |  | 3 | 5.955 | 2.834 | 2.102 | 408 | 0.362 |
|  |  | 4 | 8.591 | 2.834 | 3.032 | 408 | ().026 |
|  |  | 5 | 3.477 | 2.834 | 1.227 | +08 | $1.000)$ |
|  | 3 | 1 | -4.073 | 2.834 | -1.4.37 | +(0) | $1.00)$ |
|  |  | 2 | -5.955 | 2.834 | -2.1(02 | +08 | 0.362 |
|  |  | $+$ | 2.636 | 2.834 | 0.930 | +()8 | 1.000 |
|  |  | 5 | -2.478 | 2.834 | -(0.875 | +08 | 1.000 |
|  | $t$ | 1 | -6.709 | $2.83+$ | -2.368 | +108 | (0.18t |
|  |  | 2 | -8.591 | $2.83+$ | -3.032 | +()8 | (0.026 |
|  |  | 3 | -2.6.36 | 2.834 | -(0.930) | +08 | 1.000 |
|  |  | 5 | -5.114 | $2.83+$ | -1.805 | +()8 | 0.718 |
|  | 5 | 1 | -1.595 | $2.83+$ | -(0.563 | +()8 | $1.000)$ |
|  |  | 2 | -3.477 | $2.83+$ | -1.227 | $4(1)$ | $1.000)$ |
|  |  | 3 | 2.478 | 2.834 | 0.875 | +()8 | $1.000)$ |
|  |  | $+$ | $5.11+$ | 2.834 | 1.805 | +()8 | 0.718 |

Based on estimated marginal means
a. Adjustment for multiple comparisons: Bonferroni

### 1.3 Main effect of group

Pairwise comparisons to compare the main effect of group when ROI is in a dorsal and palmar position

| position | Exercised <br> $(\mathrm{l})$ | Non <br> exercised <br> $(\mathrm{J})$ | Mean <br> difference <br> $(\mathrm{I}-\mathrm{J})$ | Std Error | Sig |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Dorsal | 125.37 | $11(0.6()$ | 14.77 | 0.479 | $<(0.0)(0)$ |
| palmar | 138.38 | $12(0.10$ | 18.28 | 0.476 | $<(0.0(0) 1$ |

b. An estimate of the modified population marginal mean

### 1.3.1 Group at one level of angle

Pairvise comparisons to compare group means while holding angle constant when ROl's are in a dorsal position.

Dependent Variable: MEAN

| ANGLE | Mean Difference (1-J) | Std. Error | t value | Degrees of freedom | significance |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 60 | 20.221 | 1.792 | $11.28+$ | +()8 | <().)() 1 |
| 65 | 12.022 | 1.792 | 6.708 | +()8 | <().)(0) |
| 7) | 13.547 | 1.792 | 7.559 | +()8 | <().0) 1 |
| 75 | 12.8+1 | 1.792 | 7.165 | +()8 | <().0) 1 |
| 80 | 14.951 | 1.792 | $8.3+3$ | +()8 | <().)(0) |
| 85 | 15.151 | 1.792 | 8.454 | +()8 | <().)() 1 |
| 90 | $1+6+7$ | 1.792 | 8.173 | 408 | <().)(0) 1 |

l = exercised
$\mathrm{J}=$ nonexercised

## 1.3 .2 group at one level of ROI

Painvise comparisons to compare group means while holding ROl constant when ROI's are in a dorsal position.

Dependent Variable: MEAN

| ROI | Mean Difference (1-J) | Std. Error | t value | Degrees of freedom | significance |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | -11.782 | 1.773 | -6.646 | 117 | <0.()) () |
| 2 | -19.813 | 1.773 | -11.176 | 117 | <().0) ${ }^{\text {( }}$ |
| 3 | -18.0) 1 | 1.773 | -10.154 | 117 | <(0.)() ) |
| 4 | -16.13t | 1.773 | -9.101 | 117 | <().)() 1 |
| 5 | -8.11() | 1.773 | -4.575 | 117 | <0.0) ${ }^{\text {l }}$ |

[^1]
## 2. Palmar data

Tabulated data prior to statistical analysis

| Average of mean |  | ROI | ROI | ROI | ROI | ROI |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| angle | group | 1 | 2 | 3 | 4 |  |
| 60 | () | 136.0762571 | 121.7521571 | 118.386 | 119.8466571 | 129.0873143 |
|  | 1 | $158.268+1+3$ | 149.4595857 | $1+2.6131$ | $148.8+59571$ | $1+0.4601$ |
| 60) Total |  | 1+7.172.3357 | 135.6058714 | 1.30 .49955 | $13+.3+6.3071$ | 134.77.37071 |
| 65 | () | 131.9321286 | 118.6+22714 | 118.5579571 | 119.26.37286 | 127.458 |
|  | 1 | $1+7.873+429$ | $1+1.1792857$ | 138.6190714 | 138.8018143 | 135.1219143 |
| 65 Total |  | 139.9027857 | 129.91()7786 | 128.58851+3 | 129.0.327714 | 131.2899571 |
| 7) | () | 126.7036 | 116.3538571 | 115.9089857 | 115.3619857 | 124.1215 |
|  | 1 | $1+4.4138286$ | 1+1.3019714 | 137.61871+3 | 13+.73.311+3 | $131.2+4(0286$ |
| 7) Total |  | $135.55871+3$ | $128.82791+3$ | 126.76 .385 | 125.04755 | 127.682764.3 |
| 75 | () | 122.06000857 | $112.9+72714$ | 113.10+271t | 113.68865571 | $12+.9+25571$ |
|  | 1 | 138.9266714 | 137.6562571 | 133.26981+3 | 1.31 .967 .3 | 129.4500857 |
| 75 Total |  | 130.4933786 | 125.30176+3 | 123.187()+29 | 122.8279786 | 127.196.3214 |
| 80 | () | 118.1328571 | 111.4038286 | $109.816+857$ | 111.9089714 | 122.2712857 |
|  | 1 | 136.6913 | 137.3381714 | 131.5278286 | $132.0677+29$ | $128.09+8+29$ |
| 80 Total |  | 127.4120786 | 12+.371 | 120.6721571 | 121.9883 .571 | 125.183064 3 |
| 85 | 0 | 124.087+714 | 118.3069286 | 115.1590571 | 117.5555286 | 129.20061+3 |
|  | 1 | $1+1.5+6.3857$ | $1+3.1269+29$ | 136.3717286 | 138.7307714 | $132.3+52286$ |
| 85 Total |  | 132.8169286 | 130.7169357 | 125.7653929 | 128.1+315 | 130.7729214 |
| 90 | () | 122.0192857 | $118.55891+3$ | 115.5319 | $115.6691+29$ | 127.746()+29 |
|  | 1 | 1.39.676+14.3 | $1+0.9868571$ | $13+.51251+3$ | 137.751+857 | $130.805 .3+29$ |
| 90) Total |  | $1.30 .8+785$ | 129.7728857 | 125.0222071 | 126.71031+3 | 129.2756929 |

### 2.1 Main effect of angle

Pairwise comparisons to compare the main effect of angle when ROI's are in a palmar position.
Dependent variable: MEAN

| Angle (1) | Angle (J) | Mean difference $(\mathrm{I}-\mathrm{J})$ | Std error | Significance ${ }^{\text {a }}$ |
| :---: | :---: | :---: | :---: | :---: |
| 60 | 65 | +.735* | 1.259 | <().)(0) |
|  | 70 | 7.703* | 1.259 | <().)(0) |
|  | 75 | 10.678* | 1.259 | <().)() ${ }^{\text {l }}$ |
|  | 80 | 12.554* | 1.259 | <().)() 1 |
|  | 85 | 6.826* | 1.259 | <().)() 1 |
|  | 9() | 8.154* | 1.259 | <().)() 1 |
| 65 | 60 | -4.735* | 1.259 | <().)() 1 |
|  | 71 | 2.969* | 1.259 | (0.019 |
|  | 75 | 5.944* | 1.259 | <().)() 1 |
|  | 80 | 7.820** | 1.259 | <().()0) |
|  | 85 | $2.102^{\text {b }}$ | 1.259 | 0.096 |
|  | 9() | 3.419* | 1.259 | 0.007 |
| 7) | 60 | -7.703* | 1.259 | <().)() 1 |
|  | 65 | -2.969* | 1.259 | (0.019 |
|  | 75 | 2.975* | 1.259 | (0.019 |
|  | 80 | +.851* | 1.259 | <().)() 1 |
|  | 85 | $-0.867^{\text {b }}$ | 1.259 | 0.491 |
|  | 9() | $0.450^{\text {b }}$ | 1.259 | (0.721 |
| 75 | 60 | -10.678* | 1.259 | <().)() ) |
|  | 65 | -5.9+4* | 1.259 | <().()) 1 |
|  | 70 | -2.957* | 1.259 | (0.019 |
|  | 80 | $1.876^{\text {b }}$ | 1.259 | 0.137 |
|  | 85 | -3.8-42* | 1.259 | ().0)2 |
|  | 9() | -2.524* | 1.259 | ().046 |
| 8() | 60 | -12.554* | 1.259 | <().)() 1 |
|  | 65 | -7.82()* | 1.259 | <().)() ) |
|  | 7 () | -4.851* | 1.259 | <().)(0) |
|  | 75 | $-1.876^{\text {b }}$ | 1.259 | (0.137 |
|  | 85 | -5.718* | 1.259 | <().0) 1 |
|  | 90 | -4.40)* | 1.259 | ().00) |
| 85 | 60 | -6.836* | 1.259 | <().)() 1 |
|  | 65 | $-2.102^{\text {b }}$ | 1.259 | 0.096 |
|  | 7() | $0.867^{\text {b }}$ | 1.259 | ().491 |
|  | 75 | 3.8.+2* | 1.259 | ().0)2 |
|  | 80 | 5.718* | 1.259 | <().)() 1 |
|  | 9() | $1.317^{\text {b }}$ | 1.259 | 0.296 |
| 90 | 60 | -8.154* | 1.259 | <().)() 1 |
|  | 65 | -3.419* | 1.259 | ().0) 7 |
|  | 7) | $-0.450^{\text {b }}$ | 1.259 | (0.721 |
|  | 75 | 2.524* | 1.259 | (0.)46 |
|  | $8($ | +.4())* | 1.259 | ().)(0) |
|  | 85 | $-1.317^{\text {b }}$ | 1.259 | (0.296 |

Based on estimated marginal means
*. The mean difference is significant at the 0.5 level
a. Adjustment for multiple comparisons: Bonferroni
b. An estimate of the modified population marginal mean (l)

### 2.1.1 Angle at one level of ROI

Pairwise comparisons comparing angle means at one level of ROl when ROl's are in a palmar position.
Depedent variable:MEAN

| ROI | (1) ANGLE | (J) ANGLE | Mean Difference (1-J) | Std. Error | $\begin{gathered} \mathrm{T} \\ \text { value } \end{gathered}$ | Degrees of freedon | Significance ${ }^{\text {a }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 60 | 65 | 7.27() | $2.81+$ | 2.583 | +()8 | 0.213 |
|  |  | 70 | 11.614 | 2.814 | +.127 | +1)8 | (0.)(0) |
|  |  | 75 | 16.679 | 2.814 | 5.927 | $4(18$ | <().()) 1 |
|  |  | 80 | 19.760) | $2.81+$ | 7.122 | +108 | <().0) ${ }^{\text {a }}$ |
|  |  | 85 | $1+.355$ | $2.81+$ | 5.101 | 418 | <0.0) 01 |
|  |  | 90 | $16.32+$ | $2.81+$ | 5.801 | +(1) | <0.)(0) 1 |
|  | 65 | 60 | -7.27() | $2.81+$ | -2.583 | +1)8 | (0.213 |
|  |  | 70 | +.34+ | $2.81+$ | $1.5+4$ | $4(18$ | $1.000)$ |
|  |  | 75 | 9.4() 9 | $2.81+$ | 3.3+4 | +(1) | (0.019 |
|  |  | 80 | 12.491 | $2.81+$ | +.4.39 | +(1)8 | <0.)(0) 1 |
|  |  | 85 | 7.086 | 2.814 | 2.518 | +(1) | 0.256 |
|  |  | 9() | 9.055 | $2.81+$ | 3.218 | $4(18$ | (0.)29 |
|  | 71 | 60 | -11.614 | 2.814 | -4.127 | +()8 | ().)(0) |
|  |  | 65 | -4.344 | 2.814 | -1.54t | +()8 | $1.000)$ |
|  |  | 75 | 5.065 | 2.814 | $1.800)$ | +()8 | $1.000)$ |
|  |  | 8() | 8.147 | 2.814 | 2.895 | +()8 | (0.08t |
|  |  | 85 | $2.7+2$ | 2.814 | 0.974 | $4(1)$ | $1.000)$ |
|  |  | 9() | +.711 | 2.814 | 1.674 | +()8 | $1.000)$ |
|  | 75 | 60 | -16.679 | 2.814 | -5.927 | -1)8 | <().0) ${ }^{\text {(1) }}$ |
|  |  | 65 | -9.4()9 | $2.81+$ | -3.344 | 408 | (0.019 |
|  |  | 70 | -5.065 | $2.81+$ | -1.80) | +()8 | $1.000)$ |
|  |  | 80 | 3.081 | $2.81+$ | 1.095 | +(1)8 | 1.000 |
|  |  | 85 | -2.32-t | 2.814 | -0.826 | $4(18$ | $1.000)$ |
|  |  | 9() | -0.35+ | $2.81+$ | -0.126 | +()8 | 1.000 |
|  | 80 | 60 | -19.760) | 2.814 | -7.122 | -1(1) | <().0) 1 |
|  |  | 65 | -12.491 | $2.81+$ | $-4.4 .39$ | -148 | <().0) 1 |
|  |  | 70 | -8.147 | 2.814 | -2.895 | -1(1) | 0.084 |
|  |  | 75 | -3.081 | $2.81+$ | -1.095 | $4(1)$ | $1.000)$ |
|  |  | 85 | -5.405 | $2.81+$ | -1.921 | +()8 | $1.000)$ |
|  |  | 9() | -3.4.36 | $2.81+$ | -1.221 | +(1) | $1.000)$ |
|  | 85 | 60 | -1+.355 | $2.81+$ | -5.101 | +1)8 | <().)(0) |
|  |  | 65 | -7.086 | 2.814 | -2.518 | +(1)8 | 0.256 |
|  |  | 70 | -2.7+2 | $2.81+$ | -(0.974 | +(1)8 | $1.000)$ |
|  |  | 75 | 2.324 | $2.81+$ | 0.826 | +1)8 | $1.000)$ |
|  |  | 80 | $5.4(1)$ | $2.81+$ | 1.921 | -4)8 | 1.000 |
|  |  | 9() | 1.969 | $2.81+$ | (0.70) | -1)8 | $1.000)$ |
|  | 9() | 60 | -16.32t | $2.81+$ | -5.801 | +(1)8 | <().)(0) |
|  |  | 65 | -9.055 | 2.814 | -3.218 | -108 | (0.029 |
|  |  | 70 | -4.711 | 2.814 | -1.67t | $4(1)$ | $1.000)$ |
|  |  | 75 | 0.35.4 | 2.814 | 0.126 | $4(1)$ | 1.000 |
|  |  | 80 | $3 .+36$ | 2.814 | 1.221 | -108 | 1.000 |
|  |  | 85 | -1.969 | 2.814 | -0.70) | +(1) | 1.000 |
| 2 | 60 | 65 | 5.695 | $2.81+$ | $2.02+$ | +(1) | 0.917 |
|  |  | 7) | 6.778 | 2.814 | 2.4()9 | $4(1)$ | 0.346 |
|  |  | 75 | $10.30 .+$ | $2.81+$ | 3.662 | +(1) | 0.006 |
|  |  | 80 | 11.235 | 2.814 | 3.992 | $4(1)$ | (0.0)() |


| （）0）${ }^{\text {－}}$ | $80 \dagger$ | 8＋9 ${ }^{\text {（）－}}$ | ＋18． | ¢28 ${ }^{-}$ | 59 |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $000{ }^{\circ} 1$ | 80） | LてE゙「－ | ＋18．2 | $9 L^{\circ} \mathrm{C}$ | 09 | （）L |  |
| （）0）$)^{1}$ | $80 \dagger$ | L9て「 | ＋182 | 995 | 06 |  |  |
| $000 \cdot 1$ | 80）+ | ¢0） 1 | ＋18．2 | ¢28て | 58 |  |  |
| $80)^{\circ}()$ | $80 \dagger$ | ¢18て | ＋182 | $916{ }^{\circ} \mathrm{L}$ | () 8 |  |  |
| （）（））${ }^{\circ}$ | $80 \uparrow$ | 616．1 | ＋182 | $10+5$ | SL |  |  |
| （）（0） 1 | 80 ＋ | 8＋9 ${ }^{(0)}$ | ＋18．2 | ¢28 I | （）L |  |  |
| $000{ }^{\circ} 1$ | $80 \dagger$ | 6L9 ${ }^{\text {（）－}}$ | ＋18． | $116{ }^{\circ}{ }^{-}$ | （）9 | 59 |  |
| （）（）） 1 | 80）$\dagger$ | $9+6.1$ | $\dagger 18$ ¢ | LLけS | 06 |  |  |
| （）（））${ }^{\text {I }}$ | 80）$\dagger$ | 289 ${ }^{\text {I }}$ | ＋18．2 | ナEL＇$\dagger$ | 58 |  |  |
| II（） 0 | 80 ＋ | 26け＇s | ＋18．2 | L286 | () 8 |  |  |
| ＋（）で） | 80）$\dagger$ | 86ごて | ＋182 | E1E゙し | 5 |  |  |
| （）（）） 1 | 80 ＋ | Lてご1 | ＋182 | 9 9\％ | （）L |  |  |
| （）（））${ }^{\prime}$ | $80 \dagger$ | 6L9（） | ＋182 | $116{ }^{\circ}$ | 59 | 09 | 5 |
| （）（））${ }^{\circ}$ | 80）$\dagger$ | ¢¢ご0－ | ＋182 | ＋ち6（）－ | ¢8 |  |  |
| （）（）） 1 | 80）$\dagger$ | （）26． | †18て | て）+ ¢ | （）8 |  |  |
| （0）（） 1 | 80 ＋ | 685 I | ＋18て | ILt $\dagger$ | $\leq 1$ |  |  |
| （）0）${ }^{\prime}$ | 80 ） | 9ゼぐ） | ＋18て | S†6\％ | （）L |  |  |
| $000)^{\circ}$ | 80 ＋ | $\left.6+()^{\circ}\right)^{-}$ | ＋18て | $\left.8 \mathrm{Cl}^{\circ}\right)^{-}$ | 59 |  |  |
| SI80 | $80+$ | ご（）${ }^{-}$ | ＋18て | cc8s－ | （）9 | 06 |  |
| $000)^{\circ}$ | $80 \dagger$ | ¢¢ご） | ＋18て | ＋560） | 06 |  |  |
| 8150 | $80+$ | ¢くでて | ＋18て | 9 9ど9 | $(1)$ |  |  |
| （）（0）I | $80 \dagger$ | ＋て6．1 | ＋18て | SItS | SL |  |  |
| $000{ }^{\circ} \mathrm{I}$ | $80 \dagger$ | IL9 0 | ＋18て | $688{ }^{\circ}$ | （）L |  |  |
| $000)^{\prime}$ | $80 \dagger$ | $987^{\circ}$（） | ＋18て | $908^{\circ} 0$ | 59 |  |  |
| （0）（） 1 | $80 \dagger$ | L゙く「1－ | ＋18て | $688{ }^{+}$ | （）9 | 58 |  |
| （）0）$)^{\circ}$ | $80+$ | （）26 ${ }^{-}$ | ＋18て | て）+ － | 06 |  |  |
| 8150 | $80+$ | ¢ ¢ て－ | ＋18て | $9+$－ 9 － | 58 |  |  |
| $000)^{\circ}$ | 80） | IEぐ（）－ | ＋18て | $156{ }^{\circ}$ | SL |  |  |
| 0 （）0 ${ }^{\circ}$ | $80 \dagger$ | ＋8S $\mathrm{I}^{-}$ | ＋18て | LSt＋ | （）L |  |  |
| 0 （）0 ${ }^{\circ}$ | $80 \dagger$ | $696{ }^{\circ}$ | †18て | O） O－S $^{\text {c }}$ | 59 |  |  |
| 200） | $80+$ | 266\％${ }^{\circ}$ | ＋18て | ¢¢でIT | （）9 | 08 |  |
| （）00 ${ }^{\circ}$ | $80+$ | 685 ${ }^{-}$ | ＋18て | ILけ ${ }^{\text {－}}$ | （）6 |  |  |
| （）0）${ }^{\prime}$ | $80+$ | ＋26 ${ }^{-}$ | †18て | SIts－ | 58 |  |  |
| $000{ }^{\circ}$ | $80+$ | Iとご（） | ＋18て | 1560 | （）8 |  |  |
| （）0）${ }^{\text {I }}$ | $80+$ | こくで1－ | ＋18て | 9てござ | （）L |  |  |
| （）00 ${ }^{\circ}$ | $80+$ | 859 ${ }^{\circ}$ | ＋18て | $609{ }^{+-}$ | 59 |  |  |
| $900{ }^{\circ}$ | $80+$ | 299 \％－ | ＋18て | †（）co ${ }^{-1}$ | （）9 | $\subseteq$ |  |
| 0 （）0 ${ }^{\circ}$ | $80+$ | 9EC（）－ | †18て | St6（）－ | 06 |  |  |
| 0 （）0 ${ }^{\circ}$ | $80+$ | IL9（）－ | ＋18て | $688{ }^{\circ}{ }^{-}$ | 58 |  |  |
| （）O（） 1 | $80+$ | ＋8s．1 | ＋18て | LSt $\dagger$ | () 8 |  |  |
| $000{ }^{\circ}$ | $80+$ | とこで1 | †18て | 92¢ ¢ | SL |  |  |
| $000{ }^{\circ}$ | $80 \dagger$ | S850 ${ }^{-}$ | ＋18て | ¢80 ${ }^{\circ}{ }^{-}$ | 59 |  |  |
| $9+$ c゙o | $80+$ | $6(1){ }^{+}$ | ＋18て | 8LL＇9－ | （）9 | （）L |  |
| $000{ }^{\circ}$ | $80+$ | $6+0{ }^{\circ}$ | ＋18て | 8E10） | （）6 |  |  |
| （）0）${ }^{\circ}$ | $80 \dagger$ | $987^{\circ}()^{-}$ | †18て | $\left.908{ }^{\circ}\right)^{-}$ | 58 |  |  |
| $000{ }^{\circ} \mathrm{I}$ | $80+$ | 6961 | †18て | （）＋5゙S | （）8 |  |  |
| （）（））${ }^{\text {I }}$ | $80+$ | 859 ${ }^{\circ}$ | ＋18て | $609 \dagger$ | SL |  |  |
| $000{ }^{\circ} \mathrm{I}$ | $80+$ | S8C゚） | ＋18て | c80 ${ }^{\circ}$ | （）L |  |  |
| $\angle 16{ }^{\circ}$ | $80 \dagger$ | ＋て0で－ | †18て | S69 ${ }^{-}$ | （）9 | 59 |  |
| SI80 | 80 | 〔L（）て | ＋182 | cc8s | （）6 |  |  |
| （）（）） 1 | $80 \dagger$ | LEL＇I | ＋18． | 688 † | S8 |  |  |


| $000{ }^{\circ}$ | 80） | （188 ${ }^{\circ} \mathrm{I}^{-}$ | ＋18\％ | 288 ¢－ | 06 |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $000{ }^{\circ} \mathrm{I}$ | 80 ） | 688 ${ }^{-}$ | ＋18．2 | ¢IC゚S | 58 |  |  |
| 0 （）0 ${ }^{\text {I }}$ | $80+$ | $867^{\circ} 0$ | ＋182 | （）＋8（） | $(08$ |  |  |
| $000{ }^{\circ} \mathrm{I}$ | 80）+ | $\left.68 L^{\circ}\right)^{-}$ | ＋182 | 0てでで | （）L |  |  |
| $885^{\circ}()$ | $80+$ | ¢（）でで－ | ＋182 | S（）で9－ | S9 |  |  |
| $1000^{\circ}$ | $80 \dagger$ | ¢60 ${ }^{\text {＋}}$ | ＋18． | 8IS゚I「 | （）9 | $\leq 1$ |  |
| $000{ }^{\circ}$ | 80） | 16S ${ }^{-}$ | †18て | ¢99 ${ }^{-1}$ | 06 |  |  |
| $000{ }^{\circ}$ | 80） | $00 \mathrm{I}^{\circ} \mathrm{I}^{-}$ | †18て | $960{ }^{\circ} \mathrm{C}$ | 58 |  |  |
| （0）0 ${ }^{\circ}$ | 80）$\dagger$ | L80 ${ }^{\text {I }}$ | †18て | $6 \leq 0{ }^{\circ} \mathrm{C}$ | （）8 |  |  |
| $000{ }^{\circ} \mathrm{I}$ | $80 \dagger$ | $68 L^{\circ} 0$ | ＋18\％ | （）てでて | SL |  |  |
| $000{ }^{\circ}$ | $80+$ | 91＋「－ | ＋18て | S86 ${ }^{\circ}$ | 59 |  |  |
| て20） 0 | $80+$ | †（0）${ }^{\text {c－}}$ | ＋182 | $66 て ゙ 6-$ | （）9 | （）L |  |
| （）00）I | 80） | ¢て80 | ＋18て | ててc゙て | 06 |  |  |
| $000{ }^{\circ} \mathrm{I}$ | 80）+ | 91ぐ0 | ＋182 | $068{ }^{\circ}$ | 58 |  |  |
| L9で0 | 80） | ¢0¢て | ＋18て | $\dagger+()^{\circ} \mathrm{L}$ | $(1)$ |  |  |
| 88500） | 80） | ¢（）でて | ＋18て | ¢（）で9 | $\leq 1$ |  |  |
| （）0）$)^{\circ} 1$ | 80） | 91ナ1 | ＋18\％ | ¢86\％ | （）L |  |  |
| （）0）I | $80+$ | $888{ }^{1-}$ | ＋18て | †¢゙s－ | （）9 | 59 |  |
| $9 \dagger^{\circ}(0)$ | $80+$ | ¢IL＇て | ＋18て | $99^{\circ} \mathrm{L}$ | 06 |  |  |
| $685^{\circ}()$ | $80+$ | †（）でて | †18て | と（）で9 | 58 |  |  |
| I（））（0） | $80+$ | $16 ¢ 5$ | ＋18て | 8ごでて | $(08$ |  |  |
| ［（0） $0^{\circ}$（ | $80 \dagger$ | ¢60 $\dagger$ | ＋18て | 8IS゙11 | $\leq 1$ |  |  |
| 220） | 80） | †（）ごく | ＋182 | $662 \%$ | （）L |  |  |
| $000)^{\circ}$ | $80+$ | 888 I | ＋18て | †1¢9 | 59 | 09 | $\dagger$ |
| $000)^{\circ}$ | $80+$ | †9で（）－ | ＋18て | ctLo ${ }^{-}$ | 58 |  |  |
| $000)^{\prime}$ | $80+$ | 9 9ご1 | ＋18て | （）Sc゙t | 08 |  |  |
| （0）（）＇ 1 | 80）$\dagger$ | て59（） | ＋18\％ | ¢c81 | SL |  |  |
| $000)^{\prime}$ | $80+$ | $6190)^{-}$ | ＋18て | て＋ $\mathrm{L}^{\circ} \mathrm{T}^{-}$ | （）L |  |  |
| $000)^{\circ}$ | $80+$ | L9で1－ | ＋18て | 99¢ $0^{-}$ | 59 |  |  |
| $000{ }^{\circ} \mathrm{I}$ | $80 \dagger$ | $9+6{ }^{\circ}$ | ＋18て | $L L+\bigcirc$ | （）9 | 06 |  |
| O（）$)^{\circ}$ | $80+$ | ＋9で） | †18て | C†L＇（） | 06 |  |  |
| $000)^{\prime}$ | $80+$ | （）18 I | ＋182 | ¢60） | $(08$ |  |  |
| $00(0) 1$ |  | $916 \%$ | ＋18て | 8LS゙て | $\leq L$ |  |  |
| $000)^{\circ}$ | $80+$ | Scso ${ }^{-}$ | ＋18て | $866{ }^{\circ}$ | （）L |  |  |
| $00(0) 1$ | $80 \dagger$ | ¢0） $0 \mathrm{I}^{-}$ | ＋18て | こて8で | 59 |  |  |
| $000{ }^{\circ} \mathrm{I}$ | $80 \dagger$ | $289{ }^{\circ}{ }^{-}$ | ＋18て | †¢ $\mathrm{L}^{+}$ | （）9 | 58 |  |
| $000{ }^{\circ} \mathrm{I}$ | $80+$ | $9+5{ }^{1-}$ | ＋18て | （）Sぐ「－ | 06 |  |  |
| $000{ }^{\circ} \mathrm{I}$ | $80+$ | $018 \mathrm{I}^{-}$ | ＋18て | ¢60 ${ }^{-}$ | 58 |  |  |
| $000{ }^{\circ} \mathrm{I}$ | $80+$ | ＋68（）－ | ＋18て | ごらで | SL |  |  |
| IS900 | $80 \dagger$ | ¢91 ${ }^{\text {－}}$ | †18て | 260 ${ }^{-}$ | （）L |  |  |
| 8010 | $80+$ | とI8で | ＋18て | $916{ }^{\circ}$ | 59 |  |  |
| $1100^{\circ}$ | $80+$ | て6けと－ | ＋18て | L28 $6^{-}$ | （）9 | $(08$ |  |
| $000{ }^{\circ} \mathrm{I}$ | $80 \dagger$ | てく9＊${ }^{-}$ | ＋18て | SE8 ${ }^{-}$ | （）6 |  |  |
| $000{ }^{\circ} \mathrm{I}$ | $80+$ | $916{ }^{\circ} 0^{-}$ | ＋18て | 8LS「で | 58 |  |  |
| $000{ }^{\circ} \mathrm{I}$ | $80 \dagger$ | †680） | †18て | ¢！ | $(1)$ |  |  |
| $000{ }^{\circ} \mathrm{I}$ | $80+$ | 1Lで「－ | ＋18て | LLS゙く－ | （）L |  |  |
| $000)^{\circ}$ | $80 \dagger$ | 616．1－ | †18て | $\mathrm{I} 0+\mathrm{S}-$ | 59 |  |  |
| toで） | $80 \dagger$ | $86 \leq{ }^{\circ}$ | ＋18て | ごごじ | （）9 | $\leq L$ |  |
| $000{ }^{\circ} \mathrm{I}$ | $80 \dagger$ | 6190） | †18て | でL＇I | 06 |  |  |
| $000{ }^{\circ} \mathrm{I}$ | $80+$ | çc゙o | ＋18て | $866{ }^{\circ}$ | 58 |  |  |
| I S90 ${ }^{\text {（ ）}}$ | $80 \dagger$ | ¢917\％ | ＋18．て | 260）9 | （）8 |  |  |
| $000{ }^{\prime} \mathrm{I}$ | $80+$ | ILて＇I | ＋18て | LLS゙く | $\bigcirc$ SL |  |  |


|  | 8() | 60 | -12.358 | 2.814 | $-4.391$ | 4() 8 | <().()()] |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 65 | -7.()44 | 2.814 | -2.5()3 | 4() 8 | (0.267 |
|  |  | 7() | -3.059 | 2.814 | -1.087 | 4() 8 | $1 .()()$ |
|  |  | 75 | -().84() | 2.814 | -().298 | 4() 8 | $1 .()()$ |
|  |  | 85 | -6.155 | 2.814 | -2.187 | 4() 8 | (0.615 |
|  |  | 9() | -4.722 | 2.814 | -1.678 | 4() 8 | 1.()()) |
|  | 85 | 60 | -6.203 | 2.814 | -2.20) | $4(1)$ | (0.589 |
|  |  | 65 | -().89() | 2.814 | -(0.316 | 4() 8 | $1.0(0)$ |
|  |  | 7() | 3.096 | 2.814 | 1.1()() | +()8 | $1.0(0)$ |
|  |  | 75 | 5.315 | 2.814 | 1.889 | +()8 | $1.0(0)$ |
|  |  | $8($ | 6.155 | 2.814 | 2.187 | +()8 | (0.615 |
|  |  | $9($ | 1.433 | 2.814 | (0.5()9 | $4(1)$ | 1.0()() |
|  | 9() | 60 | -7.6.36 | 2.814 | -2.713 | +()8 | (0.146 |
|  |  | 65 | -2.322 | 2.814 | -(0.825 | +()8 | $1.0(0)$ |
|  |  | 7() | 1.66 .3 | 2.814 | (0.591 | +()8 | $10(0)$ |
|  |  | 75 | 3.882 | 2.814 | 1.38() | +()8 | $1.0(0)$ |
|  |  | 8() | 4.722 | 2.814 | 1.678 | +()8 | $1 .(0)()$ |
|  |  | 85 | $-1+33$ | 2.81+ | -(0.5()9 | +()8 | $1.0(0)$ |
| 5 | 6() | 65 | 3.484 | 2.814 | 1.238 | $4(08$ | 1.00() |
|  |  | 7() | 7.091 | 2.814 | 2.52() | 4() 8 | (0.255 |
|  |  | 75 | 7.577 | $2.81+$ | 2.693 | +()8 | (0.155 |
|  |  | 8() | 9.591 | 2.81+ | $3.4(1)$ | 4() 8 | (0.015 |
|  |  | 85 | t.()()1 | 2.814 | $1 .+22$ | $4(08$ | $1.0(0)$ |
|  |  | 90 | 5.498 | $2.81+$ | 1.954 | +()8 | $1.0(0)$ |
|  | 65 | 6() | -3.484 | 2.814 | -1.2.38 | +()8 | $1.0(0)$ |
|  |  | 70) | 3.607 | 2.814 | 1.282 | 4()8 | 1.0()() |
|  |  | 75 | 4.094 | 2.814 | 1.455 | 4() 8 | $1.0(0)$ |
|  |  | 8() | 6.107 | 2.814 | 2.17() | +()8 | (0.642 |
|  |  | 85 | (0.517 | 2.814 | ().184 | +()8 | $1 .()()()$ |
|  |  | 9() | 2.014 | $2.81+$ | 0.716 | +()8 | $1.0(0)$ |
|  | $71)$ | 60 | -7.091 | $2.81+$ | -2.52() | +()8 | (0.255 |
|  |  | 65 | -3.6()7 | 2.814 | $-1.282$ | +()8 | 1.0()() |
|  |  | 75 | 0. 486 | $2.81+$ | ().173 | +()8 | $1.0(0)$ |
|  |  | 8() | 2.50() | 2.814 | ().888 | +()8 | $1 .()()()$ |
|  |  | 85 | -3.()9() | $2.81+$ | -1.098 | -408 | $1.0(0)$ |
|  |  | $9($ | $-1.593$ | 2.814 | -().566 | +()8 | 1.0()() |
|  | 75 | 6() | -7.577 | 2.81+ | $-2.693$ | $4(08$ | (0.155 |
|  |  | 65 | $-4.09+$ | 2.814 | $-1.455$ | $4(08$ | 1.()()() |
|  |  | 7() | -().486 | 2.814 | -().173 | $4(08$ | $1 .()()()$ |
|  |  | 8() | 2.013 | 2.814 | 0.715 | $4(08$ | $1.000)$ |
|  |  | 85 | -3.577 | 2.814 | -1.271 | $4(08$ | 1.0()() |
|  |  | $9($ | -2.079 | 2.81t | -().739 | $4(08$ | $1.0(0)$ |
|  | 8() | 60 | -9.591 | 2.814 | -3.4()8 | +()8 | (0.)15 |
|  |  | 65 | -6.107 | 2.814 | -2.17() | 4() 8 | (0.642 |
|  |  | 7) | -2.5()() | 2.814 | -().888 | +()8 | $1 .()(0)$ |
|  |  | 75 | -2.013 | 2.814 | -(0.715 | 4() 8 | $1 .()()()$ |
|  |  | 85 | -5.59() | 2.814 | -1.986 | 4() 8 | $1 .(0)()$ |
|  |  | 9() | -4.09.3 | 2.814 | $-1.454$ | 4() 8 | $1 .(0)()$ |
|  | 85 | 6() | $-4.0() 1$ | 2.814 | $-1.422$ | 4() 8 | $1 .()(0)$ |
|  |  | 65 | -(0.517 | 2.814 | -0.184 | +()8 | $1 .()(0)$ |
|  |  | 7) | 3.090 | 2.814 | 1.098 | 4() 8 | 1.00() |
|  |  | 75 | 3.577 | 2.814 | 1.271 | +()8 | 1.()()() |


|  |  | 80 | 5.59() | 2.814 | 1.986 | 408 | 1.0()() |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $9(0$ | 1.497 | 2.814 | 0.532 | 408 | 1.0()() |
|  | $9(0$ | 60 | -5.498 | 2.814 | -1.954 | 408 | 1.0()() |
|  |  | 65 | -2.014 | 2.814 | -0.716 | 408 | $1.0(0)$ |
|  |  | 70 | 1.593 | 2.814 | 0.566 | 408 | $1.0(0)$ |
|  |  | 75 | 2.079 | 2.814 | 0.739 | 408 | $1.0(0)$ |
|  |  | 80 | 4.093 | 2.814 | 1.454 | 408 | $1.0(0)$ |
|  |  | 85 | -1.497 | 2.814 | -0.532 | 408 | $1.0(0)$ |

Based on estimated marginal means
a. Adjustment for multiple comparisons: Bonferroni

An estimate of the modified population marginal mean (1)
2.1.2 Angle at one level of group

Pairwise comparisons to compare angle while holding group (non-exercise) constant when ROI's are in a palmar position.

Dependent Variable: MEAN

| (I) ANGLE | (J) ANGLE | Mean Difference (I-J) | Std. Error | T value | Degrees of freedom | Significance ${ }^{\text {a }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 60 | 65 | 1.859 | 1.780 | $1.04+$ | $4(1)$ | 1.000 () |
|  | 7) | 5.340 | 1.780 | $3.000)$ | 408 | 0.06() |
|  | 75 | 7.681 | 1.780 | 4.316 | $4(1)$ | <().0) () |
|  | 80 | 10.323 | 1.780 | 5.80 () | $4(1)$ | <().()) 1 |
|  | 85 | +. 168 | 1.780 | $2.3+2$ | +()8 | (0.413 |
|  | 9() | 5.125 | 1.780 | 2.879 | $4(18$ | 0.088 |
| 65 | 60 | -1.859 | 1.780 | -1.0+4 | +()8 | $1.000)$ |
|  | 7) | 3.481 | 1.780 | 1.956 | $4(1)$ | 1.0()$)$ |
|  | 75 | 5.822 | 1.780 | 3.271 | $4(1)$ | 0.024 |
|  | 8() | 8.464 | 1.780 | 4.756 | +()8 | <().()) 1 |
|  | 85 | 2.309 | 1.780 | 1.297 | $4(1)$ | $1.000)$ |
|  | 9() | 3.266 | 1.780 | 1.835 | +()8 | $1.000)$ |
| 7) | 60 | -5.34() | 1.780 | -3.00)(0) | $4(1)$ | (0.060) |
|  | 65 | -3.481 | 1.780 | -1.956 | 408 | $1.000)$ |
|  | 75 | $2.3+1$ | 1.780 | 1.316 | $4(1)$ | $1.000)$ |
|  | 80 | 4.983 | 1.780 | 2.800 | $4(1)$ | (0.112 |
|  | 85 | -1.172 | 1.780 | -0.658 | +()8 | $1.000)$ |
|  | 90 | -0.215 | 1.780 | -(0.121 | +()8 | $1.000)$ |
| 75 | 60 | -7.681 | 1.780 | -4.316 | +()8 | <().0) 1 |
|  | 65 | -5.822 | 1.780 | -3.271 | $4(1)$ | 0.024 |
|  | 7() | -2.3+1 | 1.780 | -1.316 | $4(1)$ | $1.000)$ |
|  | 80 | 2.642 | 1.780 | 1.484 | +()8 | $1.000)$ |
|  | 85 | -3.513 | 1.780 | -1.974 | $4(1)$ | $1.000)$ |
|  | 9() | -2.556 | 1.780 | $-1.436$ | $4(1)$ | $1.0(0)$ |
| 80 | 60 | -10.32.3 | 1.780 | -5.80) | $4(1)$ | <(0.)() 1 |
|  | 65 | -8.464 | 1.780 | $-4.756$ | $4(1)$ | <().0) 1 |
|  | 7 () | -4.983 | 1.780 | -2.80) | $4(1)$ | (0.112 |
|  | 75 | -2.6+2 | 1.780 | -1.484 | +()8 | $1.000)$ |
|  | 85 | -6.155 | 1.780 | -3.4.48 | +()8 | 0.013 |
|  | 9() | -5.198 | 1.780 | -2.921 | +()8 | (0.077 |
| 85 | 60 | -+.168 | 1.780 | -2.3+2 | +()8 | 0.413 |
|  | 65 | -2.309 | 1.780 | -1.297 | $4(1)$ | $1.000)$ |
|  | 7 ) | 1.172 | 1.780 | 0.658 | $4(1)$ | $1.000)$ |
|  | 75 | 3.513 | 1.780 | 1.974 | +()8 | 1.000 |
|  | 80 | 6.155 | 1.780 | 3.458 | $4(8)$ | 0.013 |
|  | 90 | 0.957 | 1.780 | 0.5 .38 | $4(1)$ | $1.000)$ |
| 9() | 60 | -5.125 | 1.780 | -2.879 | +()8 | 0.088 |
|  | 65 | -3.266 | 1.780 | -1.835 | $4(1)$ | $1.000)$ |
|  | 7 () | 0.215 | 1.780 | (0.121 | +()8 | $1.000)$ |
|  | 75 | 2.556 | 1.780 | 1.4.36 | +()8 | $1.000)$ |
| - | 80 | 5.198 | 1.780 | 2.921 | +()8 | 0.077 |
|  | 85 | -(0.957 | 1.780 | -(0.5.38 | +()8 | $1.000)$ |

Based on estimated marginal means
a. Adjustment for multiple comparisons: Bonferroni

An estimate of the modified population marginal mean (I)

Pairwise comparisons to compare angle while holding group (exercise) constant
Dependent Variable: MEAN

| Angle (I) | Angle(J) | Mean difference $(\mathrm{I}-\mathrm{J})$ | Std Error | T Value | Degrees of freedom | Significance ${ }^{\text {d }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 61 | 65 | 7.610 | 1.780 | +.276 | +()8 | <().0) ${ }^{\text {a }}$ |
|  | 7) | 10.067 | 1.780 | 5.656 | +()8 | <(0.)(0) |
|  | 75 | 13.675 | 1.780 | 7.684 | $4(1)$ | <(0.)() 1 |
|  | $8($ | 14.785 | 1.780 | 8.307 | $4(1)$ | <().0) ${ }^{\text {a }}$ |
|  | 85 | 9.505 | 1.780 | $5.3+1$ | +(1) | <().)(0) |
|  | 9() | 11.183 | 1.780 | 6.283 | +()8 | <().0) 01 |
| 65 | 60 | -7.610 | 1.780 | -4.276 | +()8 | <().()0) |
|  | 7) | $2 .+57$ | 1.780 | 1.380 | +()8 | $1.0)(0$ |
|  | 75 | 6.065 | 1.780 | 3.408 | +()8 | 0.015 |
|  | 80 | 7.175 | 1.780 | +. 031 | +()8 | 0.001 |
|  | 85 | 1.895 | 1.780 | 1.065 | +()8 | $1.000)$ |
|  | 9() | 3.573 | 1.780 | 2.007 | +()8 | 0.953 |
| 7) | 60 | -10.067 | 1.780 | -5.656 | +()8 | <().()0) |
|  | 65 | -2.457 | 1.780 | -1.380 | +(1) | $1.000)$ |
|  | 75 | 3.608 | 1.780 | 2.027 | $4(1)$ | 0.909 |
|  | 80 | 4.718 | 1.780 | 2.651 | +(1) | 0.175 |
|  | 85 | -0.562 | 1.780 | -(0.316 | +()8 | $1.000)$ |
|  | 9() | 1.116 | 1.780 | 0.627 | 408 | $1.000)$ |
| 75 | 61 | -13.675 | 1.780 | -7.684 | +()8 | <().0) 1 |
|  | 65 | -6.065 | 1.780 | -3.408 | +()8 | 0.015 |
|  | 7) | -3.608 | 1.780 | -2.027 | +()8 | 0.909 |
|  | 80 | 1.110 | 1.780 | 0.624 | +()8 | $1.000)$ |
|  | 85 | -4.17() | 1.780 | -2.3+3 | +()8 | 0.412 |
|  | 9() | -2.492 | 1.780 | -1.40) | +()8 | 1.00() |
| 80 | 60 | -14.785 | 1.780 | -8.307 | +(1)8 | <().)(0) 1 |
|  | 65 | -7.175 | 1.780 | -4.031 | 408 | 0.001 |
|  | 70 | -4.718 | 1.780 | -2.651 | +()8 | 0.175 |
|  | 75 | -1.11() | 1.780 | -0.624 | +()8 | 1.000 |
|  | 85 | -5.280) | 1.780 | -2.967 | +()8 | 0.067 |
|  | 9() | -3.603 | 1.780 | -2.024 | +()8 | 0.916 |
| 85 | 60 | -9.505 | 1.780 | -5.3+1 | +188 | <().()) 1 |
|  | 65 | -1.895 | 1.780 | -1.065 | +()8 | $1.000)$ |
|  | 7 ) | 0.562 | 1.780 | 0.316 | $4(18$ | $1.000)$ |
|  | 75 | +.17() | 1.780 | $2.3+3$ | $4(1)$ | 0. +12 |
|  | 80 | 5.280 | 1.780 | 2.967 | $4(1)$ | 0.067 |
|  | 90 | 1.678 | 1.780 | 0.943 | +()8 | $1.000)$ |
| 9() | 60 | -11.183 | 1.780 | -6.283 | $4(1)$ | <().0) ${ }^{\text {l }}$ |
|  | 65 | -3.573 | 1.780 | -2.0) 07 | 408 | 0.953 |
|  | 7) | -1.116 | 1.780 | -0.627 | $4(1)$ | $1.000)$ |
|  | 75 | 2.492 | 1.780 | 1.40) | $4(18$ | $1.000)$ |
|  | $8($ | 3.603 | 1.780 | $2.02+$ | $4(18$ | 0.916 |
|  | 85 | -1.678 | 1.780 | -(0.9+3 | $4(18$ | 1.0)() |

### 2.2 Main effect of ROI

Pairwise comparisons to compare the main effect of ROI when ROI's are in a palmar position
Dependent Variable:MEAN

| ROI (1) | $\mathrm{ROI}(\mathrm{J})$ | Mean Difference (I-J) | Std error | Significance ${ }^{\text {a }}$ |
| :---: | :---: | :---: | :---: | :---: |
| 1 | 2 | 5.671* | 1.064 | $<(0).(0) 1$ |
|  | 3 | 9.101* | 1.064 | <().)(0) |
|  | $+$ | 8.015* | 1.064 | <().0) ${ }^{\text {l }}$ |
|  | 5 | 5.433* | $1.06+$ | <().)() 1 |
| 2 | 1 | 5.671* | $1.06+$ | <().)(0) |
|  | 3 | 3.430* | 1.064 | 0.0) 1 |
|  | $+$ | 2.34+* | 1.064 | ().028 |
|  | 5 | $0.238{ }^{\text {b }}$ | 1.064 | 0.823 |
| 3 | 1 | -9.1)1* | 1.064 | <().0) ${ }^{\text {I }}$ |
|  | 2 | -3.+3()* | $1.06+$ | ().0) |
|  | $+$ | $-1.085^{\text {b }}$ | 1.064 | 0.308 |
|  | 5 | -3.668* | 1.064 | 0.00) |
| 4 | 1 | -8.015* | 1.064 | <().00) |
|  | 2 | -2.3+4* | 1.064 | (0.)28 |
|  | 3 | $1.085^{\text {b }}$ | 1.064 | 0.308 |
|  | 5 | -2.583* | 1.064 | 0.016 |
| 5 | 1 | -5.433* | 1.064 | <().0) 1 |
|  | 2 | $0.238{ }^{\text {b }}$ | 1.064 | (0.823 |
|  | 3 | 3.668* | 1.064 | 0.0001 |
|  | $t$ | 2.583* | 1.064 | ().016 |

Based on estimated marginal means
*. The mean difference is significant at the 0.5 level
a. Adjustment for multiple comparisons: Bonferroni
b. An estimate of the modified population marginal mean (l)

### 2.2.1 ROl at one level of group

Pairwise comparisons comparing ROl means. holding group (non-exercise) constant when ROl's are in a palmar position.

Dependent variable: MEAN

| ROI (1) | ROI (j) | mean difference (I-J) | std err | t value | Degrees of freedom | Signifincance ${ }^{\text {d }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 2 | 9.007 | 1.504 | 5.989 | $4(1)$ | <().0) ${ }^{\text {l }}$ |
|  | 3 | 10.650 | 1.504 | 7.081 | +()8 | <().)(0) |
|  | 4 | 9.674 | 1.504 | 6.432 | +()8 | <().0) 1 |
|  | 5 | -0.5+5 | 1.504 | -(0.362 | +()8 | $1.000)$ |
| 2 | 1 | -9.0)( 7 | 1.504 | -5.989 | +()8 | <().0) 1 |
|  | 3 | $1.6+3$ | 1.504 | 1.092 | +()8 | $1.000)$ |
|  | 4 | 0.667 | 1.504 | (0.4+3 | $4(1)$ | 1.0)(0) |
|  | 5 | -9.552 | 1.504 | -6.351 | +(0) | <().)(0) 1 |
| 3 | 1 | -10.650) | 1.504 | -7.081 | +()8 | <().0) 1 |
|  | 2 | -1.6+3 | 1.504 | -1.092 | +()8 | $1.000)$ |
|  | $+$ | -(0.976 | 1.504 | -(0.64) | 408 | $1.000)$ |
|  | 5 | -11.195 | 1.504 | $-7.4+3$ | $4(1)$ | <().)(0) 1 |
| $t$ | 1 | -9.67t | 1.504 | -6.4.32 | +()8 | <0.()0) |
|  | 2 | -0.667 | 1.504 | -().4+3 | +()8 | $1.000)$ |
|  | 3 | 0.976 | $1.50 \downarrow$ | (0.64) | +()8 | $1.000)$ |
|  | 5 | -10.219 | $1.50+$ | -6.795 | +()8 | <().()0) 1 |
| 5 | 1 | $0.5+5$ | 1.5()$+$ | 0.362 | +()8 | $1.000)$ |
|  | 2 | 9.552 | $1.50 \downarrow$ | 6.351 | +()8 | <().0) ${ }^{\text {l }}$ |
|  | 3 | 11.195 | 1.504 | 7.44 3 | +08 | <().0) 1 |

Based on estimated marginal means
a. Adjustment for multiple comparisons: Bonferroni



| $600 \%$ | $80+$ | （）9どを－ | †（）＇I | ＋¢0 $0^{-}$ | ＋ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $905^{\circ} \mathrm{O}$ | $80+$ | 99ざて－ | †0¢I | $658 \mathrm{C}^{-}$ | $\varepsilon$ |  |
| $100^{\circ}(1)$ | $80+$ | ＋¢0）${ }^{-}$ | †） 1 | $\subseteq \angle 106^{-}$ | 乙 |  |
| $10)^{\circ} 1>$ | $80+$ | L8S゙く－ | ＋0）I | Ht＋IF－ | 1 | 5 |
| $600 \%$ | $80+$ | （19ぐく | †0 I I | ＋¢0＇s | ¢ |  |
| とLで† | $80+$ | $56 L^{\circ} 0$ | †0¢I | 5611 | $\varepsilon$ |  |
| $80^{\circ}$（） | $80+$ | ＋L9て－ | †0）I | 220）$\dagger$－ | 乙 |  |
| $100^{\circ} 18$ | $80+$ | Lで「「－ | ＋0） 1 | LSE゙9－ | 1 | † |
| SLI＇0 | $80+$ | 98 C゙て | ＋0）I | 68 ¢ ¢ | $\leq$ |  |
| clで† | $80+$ | $\left.{ }_{6} 6 L^{\circ}\right)^{-}$ | ＋0） 1 | ${ }_{5611^{\circ}}$ | † |  |
| $900{ }^{\circ}$ | $80+$ | $69+$－ | †（）${ }^{\text {I }}$ | しIで「 | て |  |
| $1000^{\circ} 1 \times$ | $80+$ | 120¢－ | †（）＇I | て¢9ぐ | 1 | \＆ |
| $100{ }^{(1)}$ | $80+$ | ＋E0） | ＋0¢＇I | SL0＇6 | ¢ |  |
| $820{ }^{\circ}$ | $80+$ | ＋ 29 て | ＋0，I | て20＇$\dagger$ | ＋ |  |
| $900 \%$ | $80+$ | $69+$ ¢ | †0）I | しIでS | $\varepsilon$ |  |
| ごで1 | $80+$ |  | †0¢1 | ¢¢どで | I | 乙 |
| $100^{\circ}(1)$ | $80+$ | L8S゙L | ＋0） 1 | IIナII | $\bigcirc$ |  |
| $100^{\circ}(1)$ | $80+$ | Lでて | †0 1 | LSc゙9 | ＋ |  |
| $1000^{\circ} 1>$ | $80+$ | IZ0＇s | †（） 1 | て¢ビL | $\varepsilon$ |  |
| \＆゙で1 | $80+$ | ¢S¢์ | †） | ¢¢E゙て | $\tau$ | 1 |
|  |  | วпן． 11 | นว pls |  | （5）IOY | （I）IOU |



| てLI（） | $80 \dagger$ | 26ざで | $\dagger 18.2$ | IEL ${ }^{-}$ | I | $\tau$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ＋50） | $80 \dagger$ | $66 L 2$ | $\dagger 18$ ¢ | $9 \angle 8{ }^{\circ}$ | S |  |  |
| て（0）（） | $80 \dagger$ | SEL＇s | ＋18．2 | I IS（ ） | $\dagger$ |  |  |
| 6100 | $80+$ | ¢てI＇s | ＋182 | $56 L 8$ | $\varepsilon$ |  |  |
| ZLI ${ }^{(0)}$ | $80+$ | 26c゙て | ＋18\％ | IEL＇9 | $\tau$ | I | （）L |
| $000{ }^{\circ} \mathrm{I}$ | 80 ＋ | 2080） | ＋18．2 | Lこでて | $\dagger$ |  |  |
| $000)^{\circ} \mathrm{I}$ | $80+$ | （）960） | ＋18． | 10くて | $\varepsilon$ |  |  |
| $000{ }^{\circ} \mathrm{I}$ | $80+$ | 06t＇0 | $\dagger 18.2$ | 6LE゙1 | $\tau$ |  |  |
| ＋て0） | $80 \dagger$ | $1900^{\circ}$ | $\dagger 18$ ¢ | ¢19 ${ }^{-}$ | 1 | $\bigcirc$ |  |
| $000{ }^{\circ} \mathrm{I}$ | 80）$\dagger$ | $2080{ }^{-}$ | $\dagger 18$ ¢ | LSでで | $\bigcirc$ |  |  |
| $000{ }^{\circ} \mathrm{I}$ | $80 \dagger$ | 8S10 | $\dagger 18$ ¢ | けナナ（） | $\varepsilon$ |  |  |
| $000{ }^{\circ} \mathrm{I}$ | $80+$ | でビ0） | $\dagger 18$ \％ | 8L8 ${ }^{-}$ | $\tau$ |  |  |
| $100)^{\circ}$ | 80 ＋ | C98 ${ }^{-}$ | †182 | （） $28{ }^{\circ} \mathrm{OH}$ | I | † |  |
| $000{ }^{\circ} \mathrm{I}$ | 80）$\dagger$ | （）96 $6^{\circ}$ | †182 | I（）$L^{\circ}$ て－ | 5 |  |  |
| $000{ }^{\circ} \mathrm{I}$ | $80 \dagger$ | 8SI（）－ | †182 | †tナ（）－ | $\dagger$ |  |  |
| $000{ }^{\circ}$ | $80 \dagger$ | （）L＋${ }^{\text {（ }}$－ | †182 | ててご「－ | $\tau$ |  |  |
| 10000 | $80+$ | 0て0 ${ }^{\text {＋}}$ | ＋182 | け¢゙II－ | I | $\varepsilon$ |  |
| $000{ }^{\circ} \mathrm{I}$ | 80）$\dagger$ | （）6t 0 | $\dagger 18.2$ | $6 \mathrm{CET}{ }^{-}$ | 5 |  |  |
| $000{ }^{\circ} \mathrm{I}$ | $80 \dagger$ | てIE゙） | ＋18．2 | 8L8（） | $\dagger$ |  |  |
| $000{ }^{\circ} \mathrm{I}$ | 80）+ | （）しや（） | †18． | ててご1 | $\varepsilon$ |  |  |
| ＋00） | $80+$ | 【くご | ＋18て | 266\％${ }^{-}$ | I | $\tau$ |  |
| †てい） | $80+$ | 190） | †18＇乙 | ¢198 | 5 |  |  |
| 1000 | $80 \dagger$ | ¢98\％ | ＋18て | $0 \mathrm{L8} 01$ | $\dagger$ |  |  |
| 1000 | $80+$ | 0Z（）$\dagger$ | ＋182 | †だ11 | $\varepsilon$ |  |  |
| ＋0）（） | 80）$\dagger$ | IS¢ | ＋18て | 2666 | $\tau$ | I | 59 |
| $000{ }^{\circ} \mathrm{I}$ | 80 $\dagger$ | てらし） | ＋18て | しで「 | t |  |  |
| $000{ }^{\circ} \mathrm{I}$ | 80）$\dagger$ | 6151 | $\dagger 18$ ¢ | †くで† | $\varepsilon$ |  |  |
| $000{ }^{\circ}$ | 80t | $\left.96 \chi^{\circ}\right)^{-}$ | †18て | てこ8（）－ | 乙 |  |  |
| I 000 （）＞ | 80）$\dagger$ | 90）${ }^{\text {＋}}$ | ＋18． | $66 \underbrace{\circ}$ で「 | 1 | $\bigcirc$ |  |
| $000{ }^{\circ} \mathrm{I}$ | $80 \dagger$ | てSI（）－ | †18て | Lで「 ${ }^{-}$ | 5 |  |  |
| $000{ }^{\circ} \mathrm{I}$ | 80）$\dagger$ | L9E゙I | †182 | L＋8． | ¢ |  |  |
| $000{ }^{\circ} \mathrm{I}$ | 80）$\dagger$ | 8tナ（）－ | †182 | 092 ${ }^{-}$ | て |  |  |
| I（0）${ }^{\circ}$（）＞ | $80+$ | 855 | †18て | $978{ }^{\text {¢ }}$－ | 1 | $\dagger$ |  |
| $000{ }^{\circ} \mathrm{I}$ | 80）$\dagger$ | $6 \mathrm{IS} \mathrm{I}^{-}$ | †182 | ＋Lで†－ | 5 |  |  |
| $000)^{1}$ | 80）$\dagger$ | L9E「 ${ }^{-}$ | $\dagger 18$ ¢ | L＋8 ${ }^{-}$ | $\dagger$ |  |  |
| cil $L^{\circ}$（） | 8（）+ | ¢181－ | $\dagger 18$ ¢ | 901 ${ }^{\text {c－}}$ | ح |  |  |
| ［（0）（）＞ | 80）+ | ¢26 ¢ | †18て | CL9 91－ | i | ¢ |  |
| $000{ }^{\circ} \mathrm{I}$ | 80t | 96で） | †18て | てこ8（） | $\bigcirc$ |  |  |
| $00(0) 1$ | $80 \dagger$ | 8tナ（） | ＋18．て | （）9で1 | $\dagger$ |  |  |
| col $L^{\circ}$（ | $80 \dagger$ | SI8 I | ＋18て | 90.15 | ¢ |  |  |
| I $000^{\circ} 0>$ | $80+$ | $01 \mathrm{I}^{+}$ | ＋182 | $99 \mathrm{Sl}^{\circ} \mathrm{I}$ | I | $\tau$ |  |
| I（0）${ }^{\circ}$（）$>$ | $80 \dagger$ | $90+\dagger$ | ＋18て | 66 C 21 | $\bigcirc$ |  |  |
| I0） 0 （）＞ | 80）$\dagger$ | 855 | ＋18\％ | 928 ZI | † |  |  |
| $100)^{\circ}(1)$ | 80t | ¢26） | ＋182 | CL9 91 | ¢ |  |  |
| I（）（）${ }^{\circ}$ | 80 ＋ | （）II† | †182 | 99¢ 11 | $\tau$ | I | （）9 |
|  |  | әпן． L |  |  | IO4（f） | IO4（I） | 37〇n |


|  |  | 3 | 2.064 | 2.814 | 0.733 | $4(1)$ | 1.0)(0) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $+$ | 3.780 | 2.814 | 1.34 3 | +()8 | $1.000)$ |
|  |  | 5 | 1.145 | 2.814 | (0.407 | 408 | $1.000)$ |
|  | 3 | 1 | -8.795 | $2.81+$ | -3.125 | 408 | 0.019 |
|  |  | 2 | -2.06t | $2.81+$ | -0.733 | 408 | $1.000)$ |
|  |  | $+$ | 1.716 | 2.814 | 0.610 | 408 | 1.0)() |
|  |  | 5 | -(0.919 | 2.814 | -0.327 | +08 | 1.0)() |
|  | 4 | 1 | -10.511 | 2.814 | -3.735 | 408 | (0.0)2 |
|  |  | 2 | -3.78() | 2.814 | -1.3+3 | $4(1)$ | 1.()()) |
|  |  | 3 | -1.716 | 2.814 | -(0.610 | 408 | 1.0)() |
|  |  | 5 | -2.6.35 | 2.814 | -0.936 | 408 | $1.000)$ |
|  | 5 | 1 | -7.876 | 2.814 | -2.799 | 408 | 0.05+ |
|  |  | 2 | -1.145 | 2.814 | -(0.4)7 | +08 | 1.000 |
|  |  | 3 | (0.919 | 2.814 | 0.. 327 | 408 | 1.000 |
|  |  | $+$ | 2.6 .35 | 2.814 | 0.936 | 408 | 1.000 |
| 75 | 1 | 2 | 5.192 | 2.814 | $1.8+5$ | 408 | 0.658 |
|  |  | 3 | 7.306 | 2.814 | 2.596 | 408 | 0.098 |
|  |  | 4 | 7.665 | 2.814 | 2.724 | 408 | 0.067 |
|  |  | 5 | 3.297 | 2.814 | 1.172 | +()8 | 1.000 |
|  | 2 | 1 | -5.192 | 2.814 | -1.8+5 | +()8 | 0.658 |
|  |  | 3 | 2.115 | 2.814 | 0.751 | 408 | 1.000 |
|  |  | $+$ | 2.47 t | 2.814 | 0.879 | +08 | 1.000 |
|  |  | 5 | -1.895 | 2.814 | -0.673 | +08 | 1.000 |
|  | 3 | 1 | -7.306 | 2.814 | -2.596 | +()8 | 0.098 |
|  |  | 2 | -2.115 | 2.814 | -0.751 | 408 | 1.000 |
|  |  | 4 | 0.359 | 2.814 | 0.128 | +()8 | 1.000 |
|  |  | 5 | -4.0)9 | 2.814 | -1.425 | 408 | 1.000 |
|  | 4 | 1 | -7.665 | 2.814 | -2.724 | +()8 | 0.067 |
|  |  | 2 | -2.47t | 2.814 | -(0.879 | +()8 | 1.000 |
|  |  | 3 | -().359 | 2.814 | -(). 128 | +()8 | 1.000 |
|  |  | 5 | -4.368 | 2.814 | -1.552 | $4(1)$ | 1.000 |
|  | 5 | 1 | -3.297 | 2.814 | -1.172 | $4(1)$ | 1.000 |
|  |  | 2 | 1.895 | 2.814 | 0.673 | 408 | 1.000 |
|  |  | 3 | 4.0(0) | 2.814 | 1.425 | $4(18$ | 1.000 |
|  |  | $+$ | +.368 | 2.814 | 1.552 | +()8 | 1.000 |
| 80 | 1 | 2 | $3.0+1$ | 2.814 | 1.081 | $4(18$ | $1.000)$ |
|  |  | 3 | 6.74 ) | 2.814 | 2.395 | $4(18$ | 0.171 |
|  |  | $+$ | 5.424 | 2.814 | 1.927 | +()8 | 0.546 |
|  |  | 5 | 2.229 | 2.814 | 0.792 | $4(18$ | 1.0)() |
|  | 2 | 1 | -3.041 | 2.814 | -1.081 | +()8 | 1.0)() |
|  |  | 3 | 3.699 | 2.814 | 1.314 | +()8 | 1.000 |
|  |  | $+$ | 2.383 | 2.814 | $0.8+7$ | +()8 | 1.000 |
|  |  | 5 | -0.812 | 2.814 | -().289 | $4(1)$ | $1.000)$ |
|  | 3 | 1 | -6.74() | 2.814 | -2.395 | +()8 | ().171 |
|  |  | 2 | -3.699 | 2.814 | -1.314 | +()8 | $1.000)$ |
|  |  | + | -1.316 | 2.814 | -().468 | $4(1)$ | $1.000)$ |
|  |  | 5 | -4.511 | 2.814 | -1.60.3 | +()8 | $1.000)$ |
|  | $+$ | 1 | -5.424 | 2.814 | -1.927 | $4(1)$ | (0.546 |
|  |  | 2 | -2.383 | 2.814 | -(). 847 | $4(1) 8$ | $1.000)$ |
|  |  | 3 | 1.316 | 2.814 | 0. 468 | +()8 | $1.000)$ |
|  |  | 5 | -3.195 | 2.814 | -1.135 | $4(1) 8$ | 1.000 |
|  | 5 | 1 | -2.229 | 2.814 | -().792 | 4() 8 | $1.000)$ |




| $000{ }^{\circ} \mathrm{I}$ | $80 \dagger$ | 2160 | ＋18て | S9Sて | $\dagger$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $000 \cdot \mathrm{I}$ | 80）+ | IIS I | ＋18て | \＆こで† | $\varepsilon$ |  |  |
| $000{ }^{\circ} \mathrm{I}$ | 80） | LLI（）${ }^{-}$ | ＋18て | L6け ${ }^{\text {（）－}}$ | て |  |  |
| $000)^{\circ}$ | 80t | $\left.6 \leq 0^{\circ}\right)^{-}$ | ＋18て | てLS ${ }^{-}$ | I | $\bigcirc$ |  |
| （0）（） 1 | 80t | 216（）${ }^{-}$ | ＋18て | 595で | $\bigcirc$ |  |  |
| $000{ }^{\circ} 1$ | 80t | （）09 ${ }^{\circ}$ | †18て | 8891 | ¢ |  |  |
| （0）（）＇ 1 | $80+$ | 880 ${ }^{-1}$ | †18て | ¢90 ${ }^{\text {c－}}$ | 乙 |  |  |
| $000)^{\circ}$ | 8（）+ | （） $\mathrm{LH}^{\text {I }}{ }^{-}$ | ＋18て | 8ご「－ | I | $\dagger$ |  |
| （）（）$)^{\circ} 1$ | 80）+ | IIST ${ }^{-}$ | ＋18て | ごでや | 5 |  |  |
| $000{ }^{\circ} \mathrm{I}$ | 80）+ | （0）9 ${ }^{\text {（0）}}$ | †18て | 889 ${ }^{-1}$ | † |  |  |
| 2260 | $80+$ | $889{ }^{-1}$ | ＋18て | ISL†－ | Z |  |  |
| 16 c゙o | $80+$ | （）LO ${ }^{\text {²－}}$ | ＋18て | 9285 | I | $\varepsilon$ |  |
| $000{ }^{\circ} \mathrm{I}$ | $80 \dagger$ | LLI ${ }^{\text {（ ）}}$ | ＋18て | L6t＇0 | $\bigcirc$ |  |  |
| 000 I | $80 \dagger$ | 880 ） | †182 | C90 ¢ | $\dagger$ |  |  |
| $226{ }^{\circ}$ | 80† | 889 I | ＋18て | ISL＇$\dagger$ | ¢ |  |  |
| $000{ }^{\circ}$ | 80）$\dagger$ | こ8ご（）－ | ＋182 | SLO）${ }^{-}$ | I | $\tau$ |  |
| （）0） 1 | $80 \dagger$ | 6Sc） | †182 | てLS゙1 | $\bigcirc$ |  |  |
| O）（）＇ 1 | $80 \dagger$ | 0 Ot I | ＋18て | $8 \mathrm{Cl} \dagger$ | $\dagger$ |  |  |
| $16 c^{\circ} 0$ | $80+$ | 0 0（0）て | †182 | 928： | $\varepsilon$ |  |  |
| （）0）${ }^{\circ}$ | 80）$\dagger$ | 28ご0 | †18．2 | SL0 1 | $\tau$ | I | 06 |
| $000{ }^{\circ}$ | 80）+ | ＋E60） | ＋18\％ | （）¢9て | † |  |  |
| $65 L^{\circ}(0)$ | 80）$\dagger$ | 6LL＇I | †18て | 800 S | E |  |  |
| $000{ }^{\circ}$ | $80 \dagger$ | 0て（） 0 | †182 | 950） | $\tau$ |  |  |
| （）（）） 1 | $80 \dagger$ | 9てL＇（）－ | †18．2 | ††（）で | I | 5 |  |
| （）（））I | 80）$\dagger$ | ＋ $6^{\circ} 0^{-}$ | †18て | （）¢9「で | 5 |  |  |
| （）（）${ }^{\circ}$ | $80+$ | $5+8{ }^{\circ}$ | †182 | 8Lごて | $\varepsilon$ |  |  |
| 000 I | 80）$\dagger$ | $\left.\subseteq 16{ }^{\circ}\right)^{-}$ | $\dagger 18$ て | ＋LSで | $\tau$ |  |  |
| 5160 | 80）+ | 199 ${ }^{-}$ | †18て | ＋L9 + － | I | $\dagger$ |  |
| 6 6L＇0 | 80）$\dagger$ | 6LL＇${ }^{-}$ | †18て | 800）${ }^{-}$ | 5 |  |  |
| 0 （）0 ${ }^{\circ}$ | $80+$ | S＋8 ${ }^{\circ}$（－ | †18て | 8Lごで | † |  |  |
| $26 L^{\circ} 0$ | 80）$\dagger$ | 09L＇I－ | †18．て | て¢6け | $\tau$ |  |  |
|  | 80）+ | 90さで | †18．て | てS0し－ | I | $\varepsilon$ |  |
| （）0）${ }^{\circ}$ | 80）+ | （）Z（） $0^{-}$ | $\dagger 18$ 亿 | 950（）－ | $\bigcirc$ |  |  |
| $000 \cdot 1$ | $80 \dagger$ | S160 | $\dagger 18$ 亿 | ＋LŞて | $\dagger$ |  |  |
| $26 L^{\circ} 0$ |  | （）9LT | $\dagger 18{ }^{\circ}$ | て56† | ¢ |  |  |
| 000 I | 80）+ | $9+L^{\circ}()-$ | †18．て | （））${ }^{\text {「 } 2-~}$ | I | $\tau$ |  |
| （0）（）＇ 1 | 80 ＋ | 9てL＇0 | †18て | ＋to $冖$ | 5 |  |  |
| Sl60 | $80 \dagger$ | I99＇I | †18．2 | ＋ 29 † | $\dagger$ |  |  |
| 9210 | 80）$\dagger$ |  | †18．て | 2S0 $0^{\circ} \mathrm{L}$ | ¢ |  |  |
| 000 I | $80 \dagger$ | 9＋L＇0 | †18て | 0017 | $\tau$ | I | 58 |
| （）0）${ }^{\text {I }}$ | $80 \dagger$ | ScII | †18て | $561 \%$ | $\dagger$ |  |  |
| （）0）${ }^{\text {I }}$ | 80）$\dagger$ | ¢09＇I | ＋18．て | IIS $\dagger$ | $\varepsilon$ |  |  |
| （）0）$)^{\text {I }}$ | 8()$+$ | $687^{\circ}()$ | †18．て | 2I80 | $\tau$ |  |  |

### 2.3 Main effect of group

Pairwise comparison to compare groups when ROl is in palmar position.

| position | Exercised (1) | Non-exercised (J) | Mean difference <br> $(\mathrm{I}-\mathrm{J})$ | Std Error | Significance |
| :--- | :--- | :--- | :--- | :--- | :--- |
| palmar | 1.38 .38 | $12(0.10$ | 18.28 | 0.476 | $<(0.0)(0)$ |

b. An estimate of the modified population marginal mean
2.3.1 Group at one level of angle

Painwise comparisons of one group mean against another while holding angle constant.

Dependent Variable: MEAN

| ANGLE | Mean Difference (I-J) | Std. Eıror | T VALUE | Degrees of freedom | significance |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $6)$ | 22.899 | 2.318 | 9.880 | +()8 | <() ()) 1 |
| 65 | 17.148 | 2.318 | 7.399 | +()8 | <().0) 1 |
| 70 | 18.172 | 2.318 | $7.8+1$ | 408 | <().)() 1 |
| 75 | 16.905 | 2.318 | 7.294 | +()8 | <().0) ${ }^{\text {l }}$ |
| 80 | 18.437 | 2.318 | 7.955 | +()8 | <().)() 1 |
| 85 | 17.562 | 2.318 | 7.578 | +()8 | <().)() 1 |
| 90 | $16.8+2$ | 2.318 | 7.267 | +()8 | <() ()) 1 |

1 = exercised
$\mathrm{J}=$ non-exercised

### 2.3.2 Group at one level of ROI

Pairvise comparisons to compare group means. holding ROI constant when ROI's are in a palmar position.

Dependent Variable: MEAN

| ROI | Mean Difference (I-J) | Std. Error | t ralue | Degrees of freedom | significance |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | -18.055 | 1.959 | -9.218 | 62 | <().0) ${ }^{\text {l }}$ |
| 2 | -24.726 | 1.959 | -12.623 | 62 | <().()) 1 |
| 3 | -21.153 | 1.959 | -10.799 | 62 | <().()) 1 |
| 4 | -21.372 | 1.959 | -10.911 | 62 | <().0) 1 |
| 5 | -6.099 | 1.959 | -3.114 | 62 | (0.0) 3 |

[^2]
## 3. ROI size analvsis

Tabulated data prior to statistical analysis

| Average of <br> mean | angle |  |
| ---: | ---: | ---: |
| radius | 60 | 90 |
| 2.5 mm | 134.663 | 129.261 |
| 3 mm | 136.480 | 127.813 |
| 3.5 mm | $137.8+7$ | $127.19+$ |

### 3.1 Main effect of radius size

There is no significant effect of diameter as determined by a p value of 0.819 from the analysis of variance performed by SPSS

### 3.1.1 Angle at one level of radius

Painvise comparisons to compare angle means while holding size of ROI constant.
Dependent variable: MEAN

| Radius(mm) | Mean difference <br> $\left(60^{\circ}-9()^{\circ}\right)$ | Std error | T value | Significance $^{\text {a }}$ |
| :--- | :--- | :--- | :--- | :--- |
| 2.5 | 5.4() 1 | 1.275 | 4.236 | $0(0.0)(0)$ |
| 3 | 8.667 | 1.275 | 6.7975 | $0.0(0)$ |
| 3.5 | 10.653 | 1.275 | 8.3555 | $(0.0)(0)$ |

### 3.1.2Radii size at one level of angle.

Pairvise comparison to compare ROl size holding angle constant.
Dependent variable: MEAN

| angle | diameters | Mean difference | Std error | T value | Significance ${ }^{\text {a }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 60 | 2.5vs3 | 1.817 | 1.275 | 1.425 | 0.931 |
|  | 3vs3.5 | 1.368 | 1.275 | 1.073 | $1.000)$ |
|  | $2.5 \mathrm{vs.3.5}$ | 3.184 | 1.275 | 2.497 | (0.078 |
| 90 | 2.5.s. 3 | 1.449 | 1.275 | 1.136 | $1.000)$ |
|  | 3 ys 3.5 | 0.619 | 1.275 | 0. 185 | $1.000)$ |
|  | $2.5 \mathrm{rs3} 3$ | 2.068 | 1.275 | 1.622 | 0.635 |

Based on estimated marginal means
a. Adjustment for multiple comparisons: Bonferroni


[^0]:    Based on estimated marginal means2
    Adjustment for multiple comparisons: Bonferroni

[^1]:    l = exercised
    $\mathrm{J}=$ nonexercised

[^2]:    $\mathrm{I}=$ e.ercised
    J = none.vercised

